Virtual Design Review 5

Team 506: Corning Plugger Pallet Short Part Stabilization

Team Members



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Mechanical Test Engineer



Robert C. Kosmas

Structural Design Engineer



Taylor M. Larson

Dynamics Engineer



Segundo A. Sanchez

Materials Analysis Engineer



Jared T. White

Manufacturing Engineer



Sponsors and Advisors

Jeffery Roche



Engineering Mentor

Heavy Duty Project

Manager

Jeffery Stott



Engineering Mentor
Equipment Engineering
Manager

Eric Hellstrom, Ph.D



Academic Advisor

Materials Science

Program Director



Project Objective

The objective of this project is to produce a stabilization system to protect ceramics on Corning's conveyor while reducing the required manual labor.



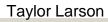
Project Background





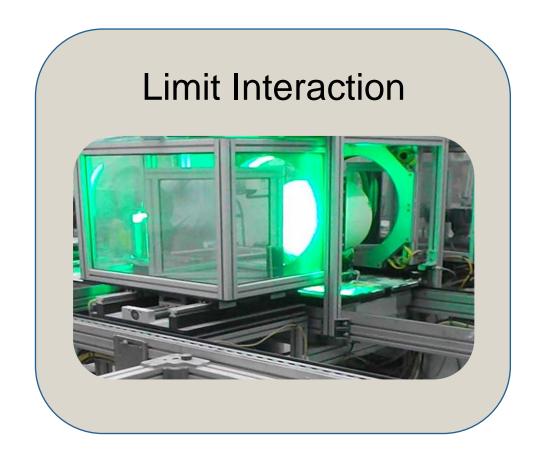




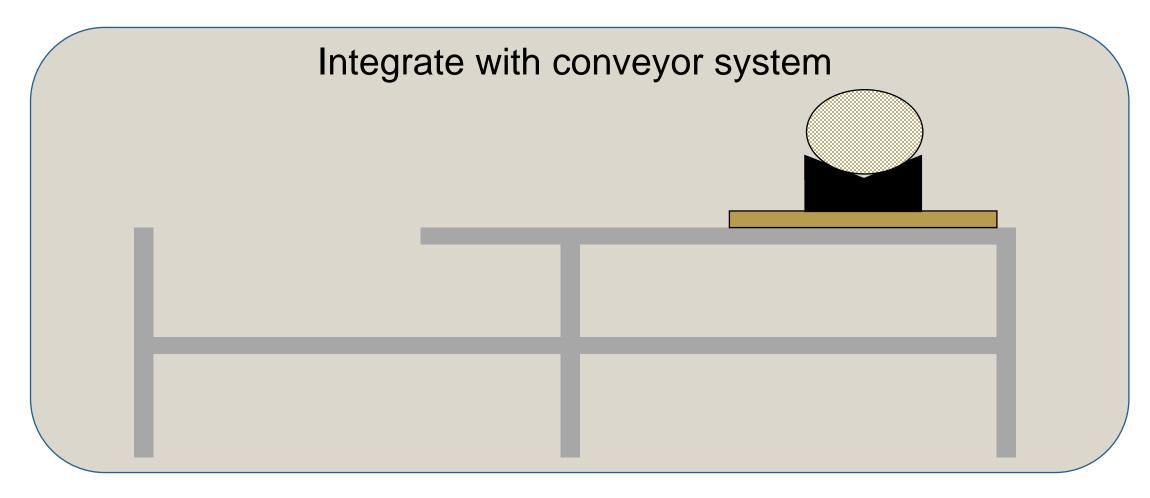












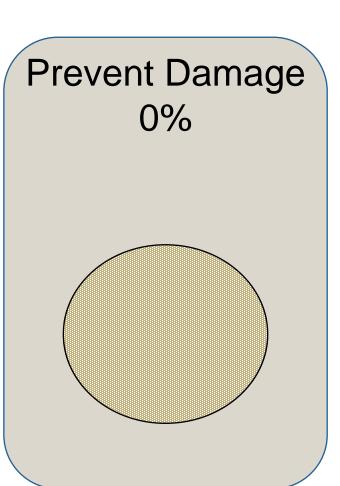


Critical Targeta



Critical Targets

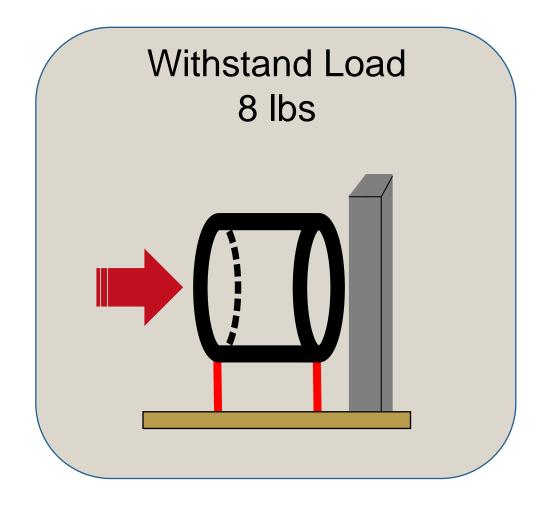
Secure Ceramic 1 DOF

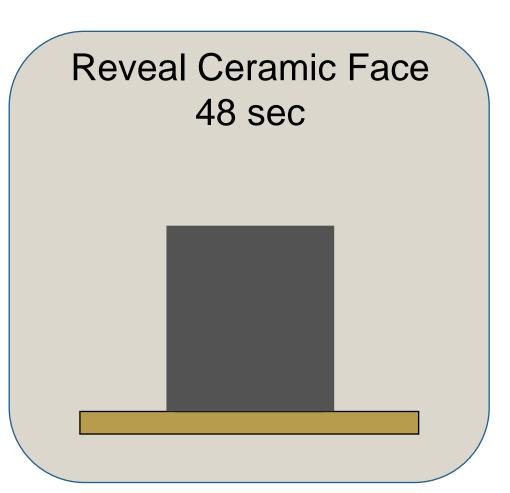






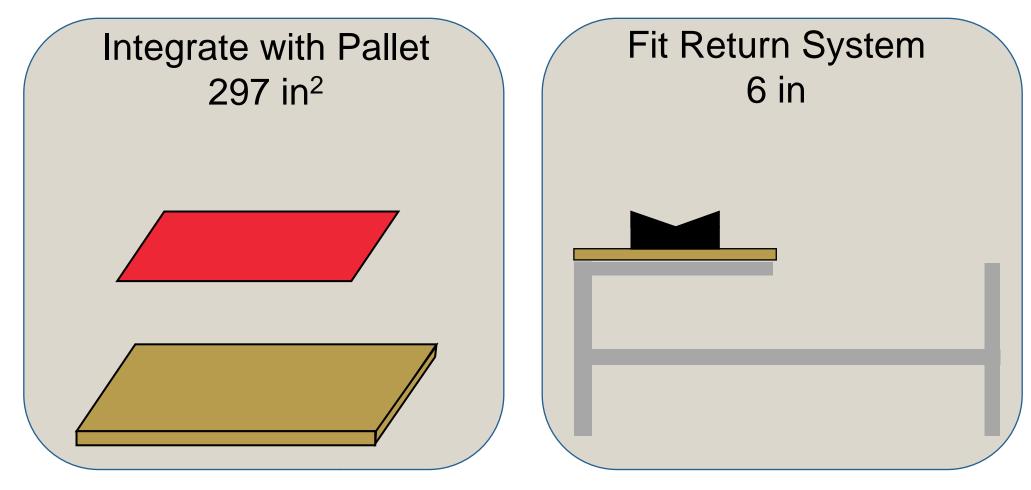
Critical Targets



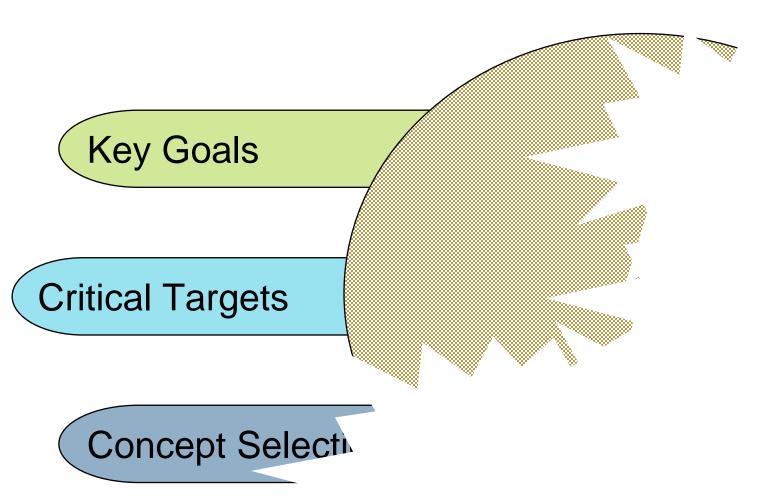




Critical Targets

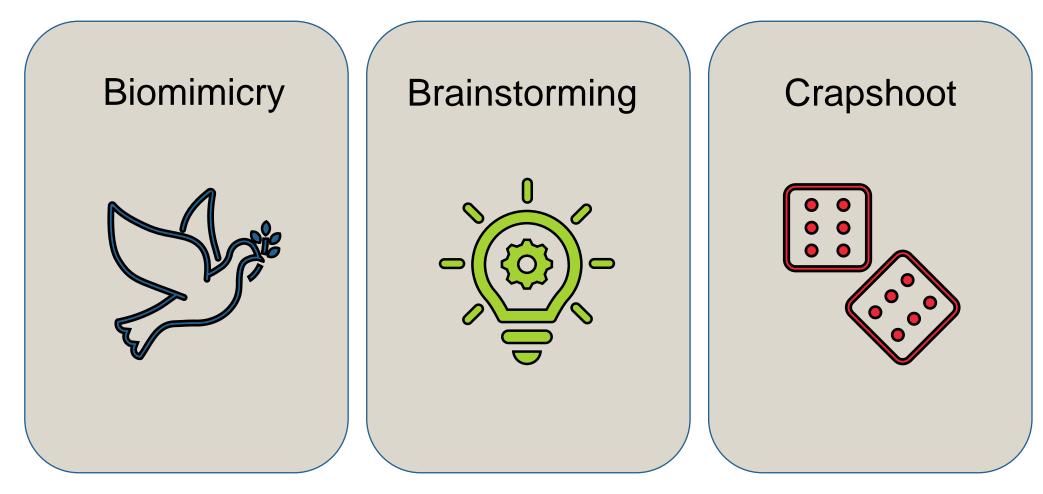






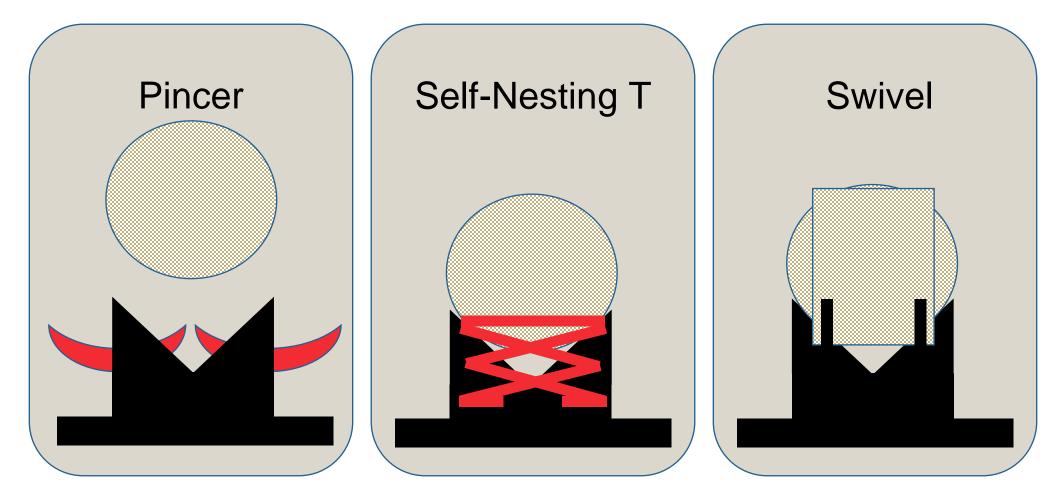


Concept Generation Tools



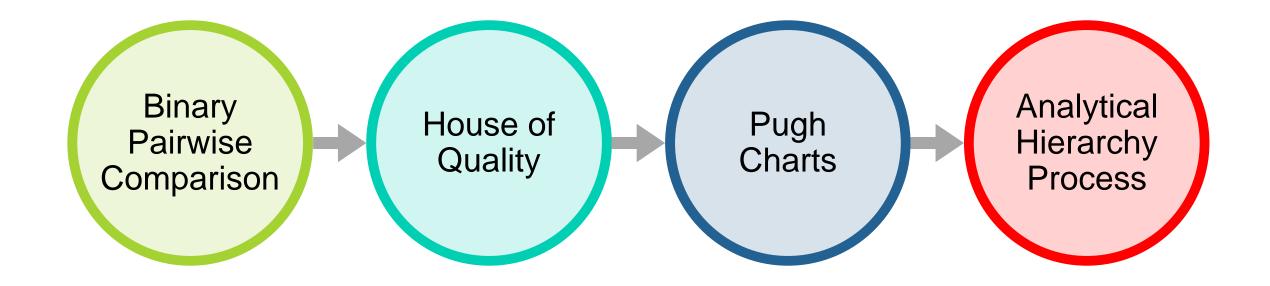


Top 3 Concepts Generated





Concept Selection

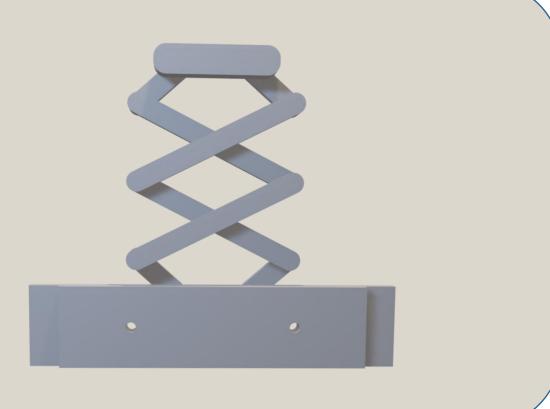




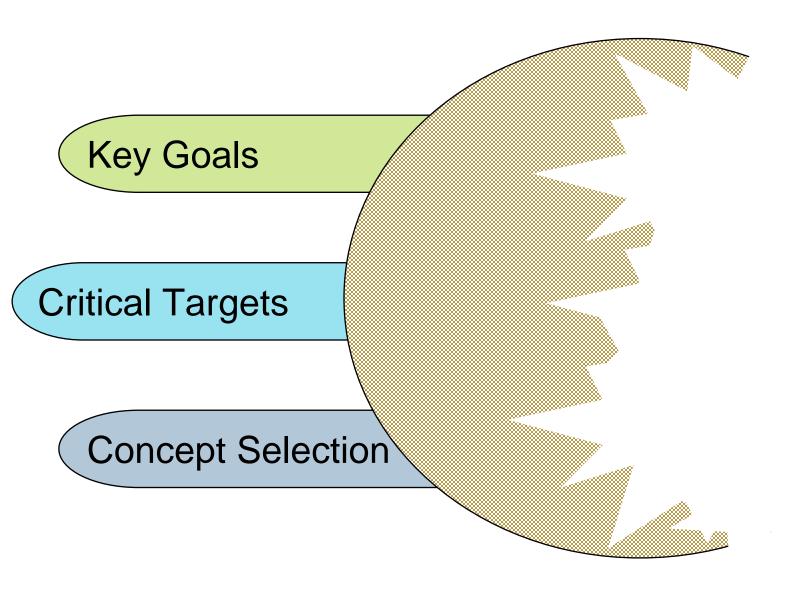
Final Selection

Self-Nesting T

- Similar to working design
- Trigger activated and collapsible
- Uses mechanism on conveyor to activate



