



FAMU-FSU  
College of  
Engineering

# Team 502: Boeing Underwater Glider

Jake Burns, Tristan Hardy, Nicolas Lorin  
Justin Sepulveda, Martin White

2/18/2025

# Team Introductions



Jake Burns  
*Simulations Engineer*



Tristan Hardy  
*Modeling Engineer*  
***Presenting***



Nicolas Lorin  
*Controls Engineer*



Justin Sepulveda  
*Systems Engineer*  
***Presenting***



Martin White  
*Materials Engineer*  
***Presenting***



# Sponsor and Advisor



Project Sponsor  
Shawn Butler



Project Sponsor  
JaQuan Young



Academic Advisor  
Shayne McConomy



Faculty Advisor  
Kourosh Shoele







# Objective

The objective of this project is to simulate and construct an underwater glider.



# Key Goals

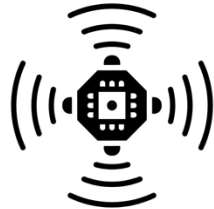
-  Energy efficiency
-  Data collection
-  Motion
-  Durability

# Customer Needs



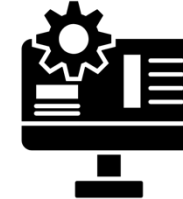
## Motion

- Operates at depths up to 10 feet.



## Sensing Capabilities

- Collects data about environment
- Processes data to make adjustments



## Simulation

- Optimal path simulations
- Performance while operating



# Functional Decomposition



# Motion

Control Lift

40-70 [lift-drag ratio]

Control Pitch

Angle of Attack  $\leq 10^\circ$

Control Yaw

Sideslip Angle  $\leq 10^\circ$

Control Roll

Bank Angle  $\leq 10^\circ$





# Operation

Store Power

150 [J/m]

Store Data

1 [GB]





# Hull

Endure Fatigue Stress

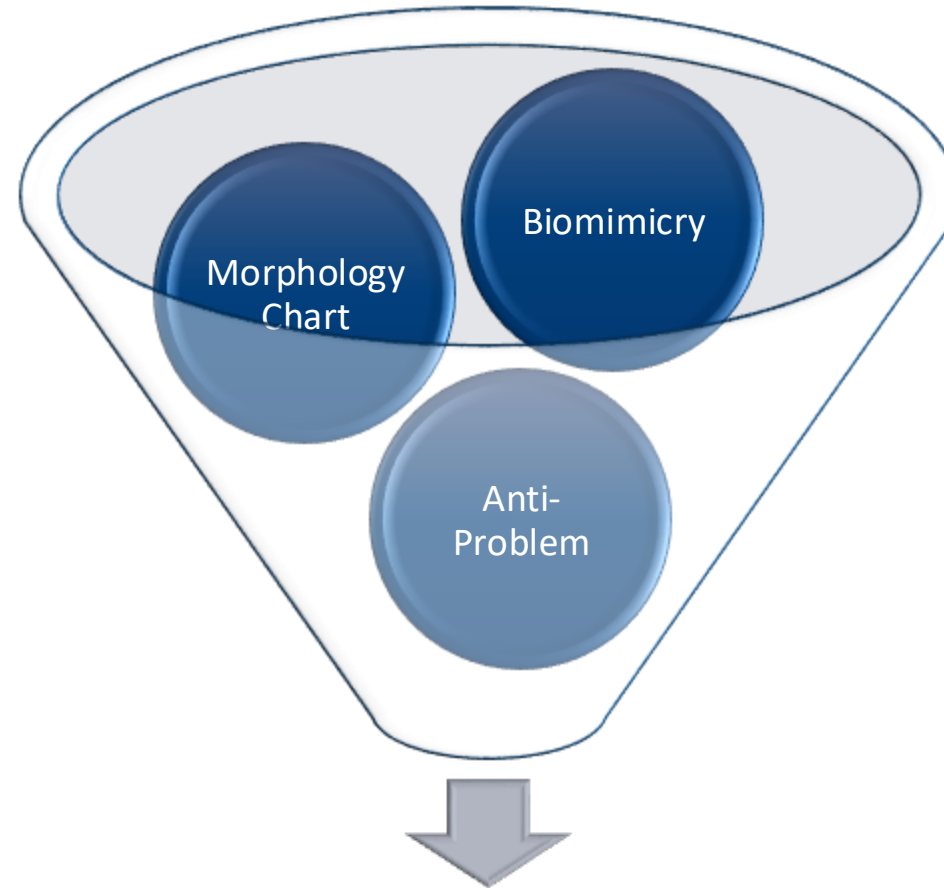
10 [cycles]

Withstand Pressure

45 [kPa]



