

#### **Team Introductions**



Bradford Andrews Mechatronics Engineer

Presenter



Albert Auer Mechanical Design Engineer

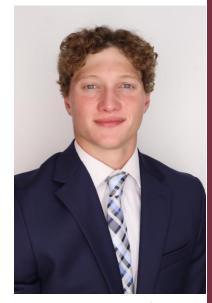


Chaney Bushman
Manufacturing and
Test Engineer

Presenter



Joseph Garvie Systems Engineer



Mason Herbet CAD Designer



#### **Sponsor and Advisors**





Sponsor
Cole Gray
Senior Mechanical Design
Engineer





FAMU-FSU College of Engineering



Academic Advisor
Patrick Hollis, Ph.D.
Associate Professor &
Undergraduate Coordinator



Academic Advisor
Shayne McConomy, Ph.D.
Senior Design Professor



#### **Objective**



The objective of this project is to design and produce a stepper motor lifecycle test fixture for Danfoss Turbocor to improve user-friendliness and reliability over their current testing procedure.



#### **Project Brief**

#### **Problem:**



The current stepper motor lifecycle test is conducted in the inlet guide vane assembly of the compressor



This adds undesirable friction forces, leading to inaccurate results for the motor's lifecycle



Failure between individual stepper motors have high variance



#### **Compressor Interior**

Worm Gear



**Stepper Motor** 

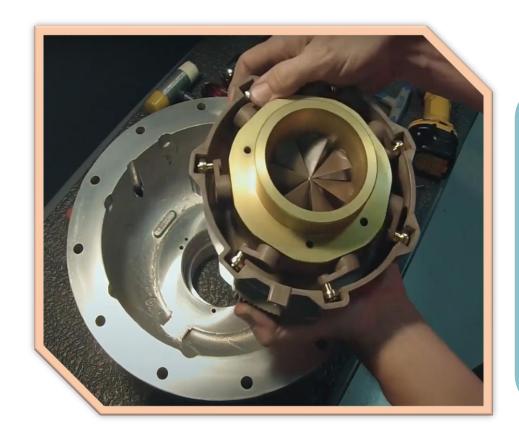
Stepper Motor Mounting Plate

Compressor Housing

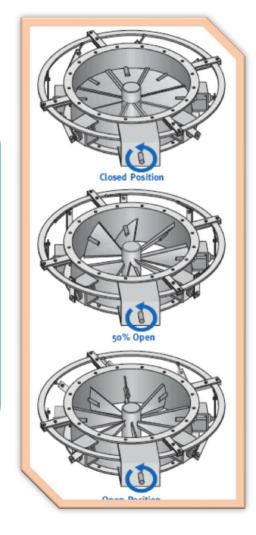
Inlet Guide Vane (IGV)