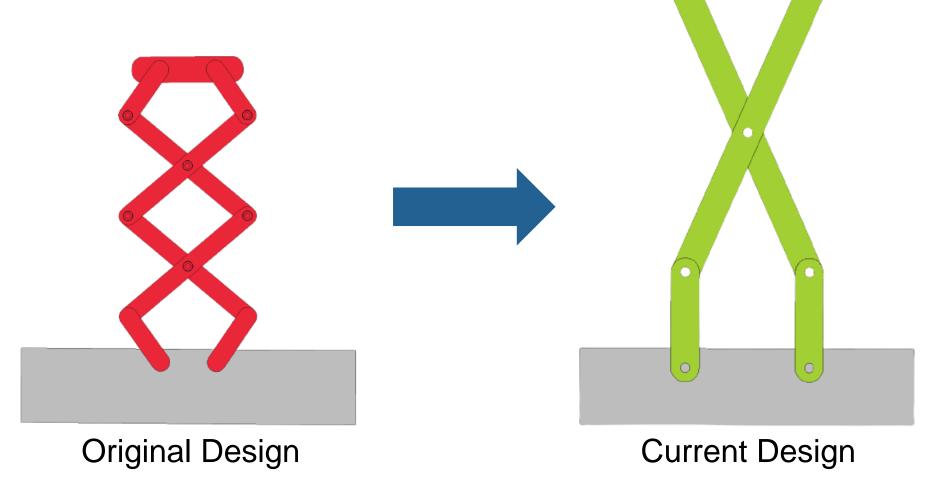




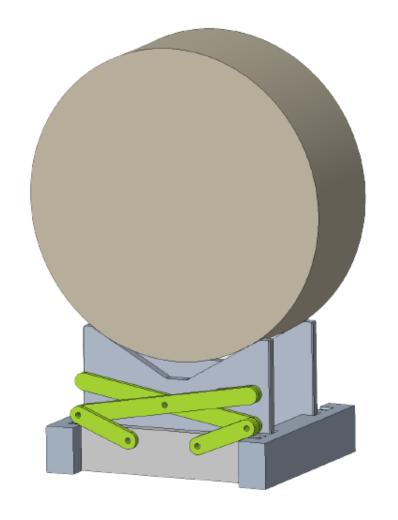


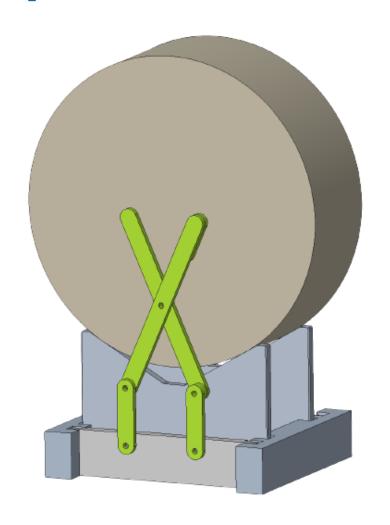


Design Update

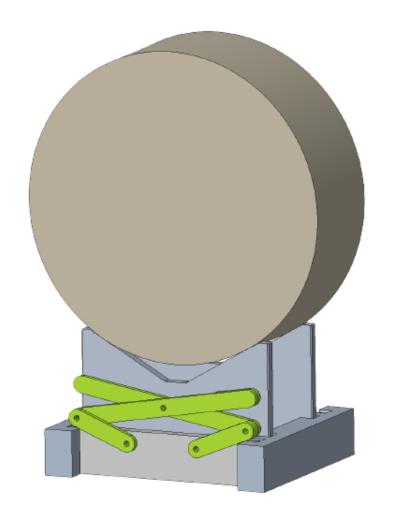


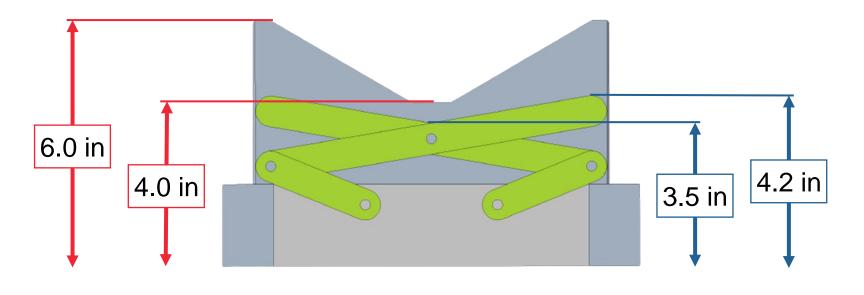




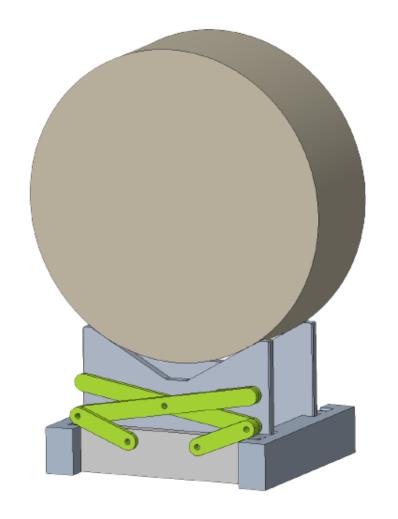


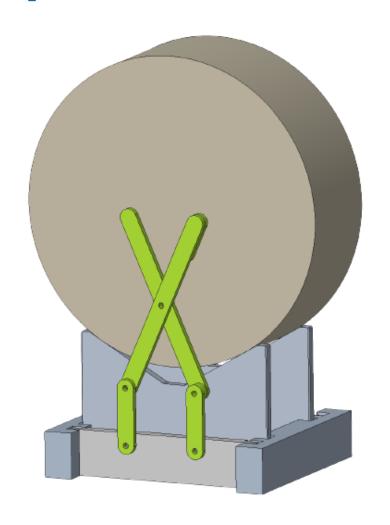