# Ideation Methodology



**Concept Generation**

# Potential Concepts

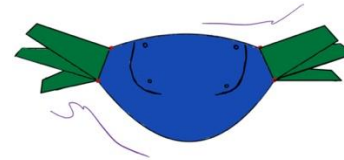
## Datum



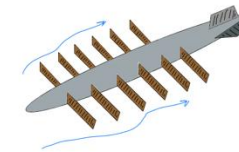
Boeing Wave Glider



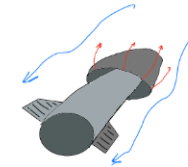
Propeller  
Glider



Adjustable Wing  
Glider



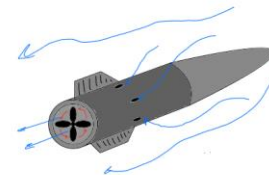
Energy Harvesting  
Glider



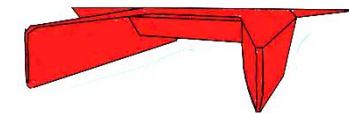
Jellyfish  
Glider



Piston Glider



DC Motor Glider



Dual Hull Glider

# Potential Concepts

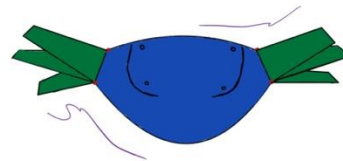
## Datum



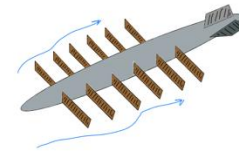
Boeing Wave Glider



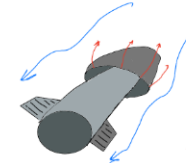
Propeller Glider



Adjustable Wing Glider



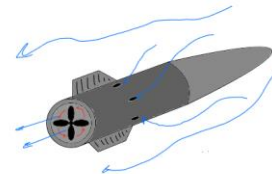
Energy Harvesting Glider



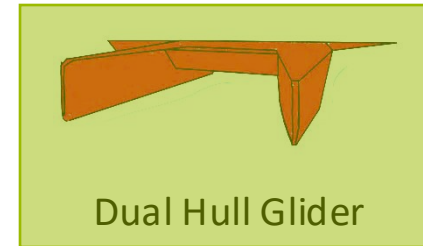
Jellyfish Glider



Piston Glider

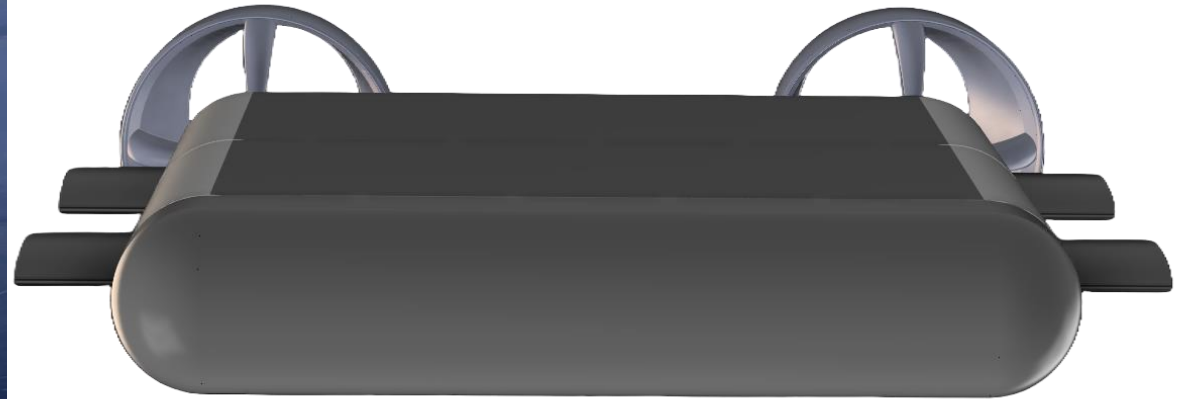


DC Motor Glider



Dual Hull Glider

# Final Concept Selection



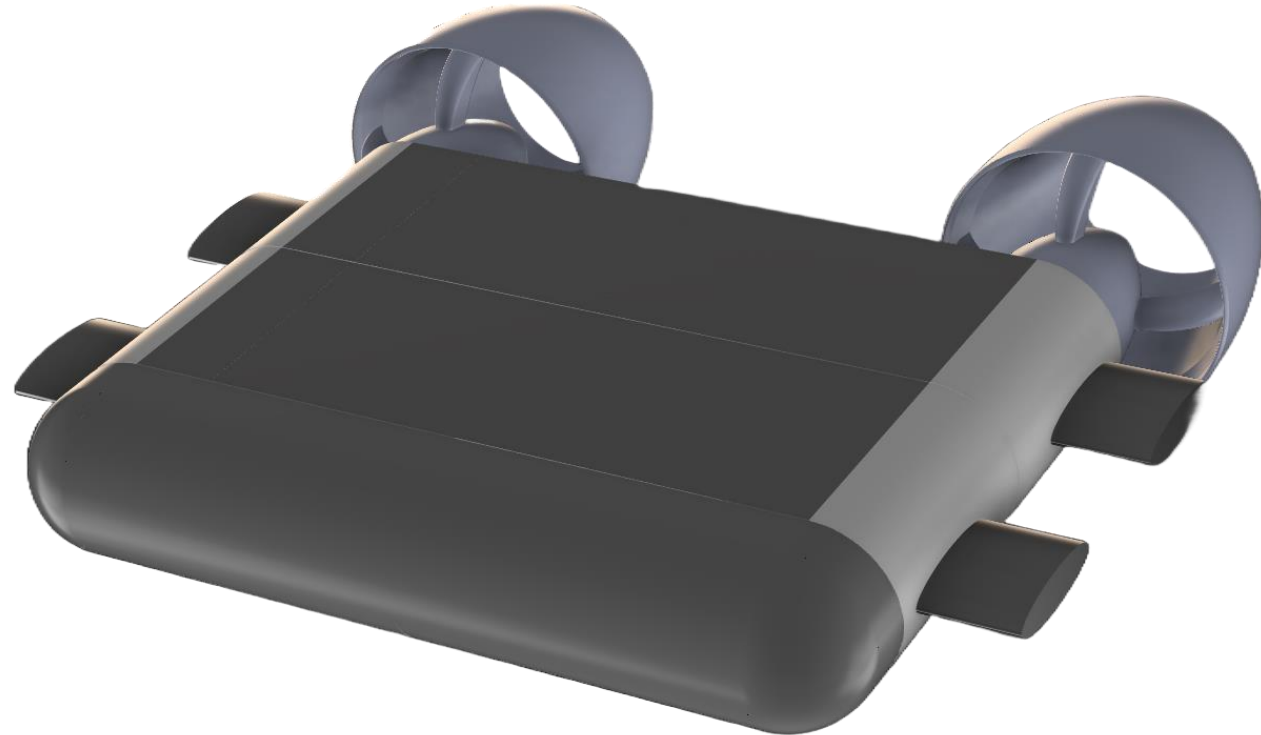
# Main Features

## Digital Model

- Dive planes
- Entirely buoyancy driven

## Physical Model

- Propellors
- Dive planes
- **Not** buoyancy driven
- Emulates motion of digital model



# Flow Separation Studies

## What is flow separation

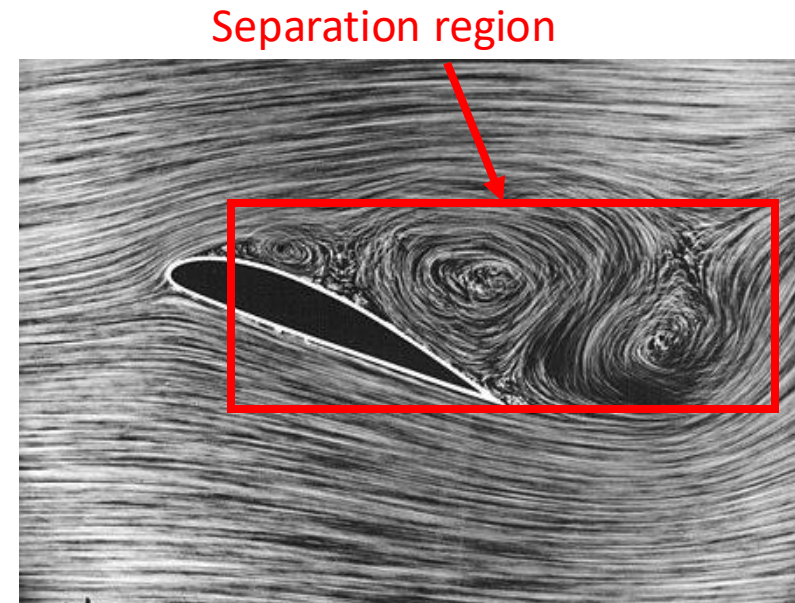
- Occurs when the fluid detaches from the body
- Results in a “separation region”

## Why is flow separation bad

- Increased drag
- Vortices which can create vibrations on the body causing unwanted fatigue
- Cavitation bubbles in water
- All decreases efficiency

## How can flow separation be used

- SolidWorks Flow Simulation toolbox was used to find surface pressure
- Force values can be resolved, which give can be used for the control law