#### **Inlet Guide Vane**

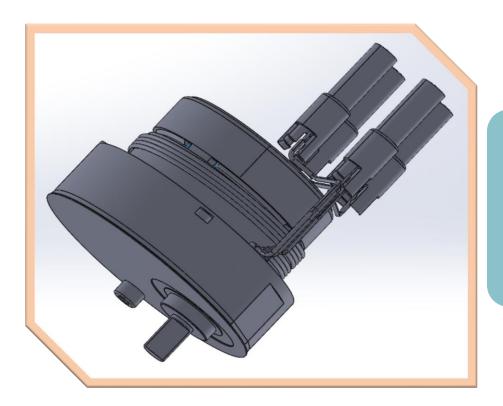


Controls the fluid flow at the intake of the compressor

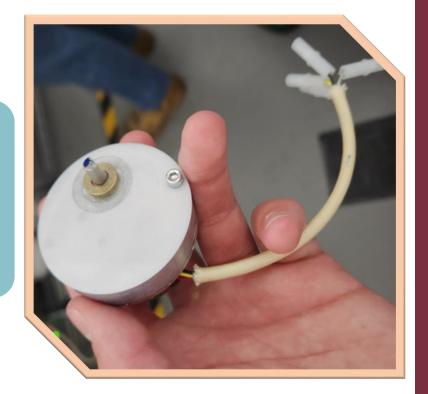




#### 910098 Stepper Motor

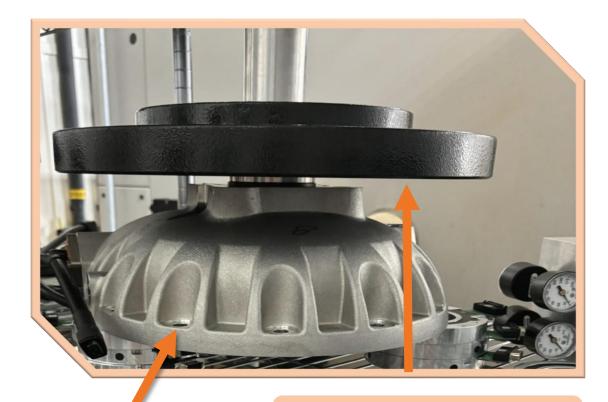


Control the angle at which IGV blades are positioned



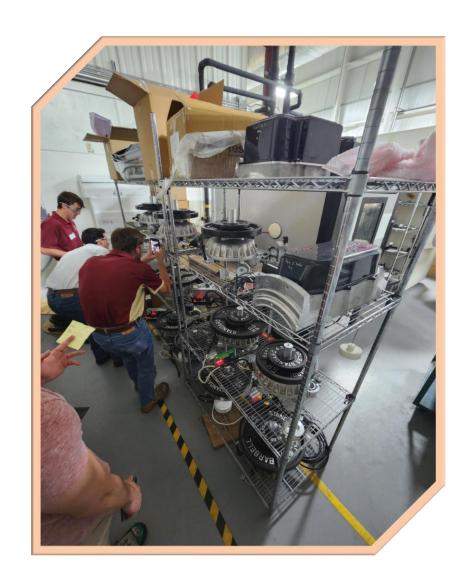


#### **Current Test Procedure**



**IGV** Housing

Various Weight Plates





# **Primary Market**





## **Secondary Market**

**Compressor Manufacturing Companies** 





**Stepper Motor Manufacturing Companies** 





Because Motion Matters™

**3D Printer Companies** 





Laboratories (Academic)

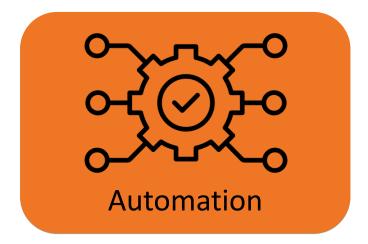






# **Key Goals**











#### Stakeholders





### **Assumptions**

The stepper motor lifecycle fixture will be in the back room of the Danfoss factory with standard room temperature and conditions.

The fixture will sit on an elevated flat working space.

A standard 120V outlet will be available.

Only the IGV stepper motor will be tested.



#### **Customer Needs**

Motor oriented vertically pointing downwards

Fabricated from non-corrosive, non-magnetic materials

Independently run six motors at a time

Allow for manual adjustment of Perma-Tork



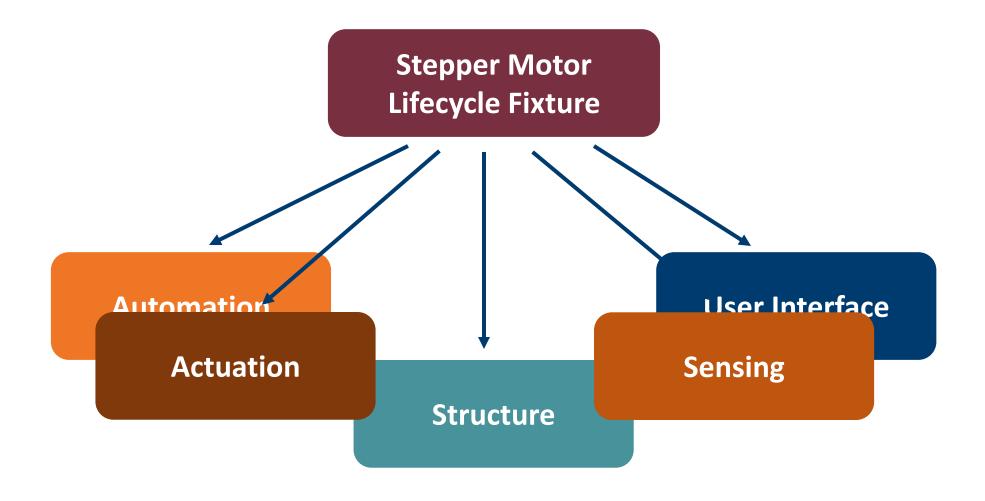
#### **Customer Needs**

#### **Testing Needs**

#### Inputs Procedure Speed in pulses per Outputs second (PPS) One direction until Resistance torque failure Total cycles Direction (CW or Alternating direction Total runtime between cycles until CCW) failure • A cycle is a certain period based on pulses/time)