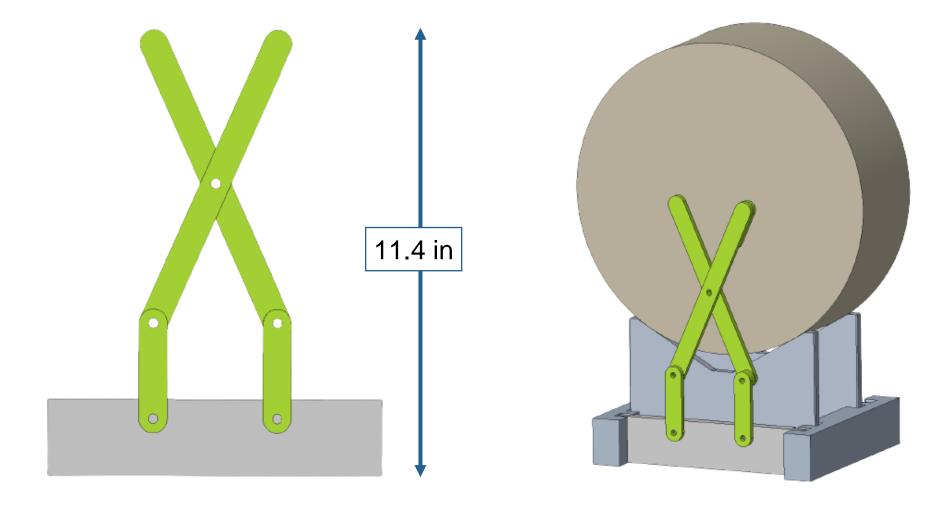




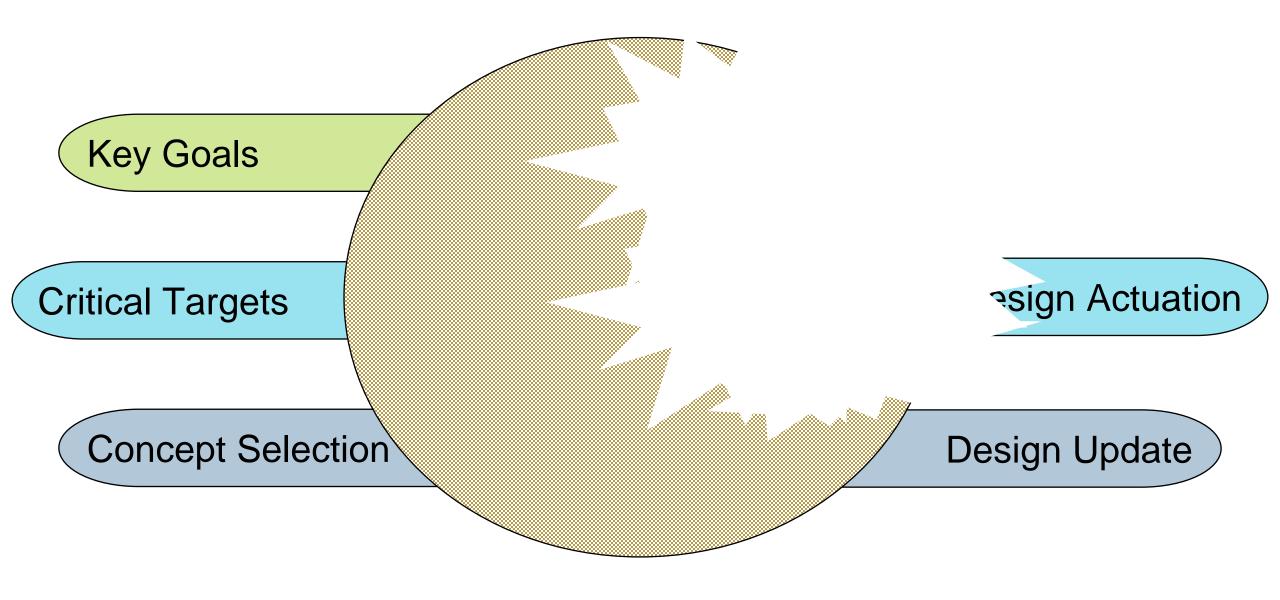








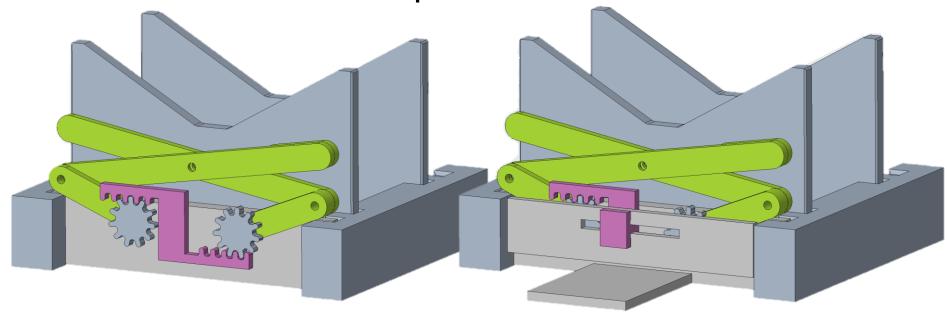






Gear and Rack Slider

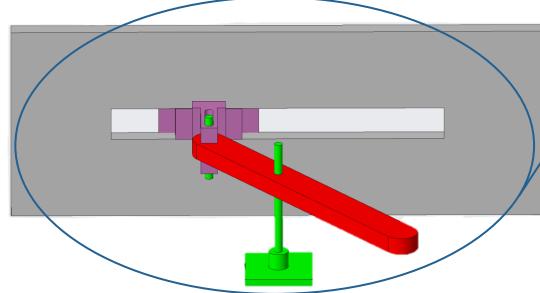
- "Z" shaped rack allows simultaneous rotation
- Slides in a slot on the outer wall
- Raised outer wall allows for particle flow