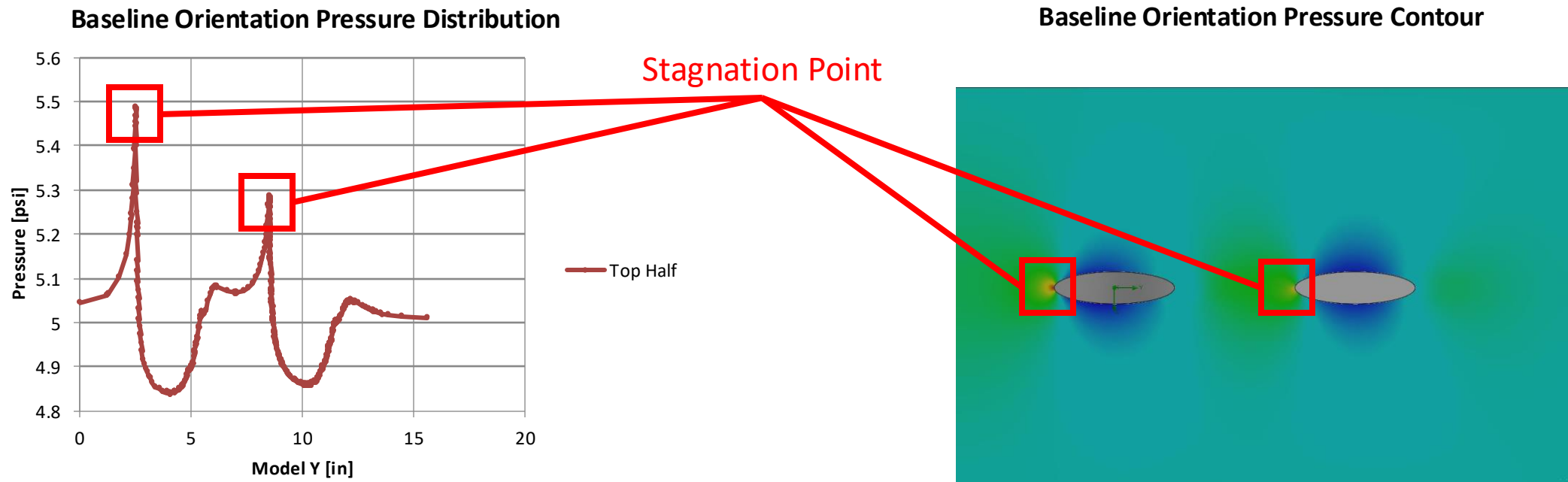
Flow on an asymmetric airfoil





# First Double Airfoil Case

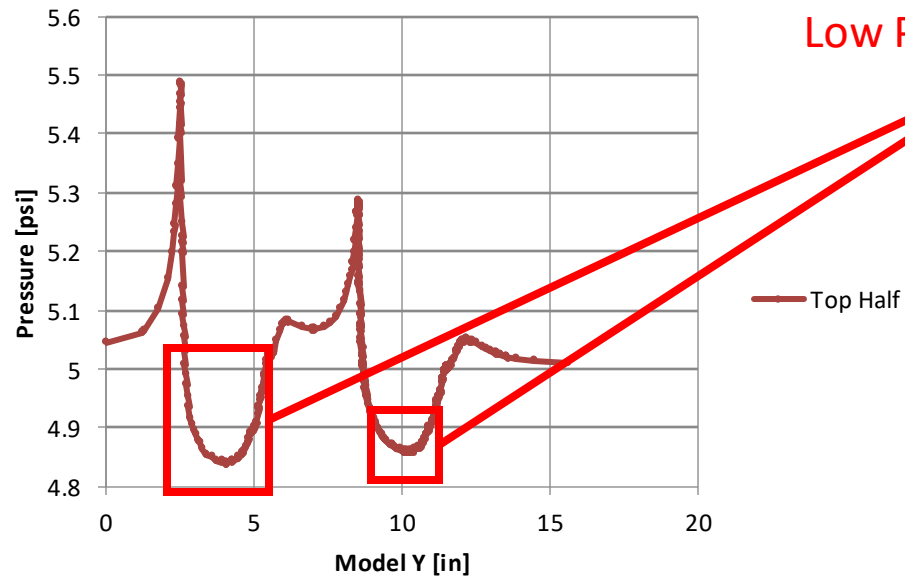
- $V = 80$  in/s
- $P = 5$  psi



# First Double Airfoil Case

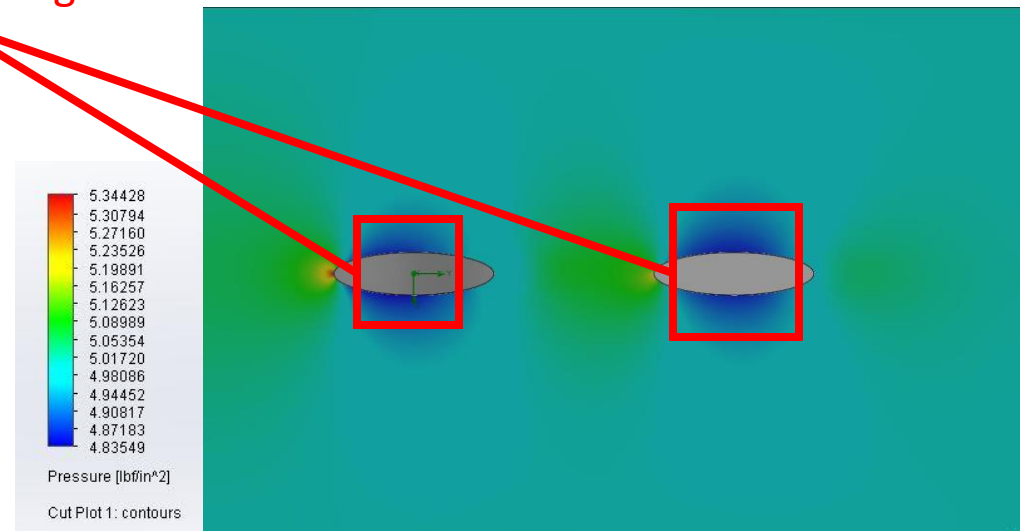
- $V = 80$  in/s
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Baseline Orientation Pressure Distribution



Low Pressure Regions

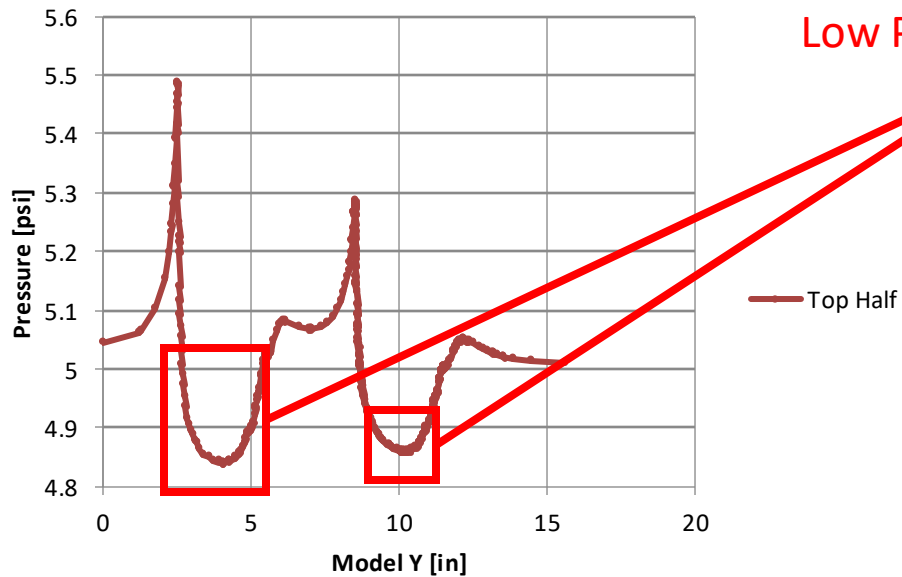
Baseline Orientation Pressure Contour



# Double Airfoil At Angle of Attack

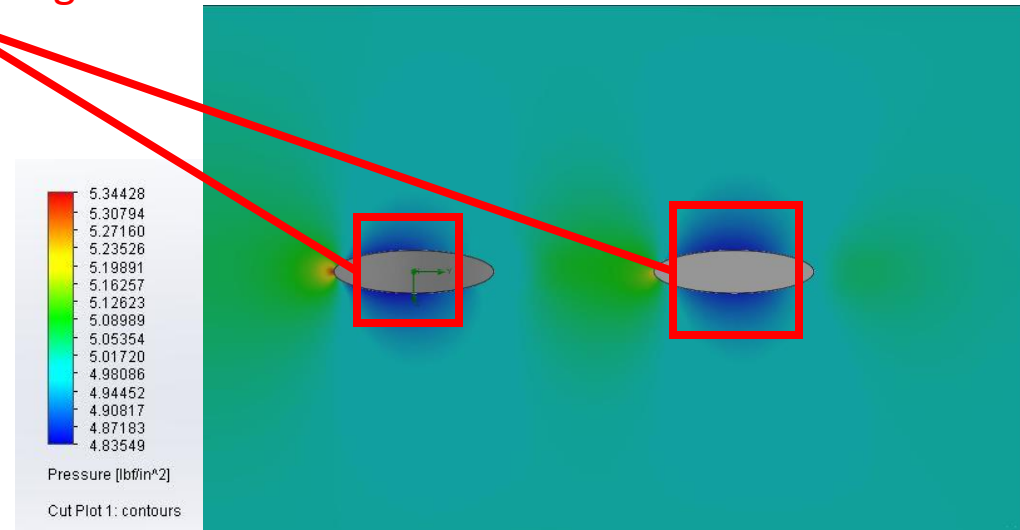
- $V = 80$  in/s
- $P = 5$  psi
- Back airfoil pitched -10 degrees