#### **Functional Decomposition**





#### **Actuation Sub-System**



**Danfoss Motor Driver** 

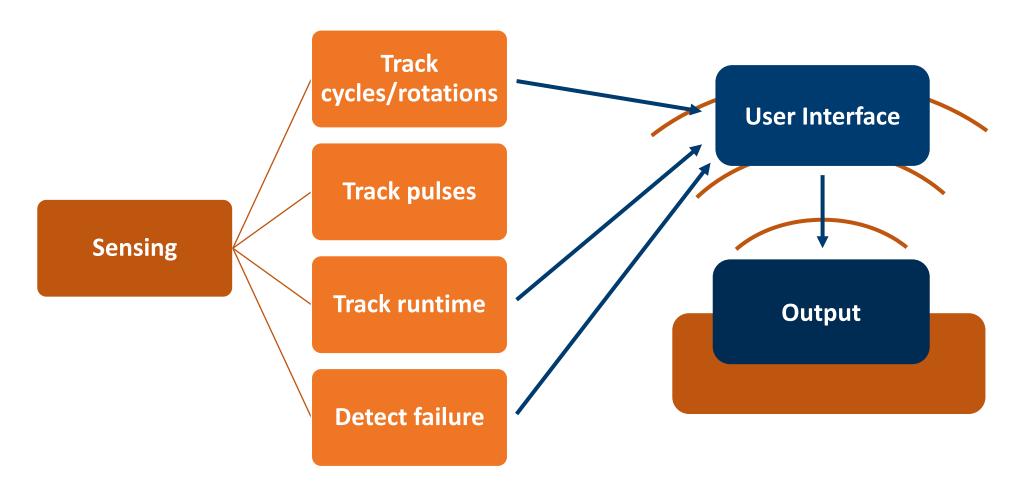
Actuation

Activate upon test initiation

Deactivate upon failure

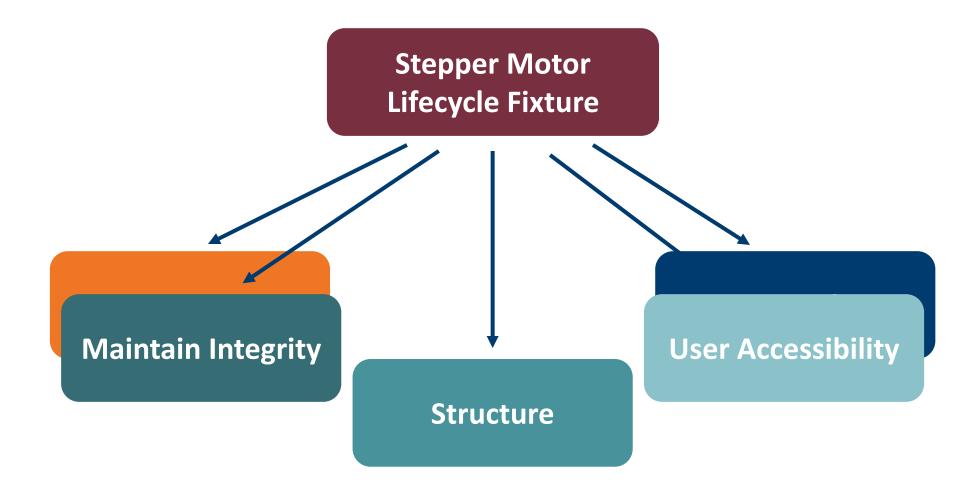


## **Sensing Sub-System**



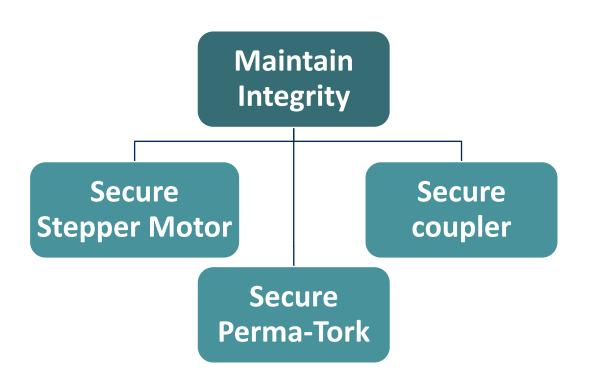


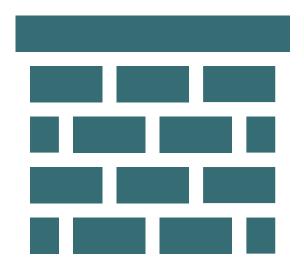
#### **Functional Decomposition**





## **Maintain Integrity Sub-System**







# **User Accessibility Sub-System**



User Accessibility Allow for six motors