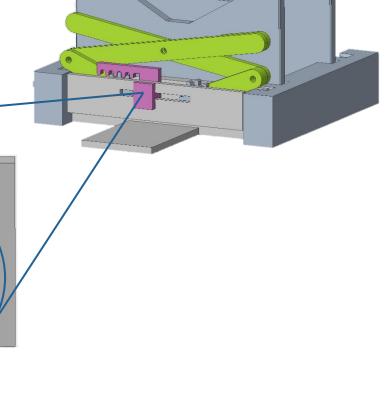




Slider Joint and Switch

- The rack will act as a slider
- Slotted joint connection will allow for rotation of the switch

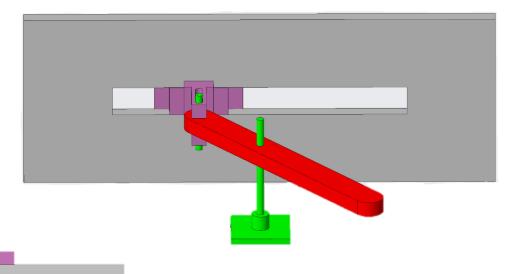


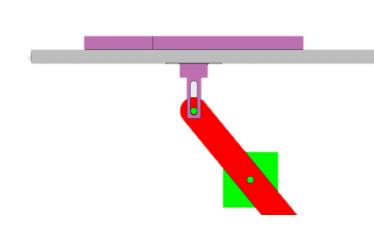


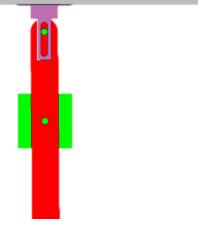


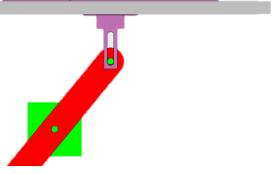
Slider Joint and Switch

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Material Selection

Base and Linkages

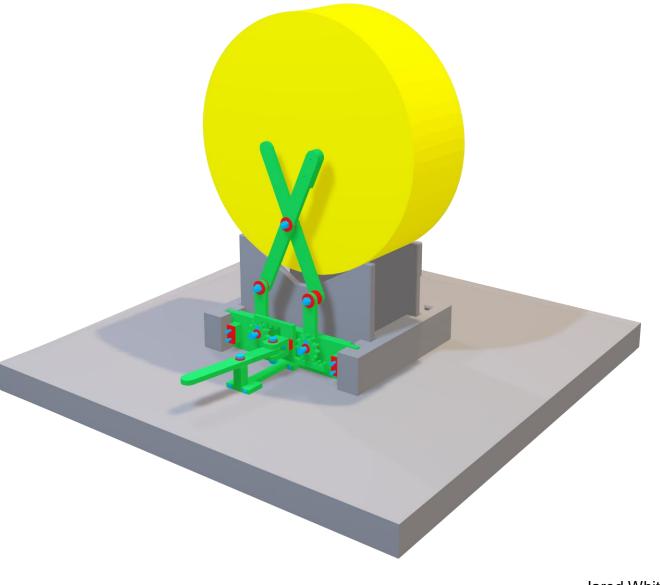
Aluminum 6061