Baseline Orientation Pressure Distribution



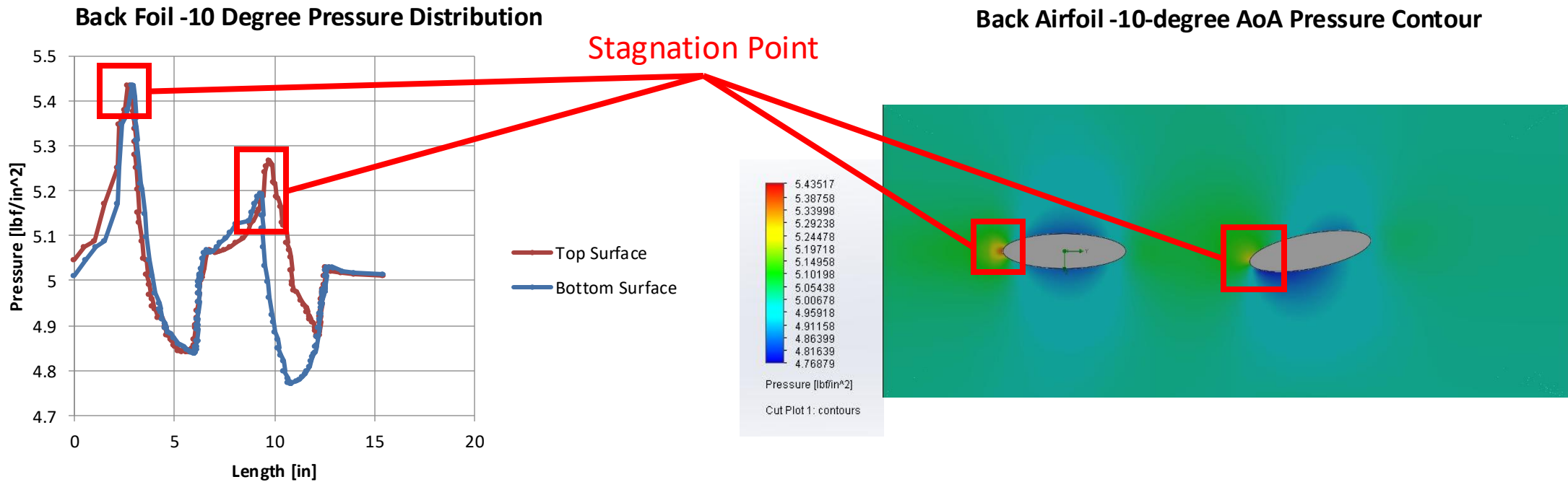
Low Pressure Regions

Baseline Orientation Pressure Contour



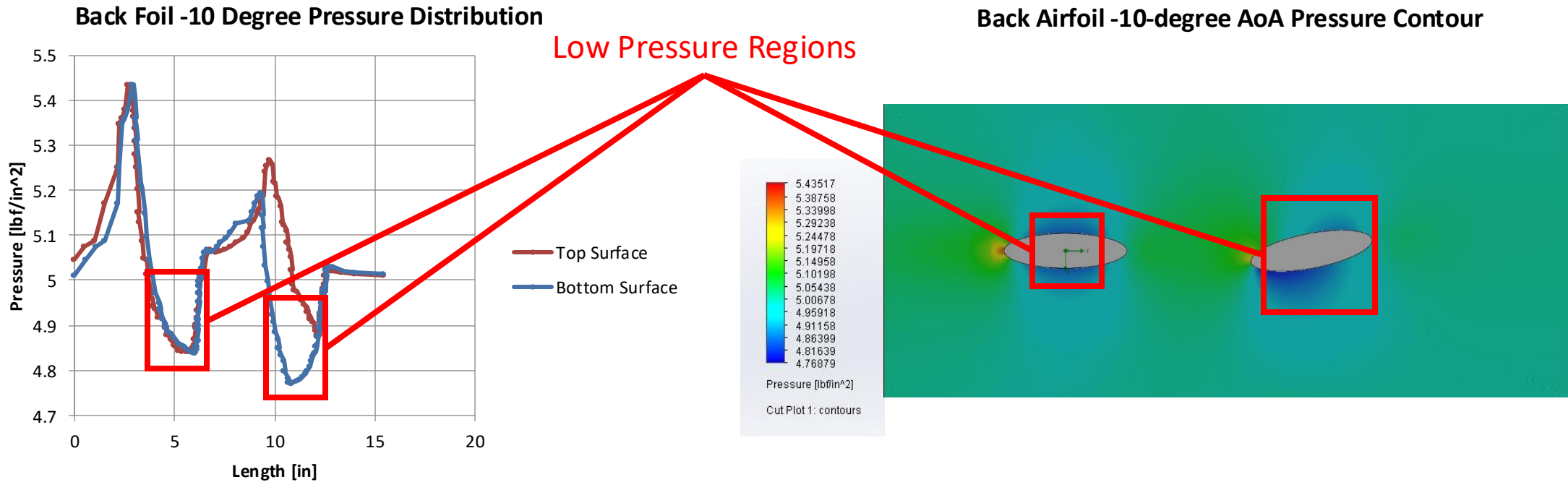
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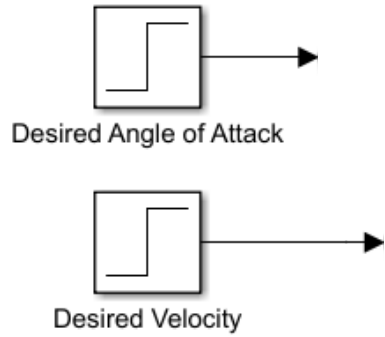


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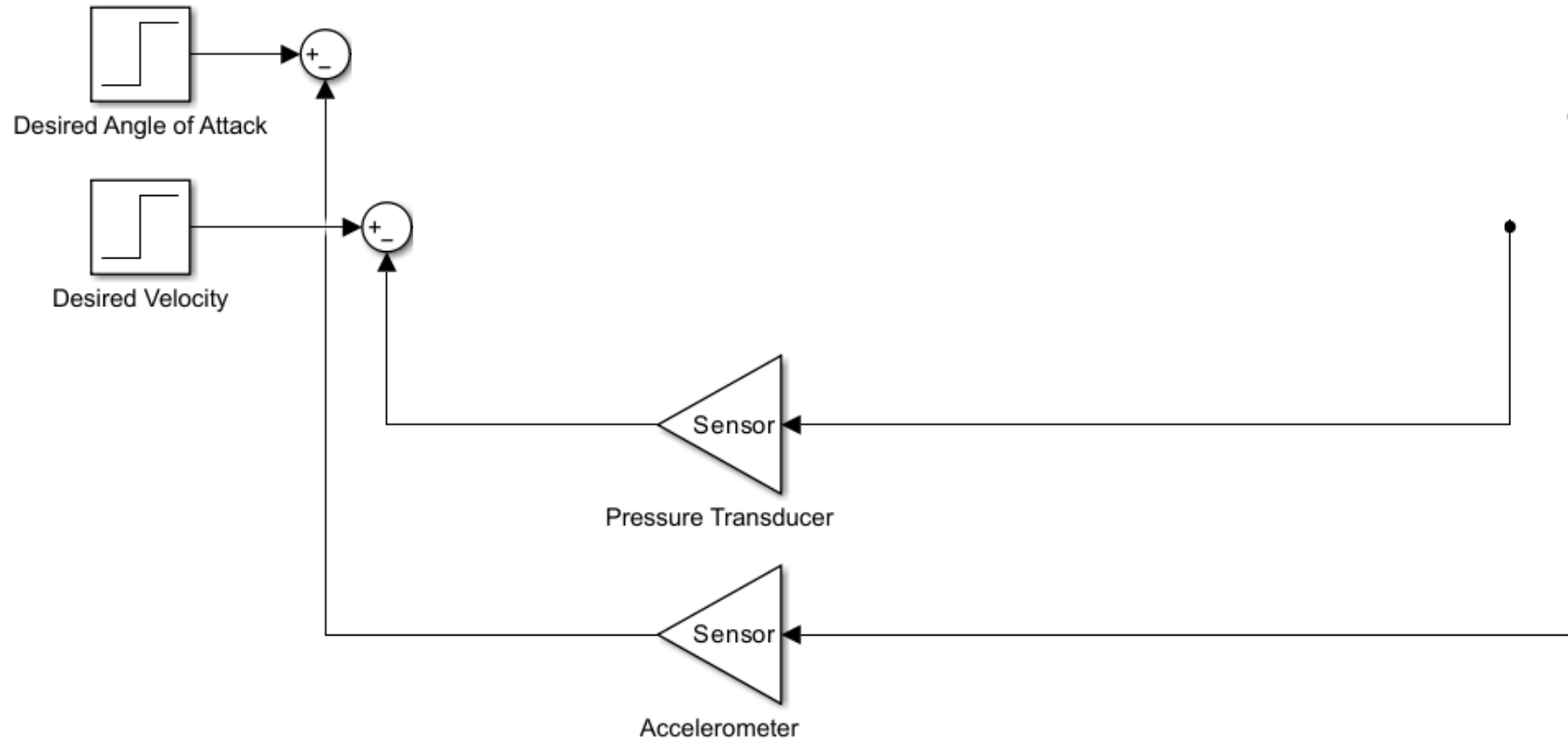
- $V = 80$  in/s
- $P = 5$  psi
- Back airfoil pitched -10 degrees



