

### **Team Members**



Ahmari Avin Computational Engineer



Brightson Bazile Systems Engineer



Michael Rodriguez
Capera
Manufacturing
Engineer



Daniel Mack Design Engineer



Craig Yox Materials Engineer



### **Sponsors and Advisors**

# CORNING



Jeffery Roche Heavy Duty Project Manager



Trent Brush Project Leader





Shayne McConomy, Ph.D. Professor/Sponsor

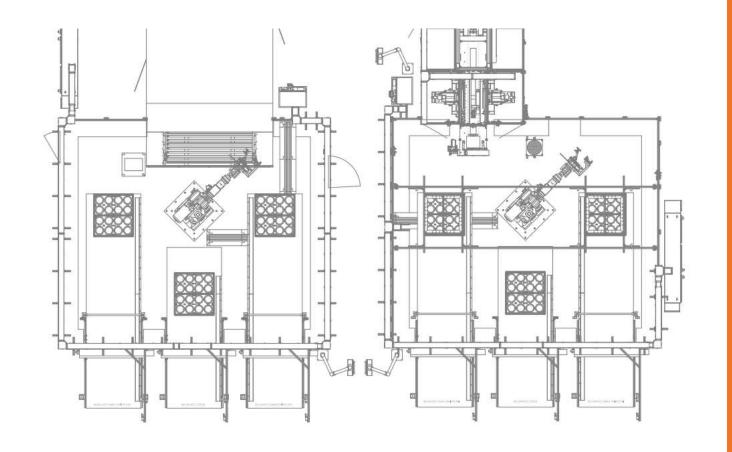


Christian Hubicki, Ph.D. Project Advisor



# **Objective**

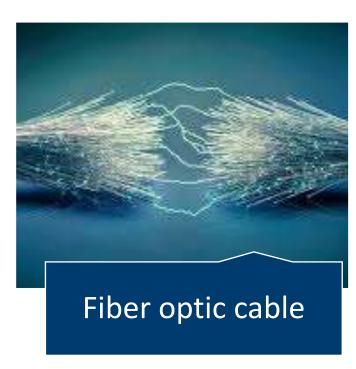
The objective of this project is to design an automated device to assist in Corning's current palletization and depalletization process through the placement and removal of pallet toppers and embedded foam layer.





# Background

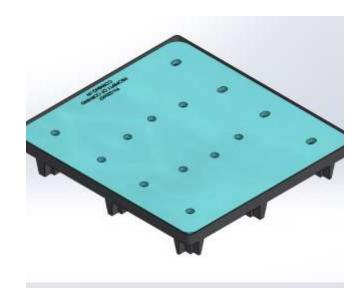








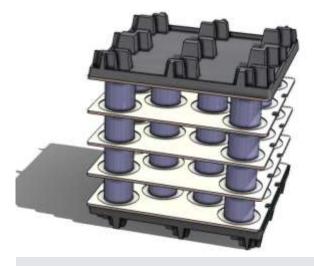
# **Project Summary**



Pallet Topper with foam



Ceramic Cylinder Stacked on pallet.



Complete Assembly with Topper



# **Key Goals**









**Sizing Constraints** 

**Safety Measures** 

Automation

Placement/Removal



### **Markets**

# Primary

- Corning and Team Sponsor.
- Diesel particulate filter manufactures

## Secondary

- John Deere (Agricultural)
- Kroger (Super Market)
- SSI Schaefer
- Ford (Auto)



## **Assumptions**



The device will have easy access to a power supply.



The pallet stacking surface will stable and uniform.



Controlled Environment within the warehouse.



The pallet stacks are removed from conveyor system quickly.



Each pallet topper and foam piece are uniform in size.

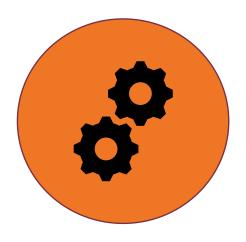


# Stakeholders

Stakeholder	Investors	Decision Makers	Advisors	Receivers
Dr. McConomy			<b>/</b>	<b>✓</b>
T.A.'s			<b>/</b>	
Dr. Hubicki			<b>/</b>	<b>/</b>
Corning		<b>/</b>	<b>/</b>	<b>/</b>
Team 504		<b>/</b>		
OSHA		·		
Secondary Market				



### **Customer Needs**



**Efficiency Synthesis** 



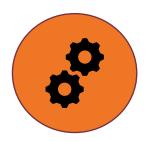
Spatial Constraints



Physical Constraints



## Efficiency/Synthesis



#### **Needs:**

- Improve current palletization/depalletization process
- Communicate with Corning's current system
- Read differing heights of pallets



## **Spatial Constraints**



#### **Needs:**

- Fit within the current or adjusted cell
- Stagnation area
- Operates without interfering with current robots



# **Physical Constraints**



#### **Needs:**

- Matches speed of employee efforts
- Ability to lift the weight of the pallet topper
- Move pallet toppers and foam layers without damage



## **Functional Decomposition**

Currently in Progress of being completed



### **Future Work**

Targets and Metrics

Concept Generation and Selection

Risk Assessment

Bill of Materials

Prototype and Modeling