Joints

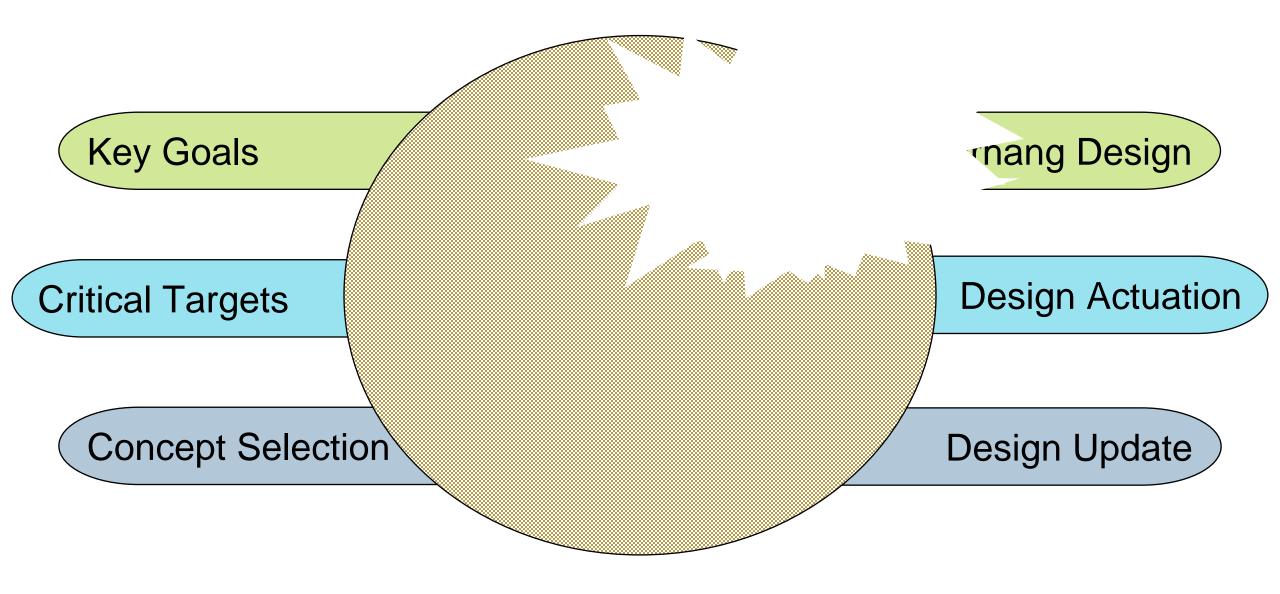
Alloy steel shoulder bolts

Washers and Spacers

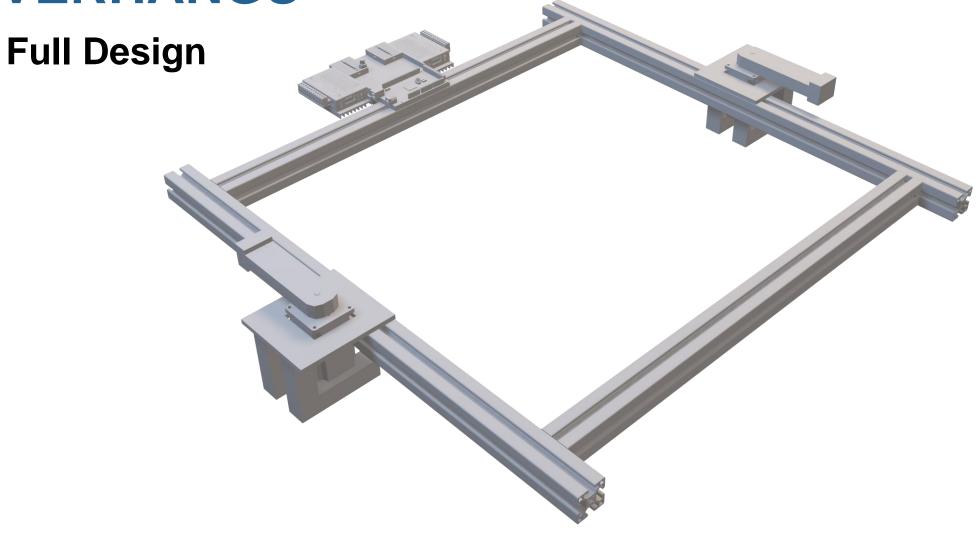
UHMW Polyethylene





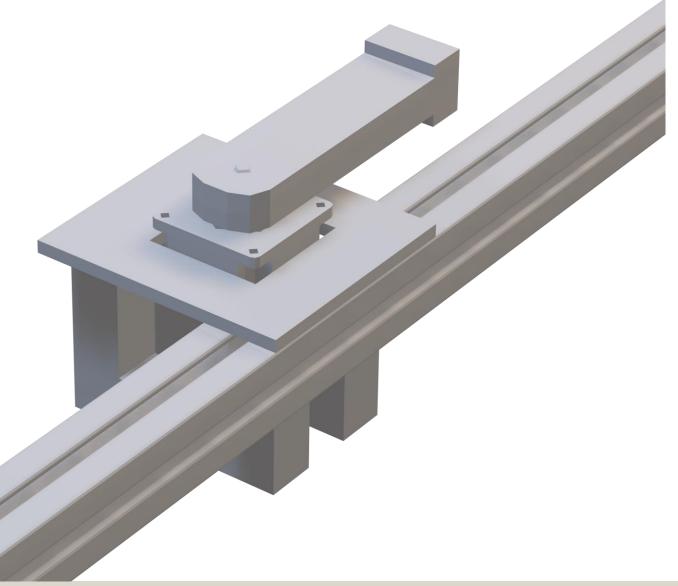






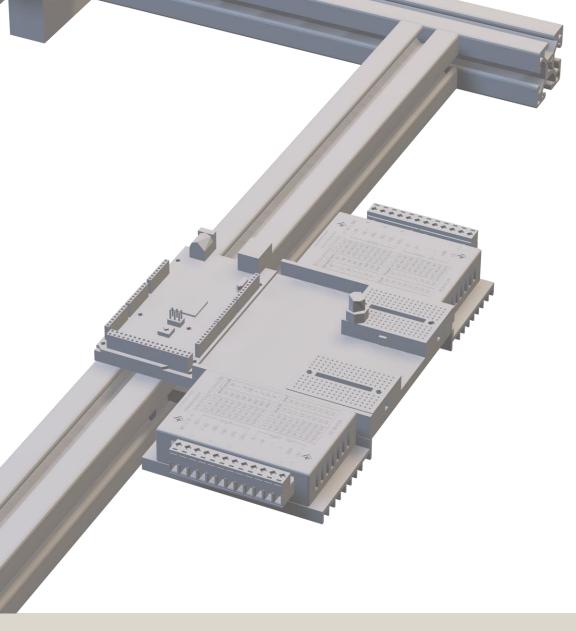


Full Design

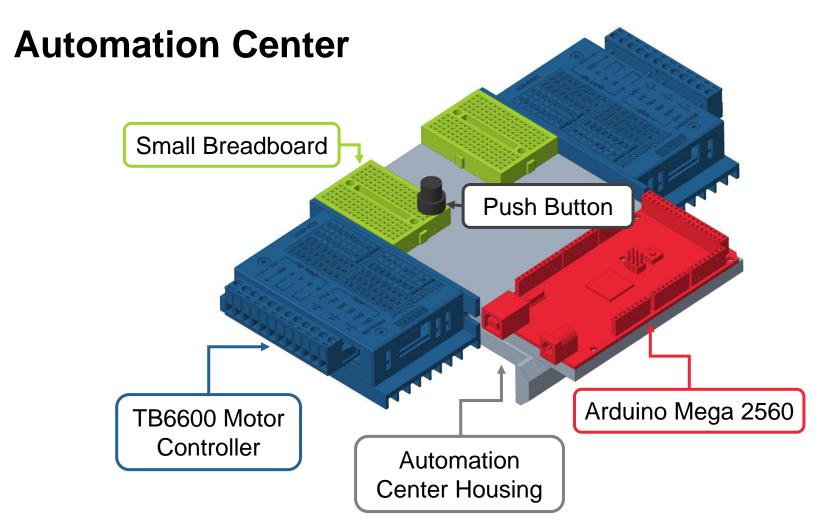


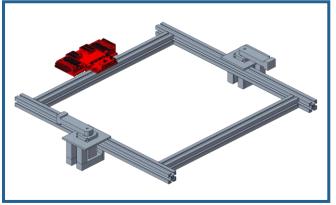


Full Design





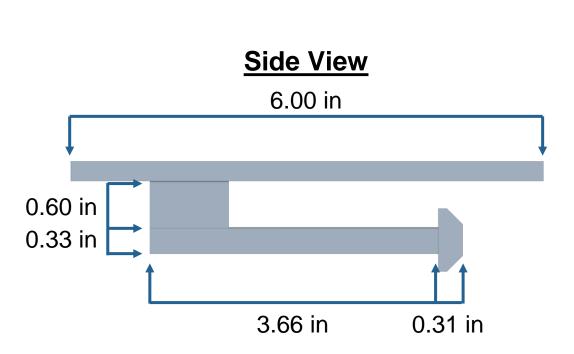


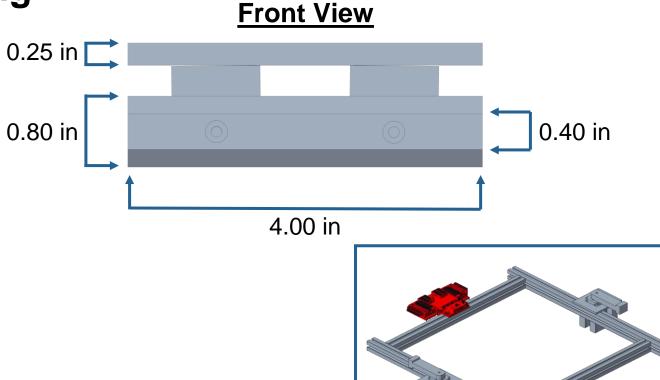


Pawel Grum

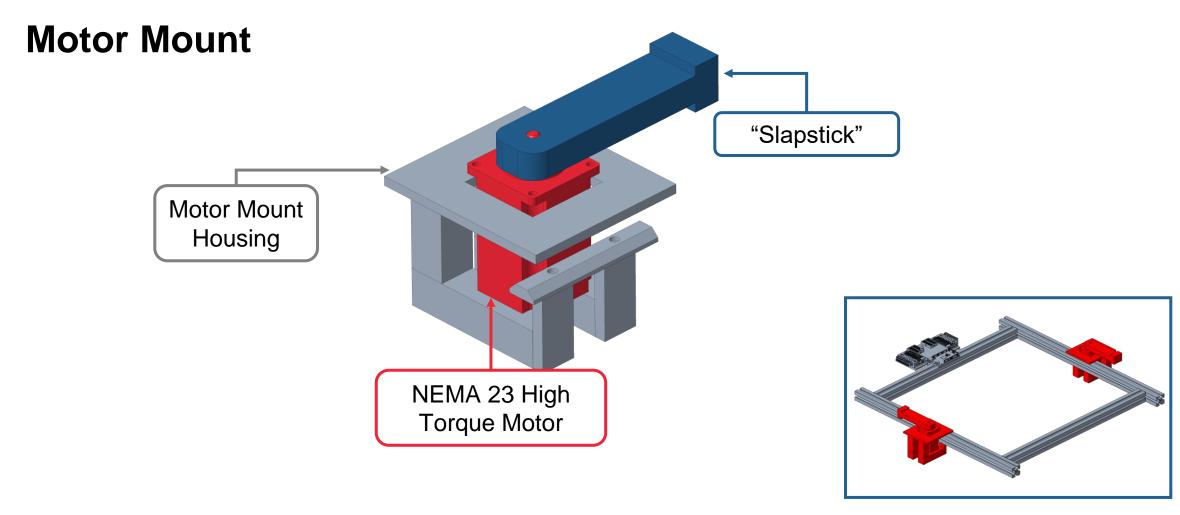