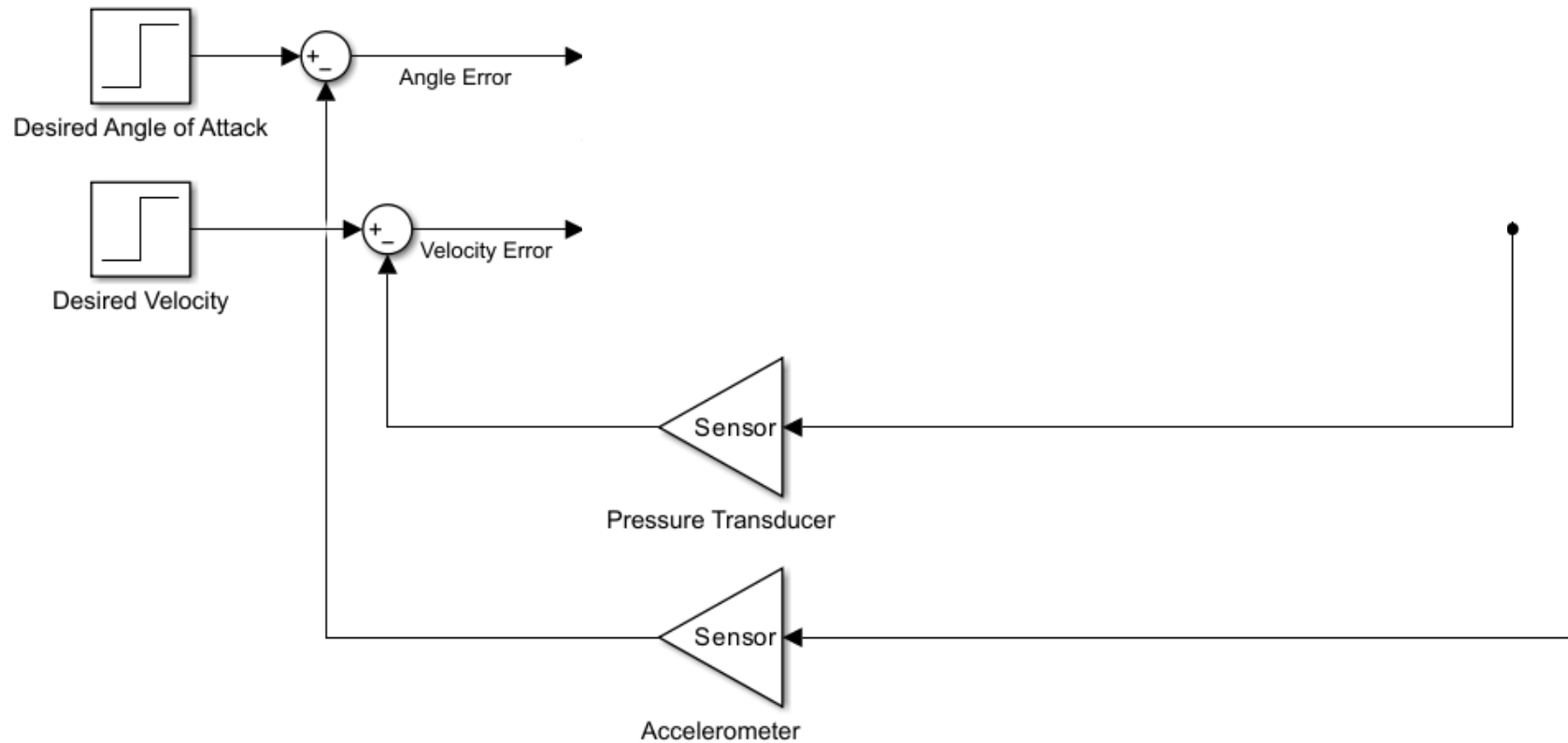
# Glider Block Diagram



# Glider Block Diagram

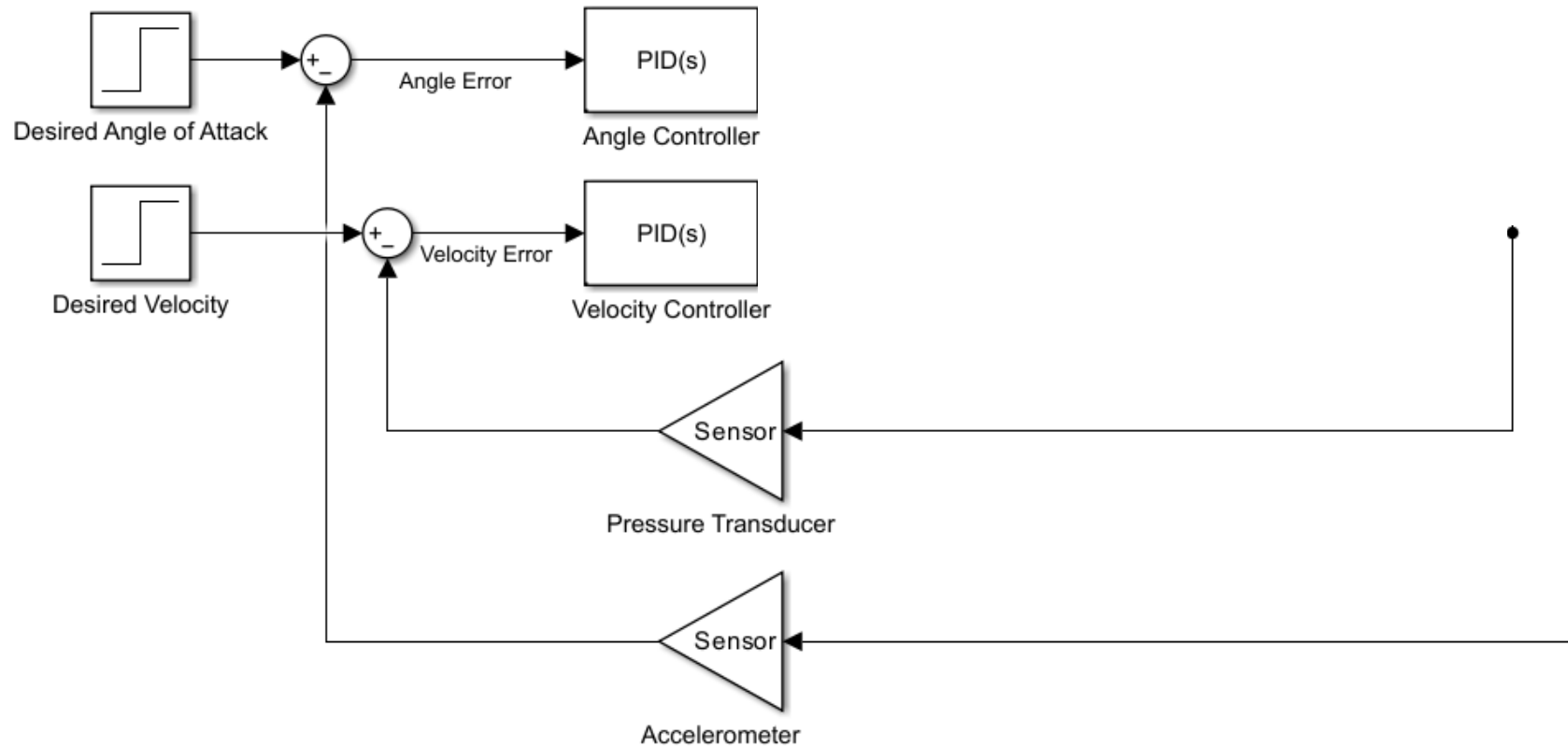


# Glider Block Diagram

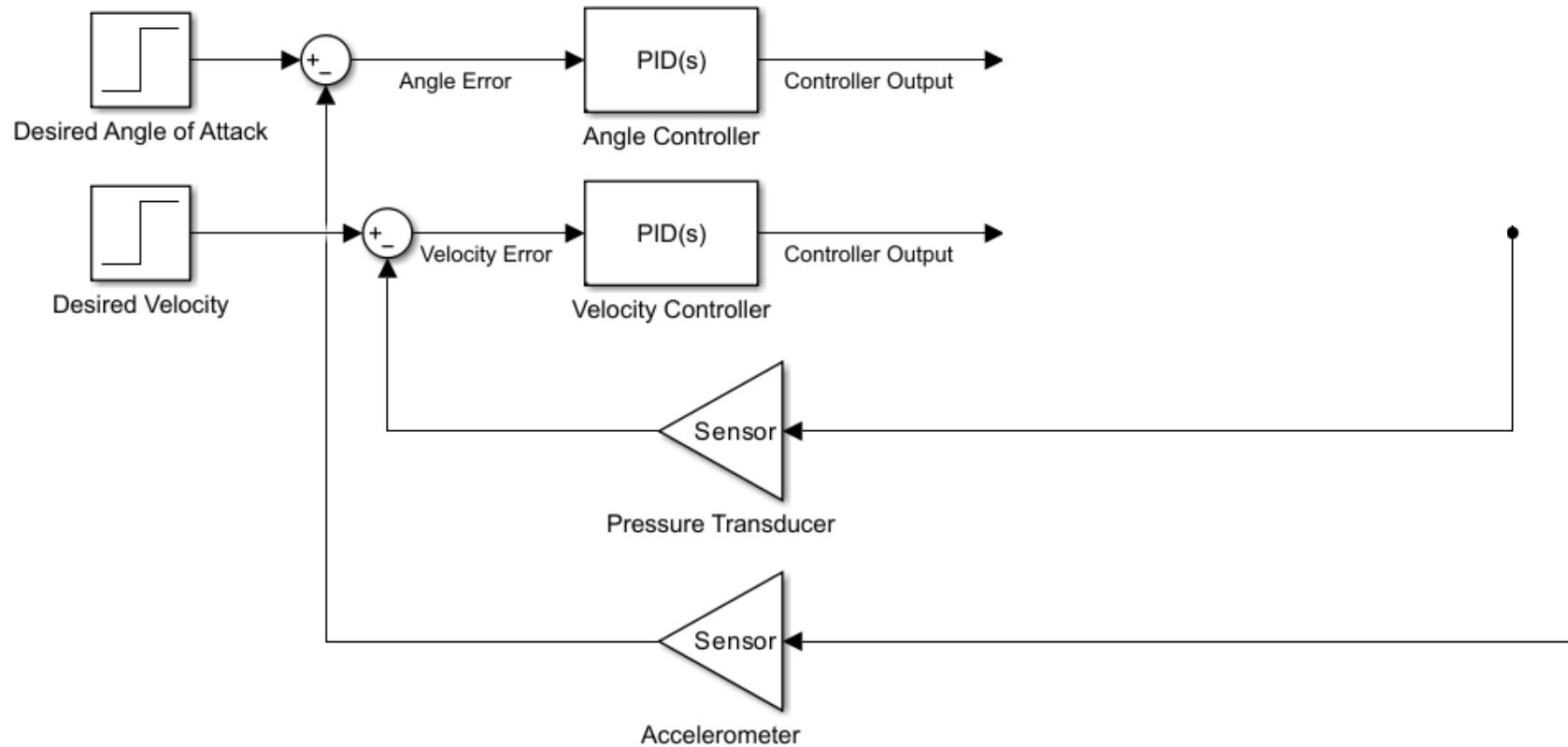