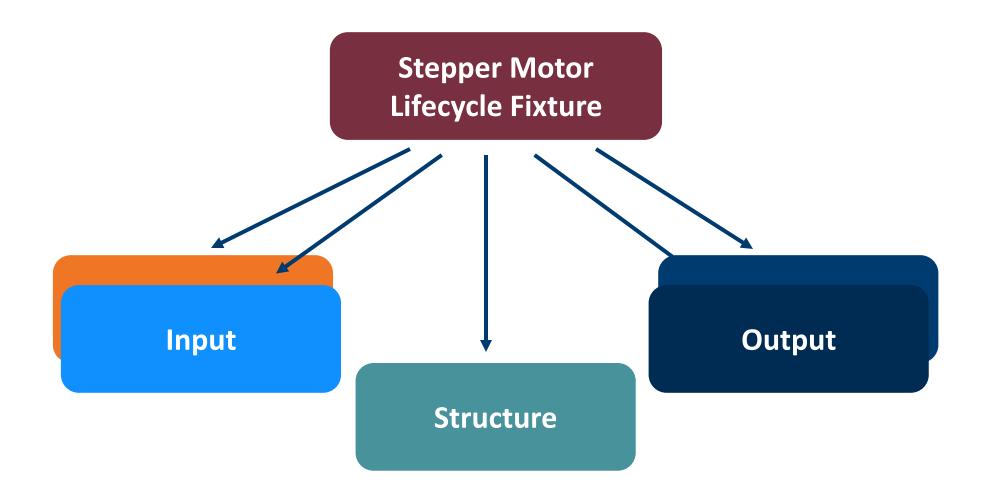
Allow for manual setting of Perma-Tork

Allow for complex accessibility

Allow for motor replacement clearance

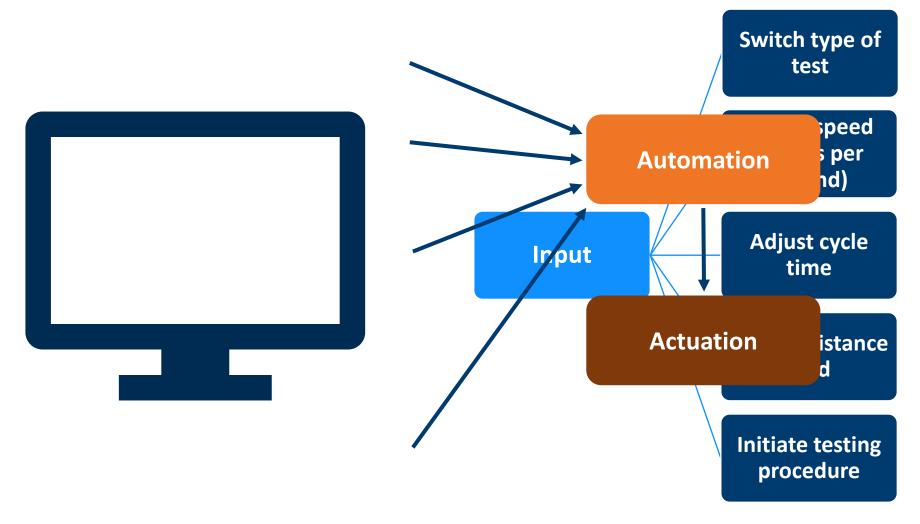


# **Functional Decomposition**



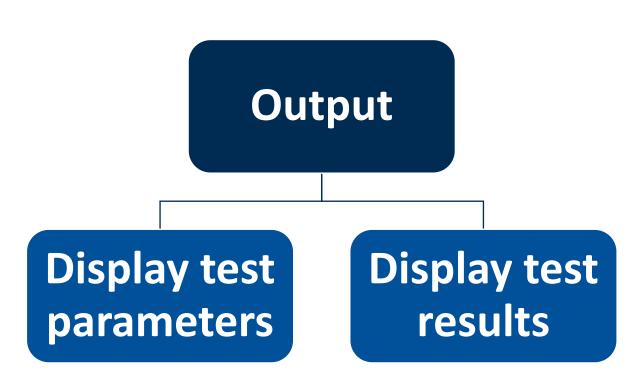


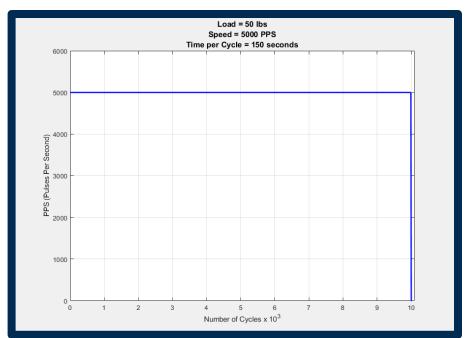
# **Input Sub-System**





#### **Output Sub-System**





Possible Test Output



#### **Future Work**

Research
Physical
Components

Develop State
Diagram

CAD Model
Prototyping

Designs



Bradford Andrews