Automation Center Housing



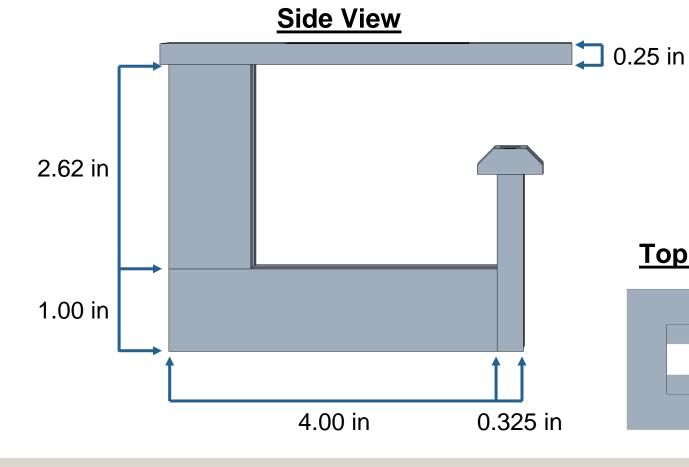


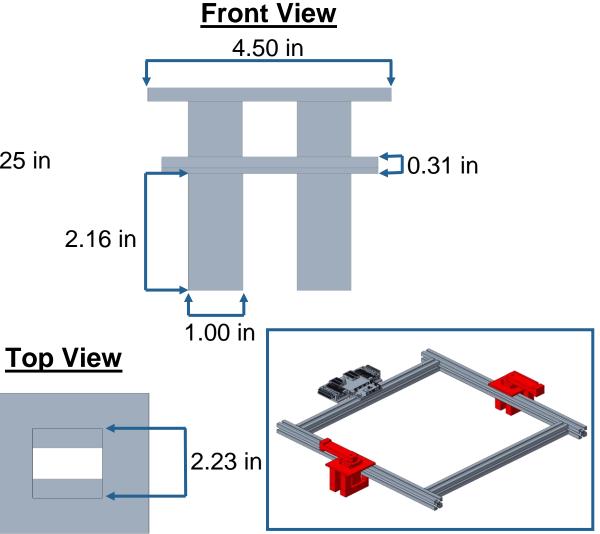






Motor Mount Housing







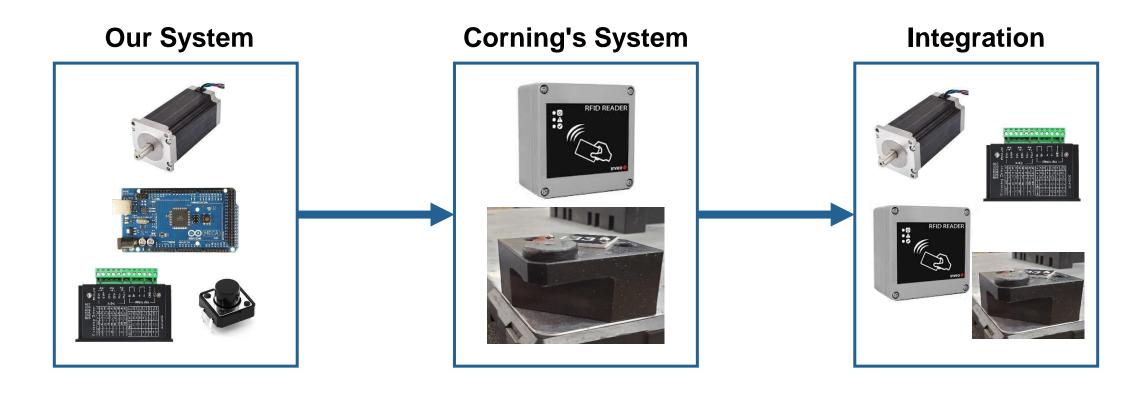
CONNECTION MAP

Flow Chart for Electronics **Program Control Push Button** Laptop NEMA 23 High Torque Motor NEMA 23 High Torque Motor Motor Motor Power Power Activation Control Arduino Mega 2560 **Motor Control Motor Control** Split 12V Split 12V TB6600 Motor Driver TB6600 Motor Driver 24V Power Supply Pawel Grum