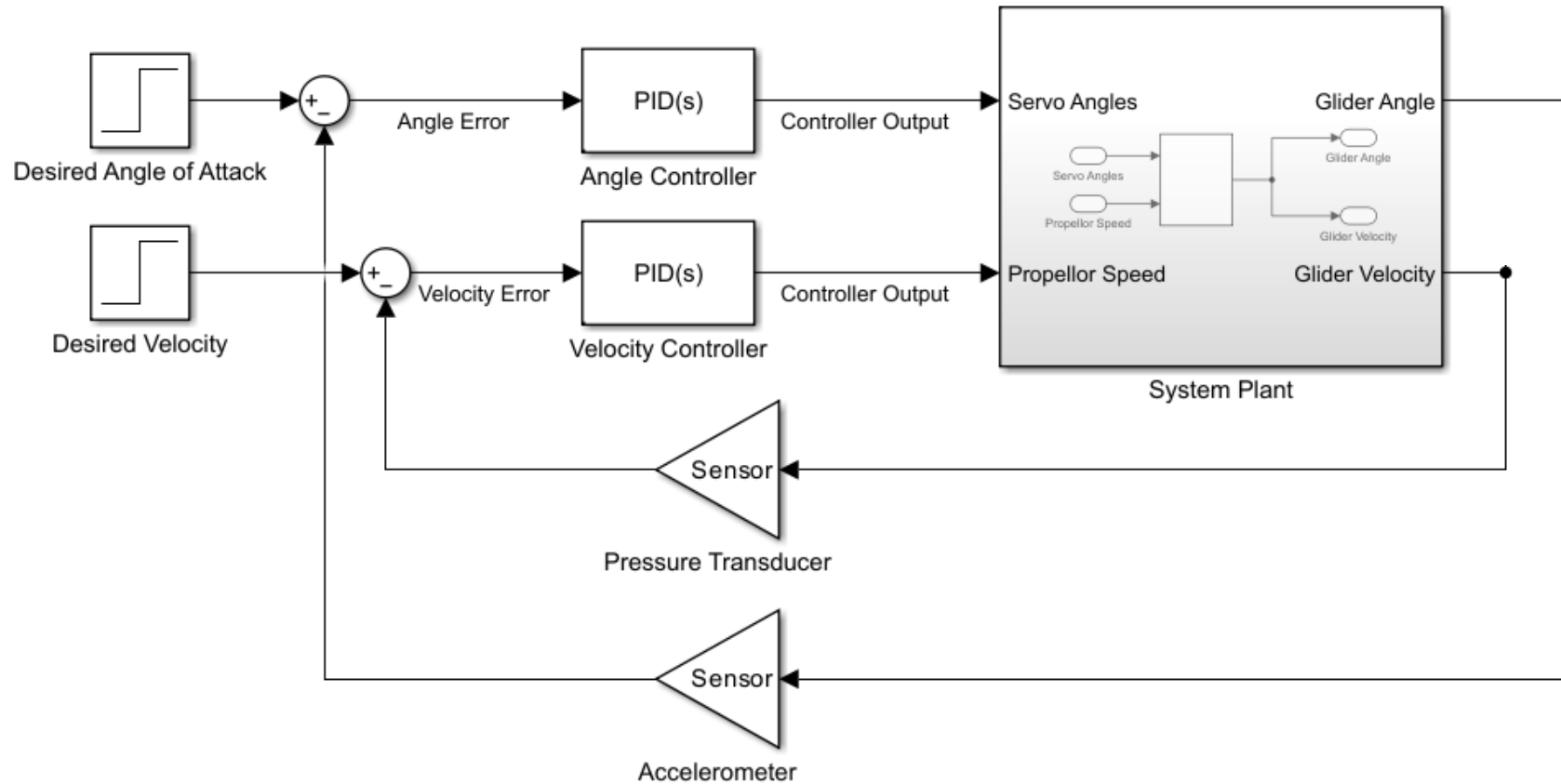
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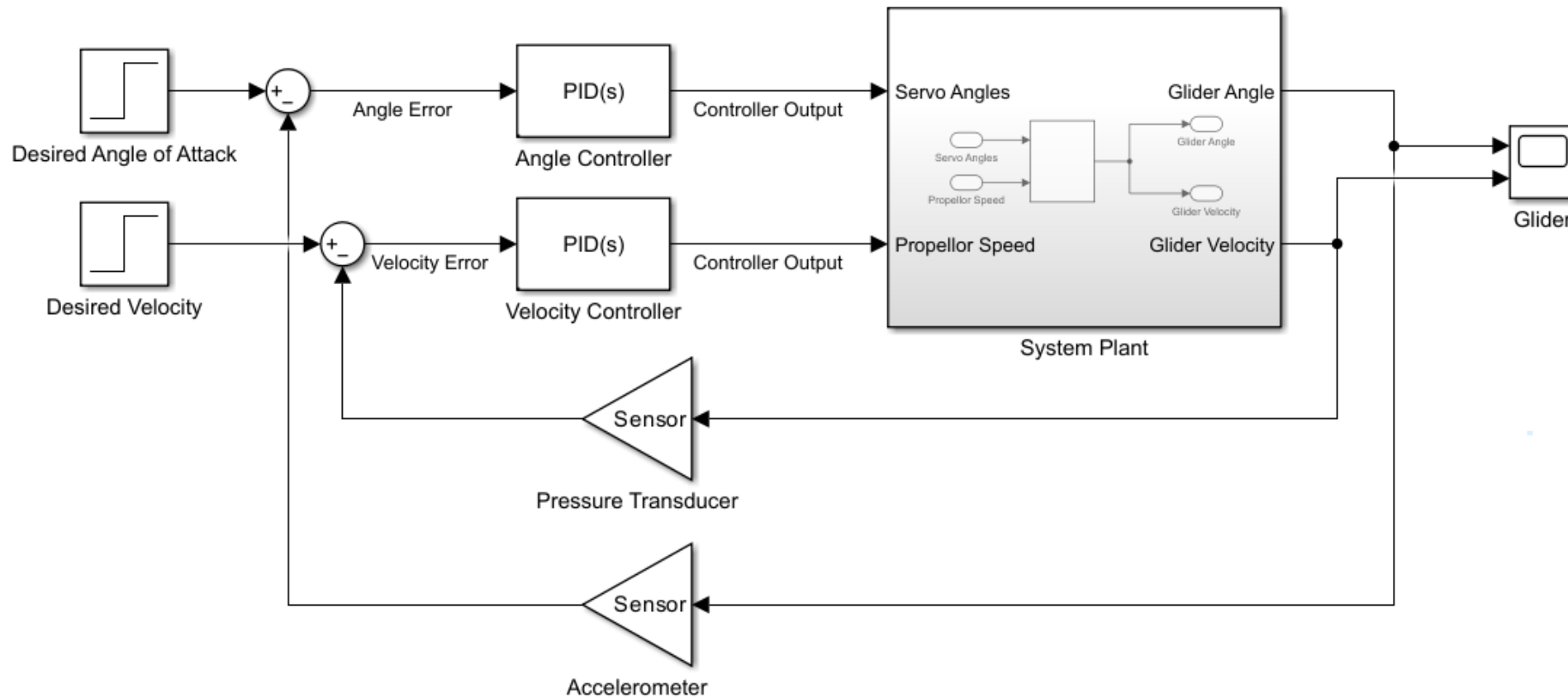
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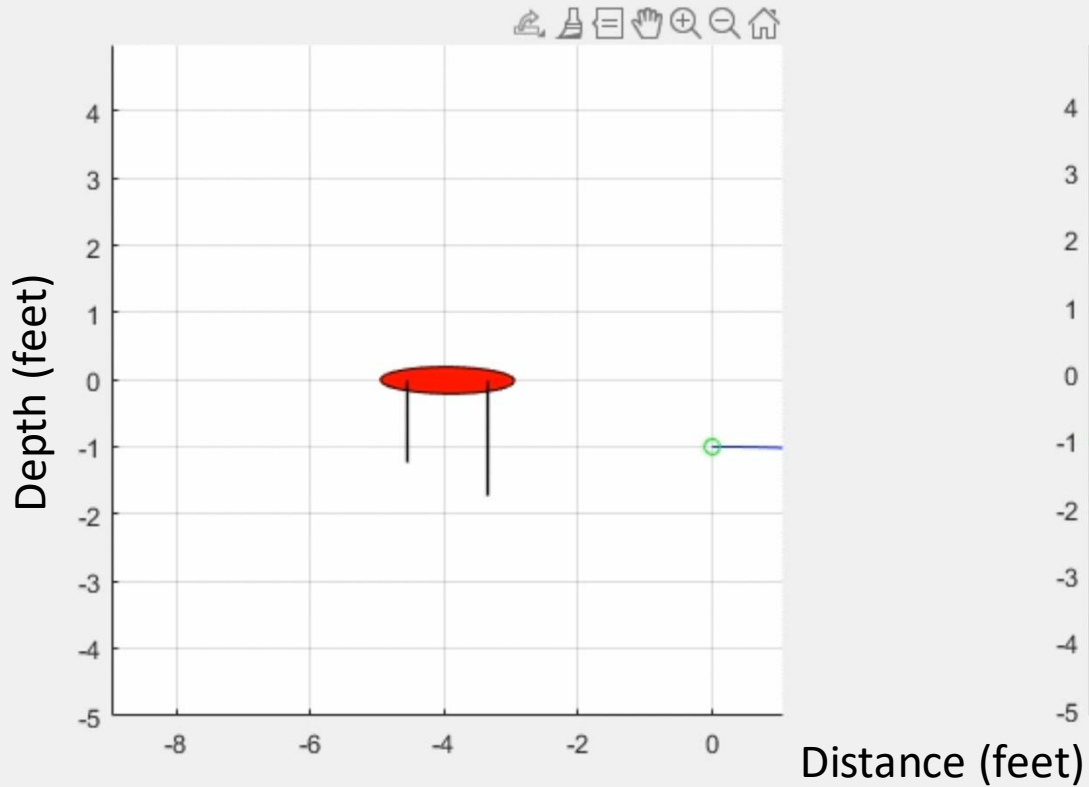


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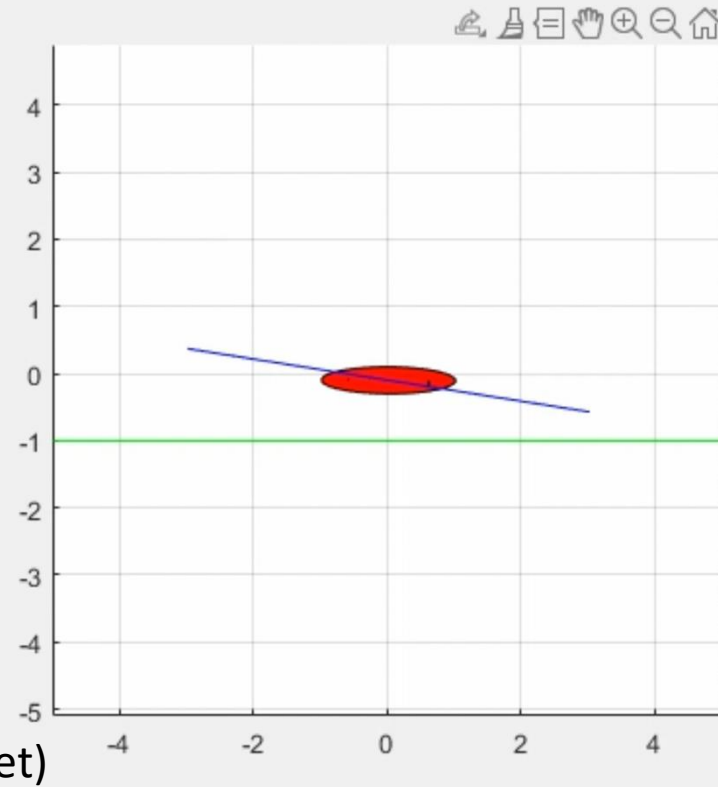


# MATLAB Simulation

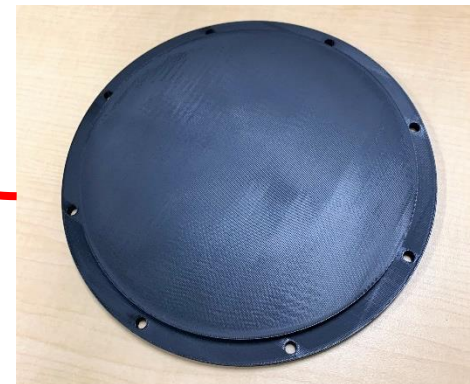
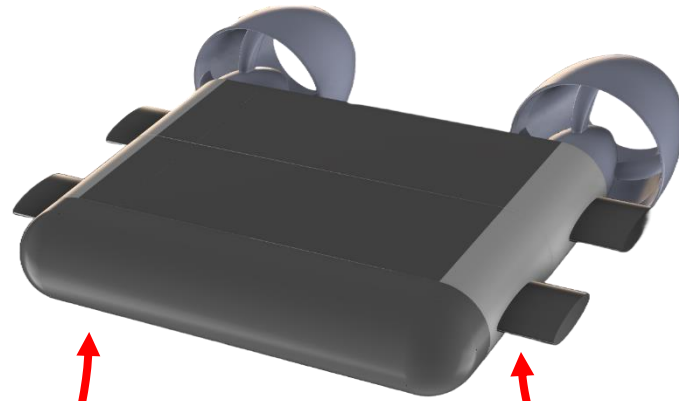
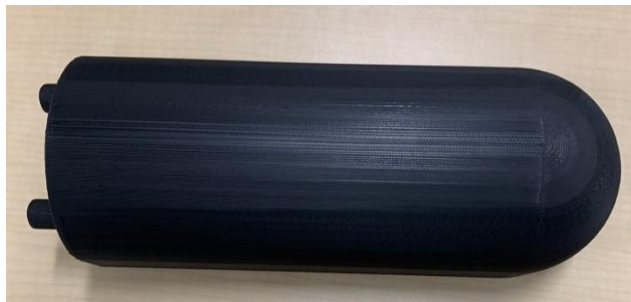
Old Model