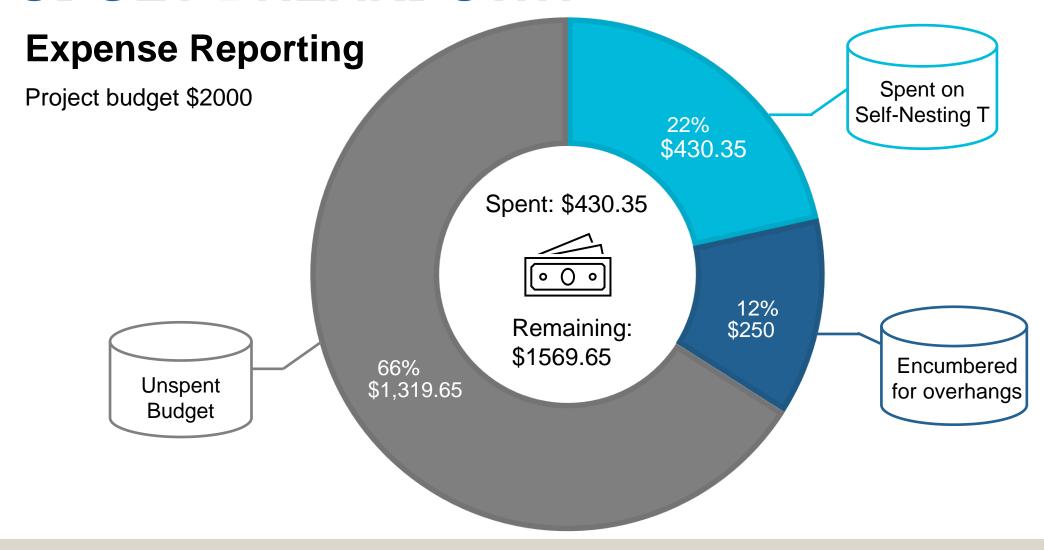
CONNECTION MAP

Corning RFID Integration

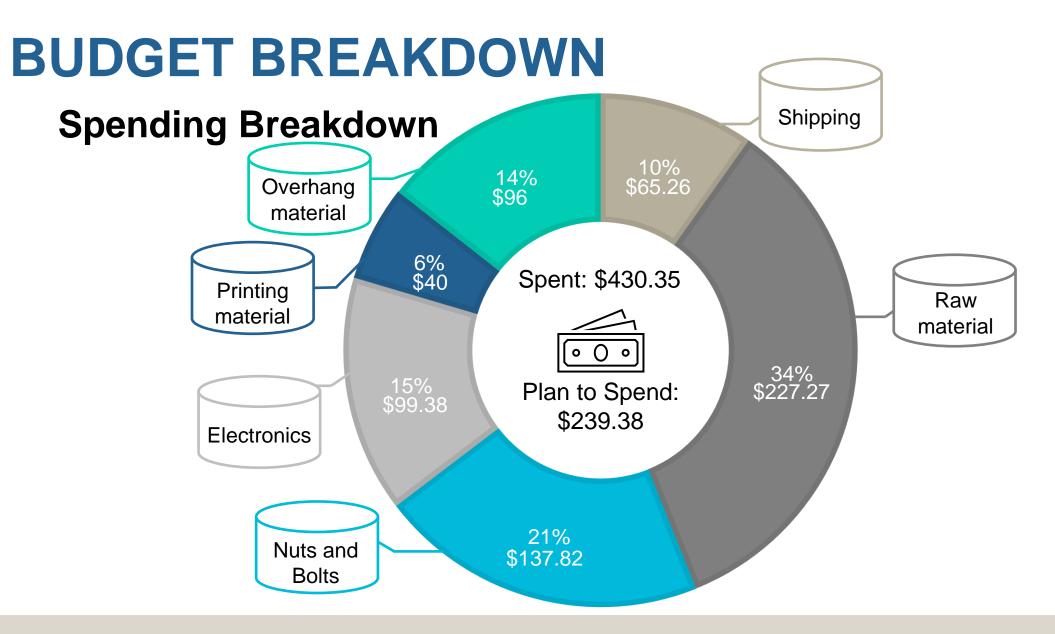




BUDGET BREAKDOWN









CURRENT CHALLENGES

- Finalize motorized overhang component selection
 - Determine final materials, motor type, and connection type
- Finalize motorized overhang CAD
 - Get CAD machine shop approved, order parts, and begin machining
- Test mechanisms durability
 - ☐ Mobility during harsh conditions, impact resistance, material resistance
- Improving initial prototype
 - ☐ Improvement to design, and functionality



FUTURE WORK

Order materials for overhangs

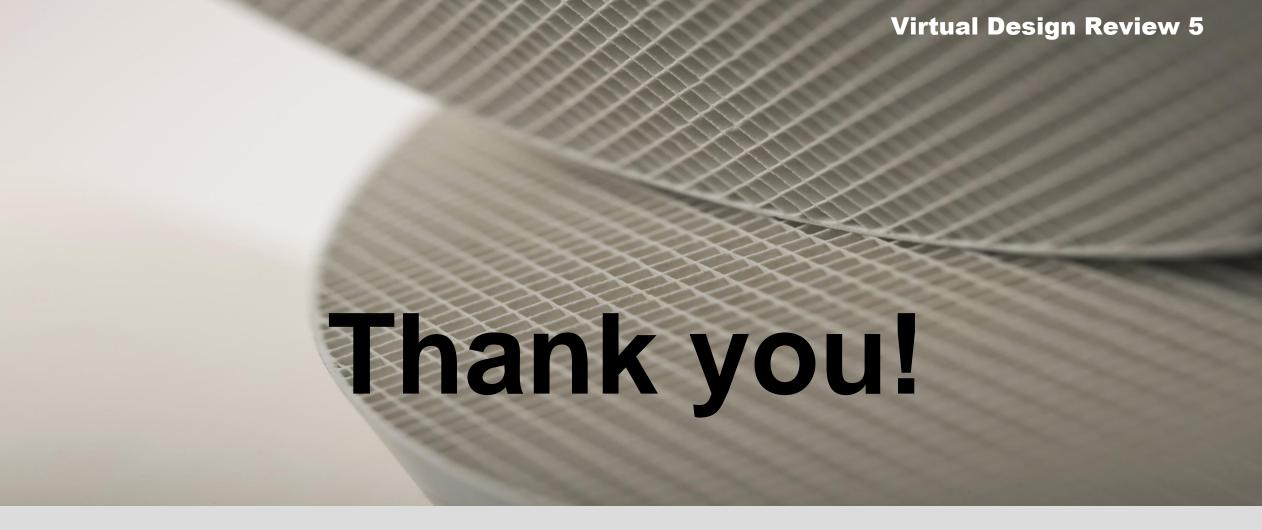
Test and evaluate prototype performance

Prepare final presentation for design day

Finalize CAD for overhangs

Make improvements to prototype





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