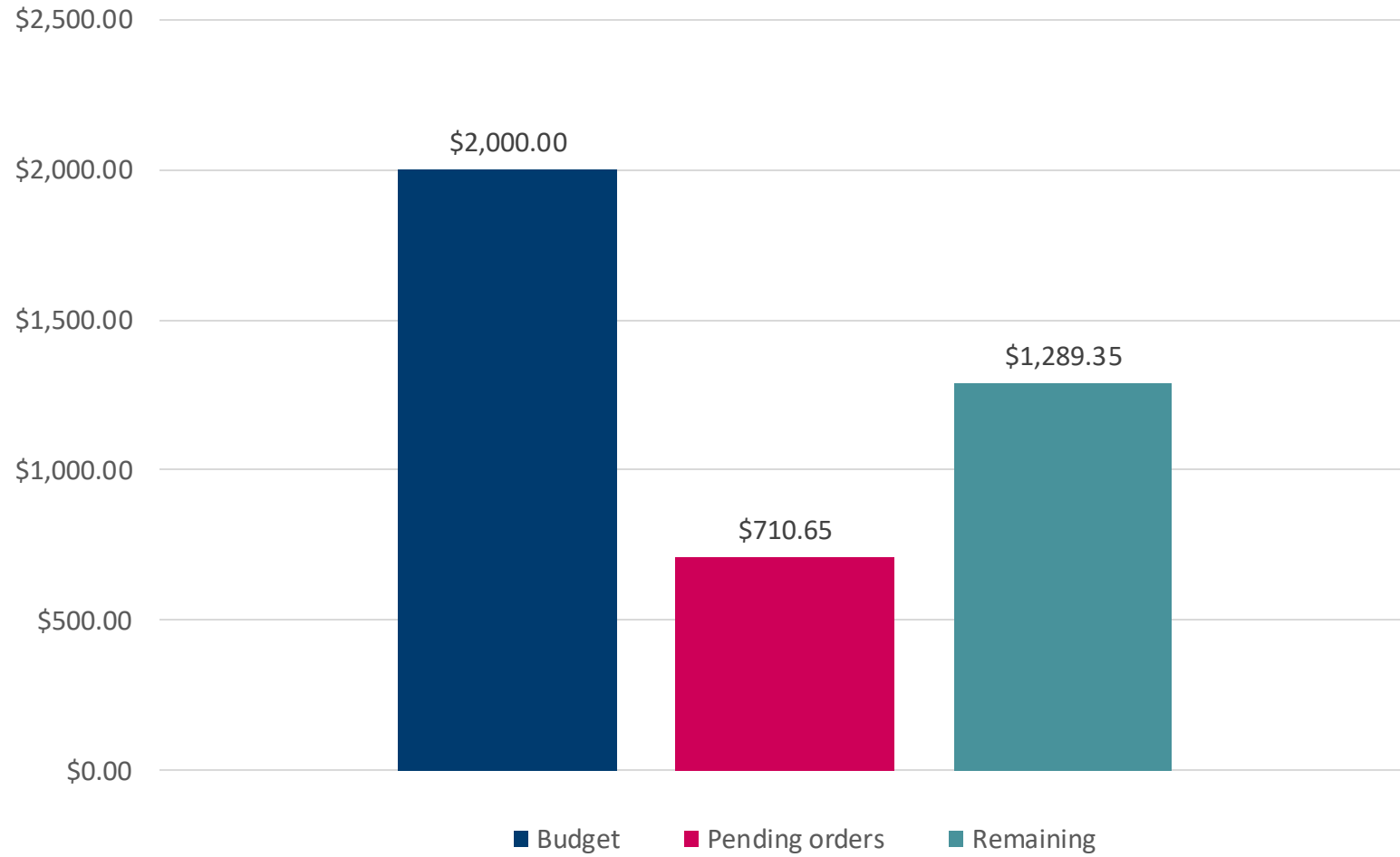
Updated Model



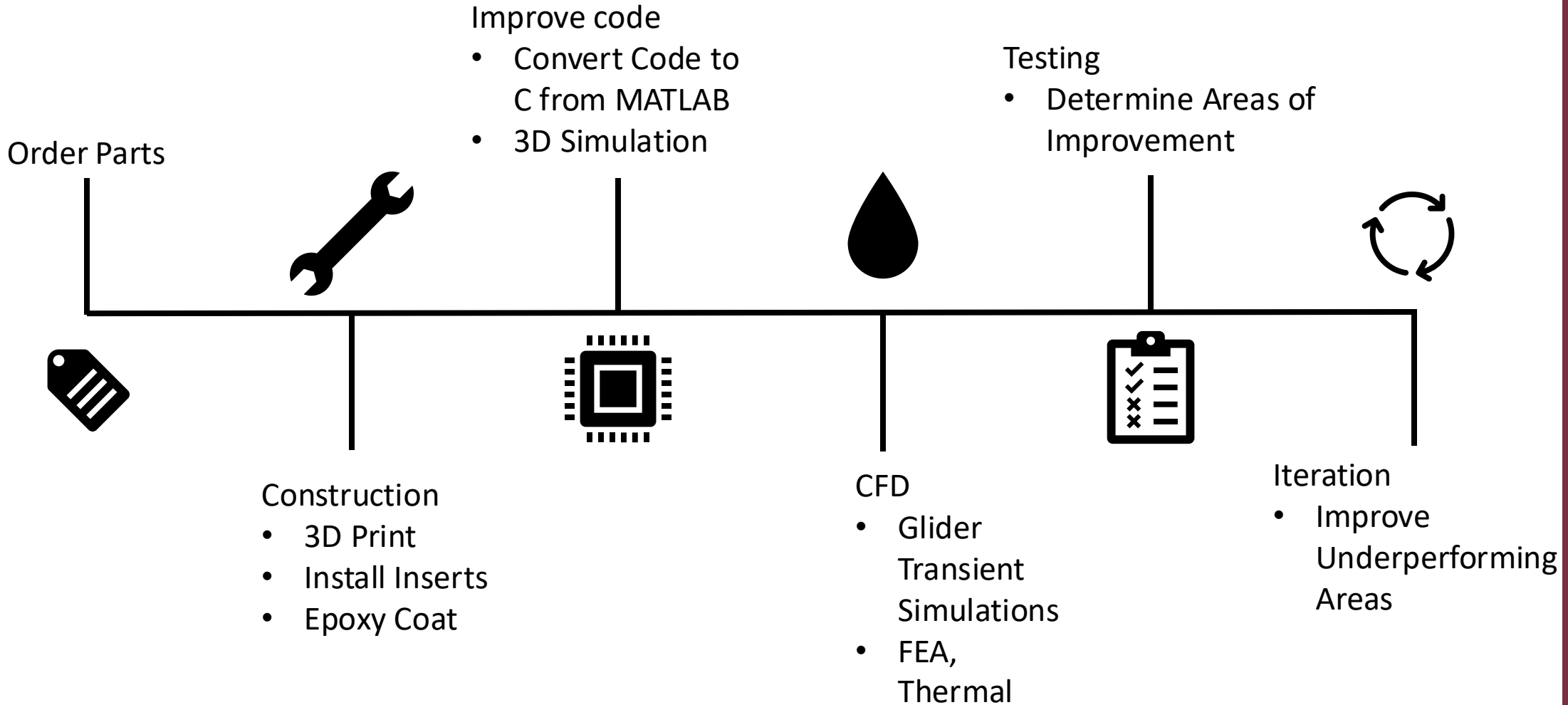
# Manufacturing



# Budget



# Future Work





# Connect on LinkedIn

Jake Burns



Tristan Hardy



Nicolas Lorin



Justin Sepulveda



Martin White

