



EML4551-2

# Human Powered Vehicle (HPV)

04-October-2018



FAMU-FSU  
COLLEGE OF  
ENGINEERING



FAMU-FSU Engineering

MECHANICAL ENGINEERING

# Team Introductions



Project Manager



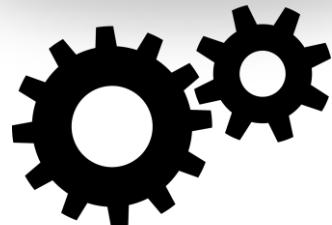
Steering Engineer



Powertrain Engineer



Ergonomics Engineer



Tristan Enriquez



# Project Objective

Create a wheeled transportation device that is safe, practical, agile, and fast.

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**Sponsor:** Jess Ball

The team will compete in the ASME North American E-Fest in East Lansing, Michigan in April of 2019.





# Project Background



# The Competition



## Design

- Methodology
- Testing and Analysis
- Safety
- Aesthetics



## Speed

- Timed race
- Top speed
- Men and Women



## Endurance

- Agility, Utility and Durability
- Obstacles
- Inclines and Declines
- Tight turning

Tristan Enriquez



# The Competition



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## Endurance

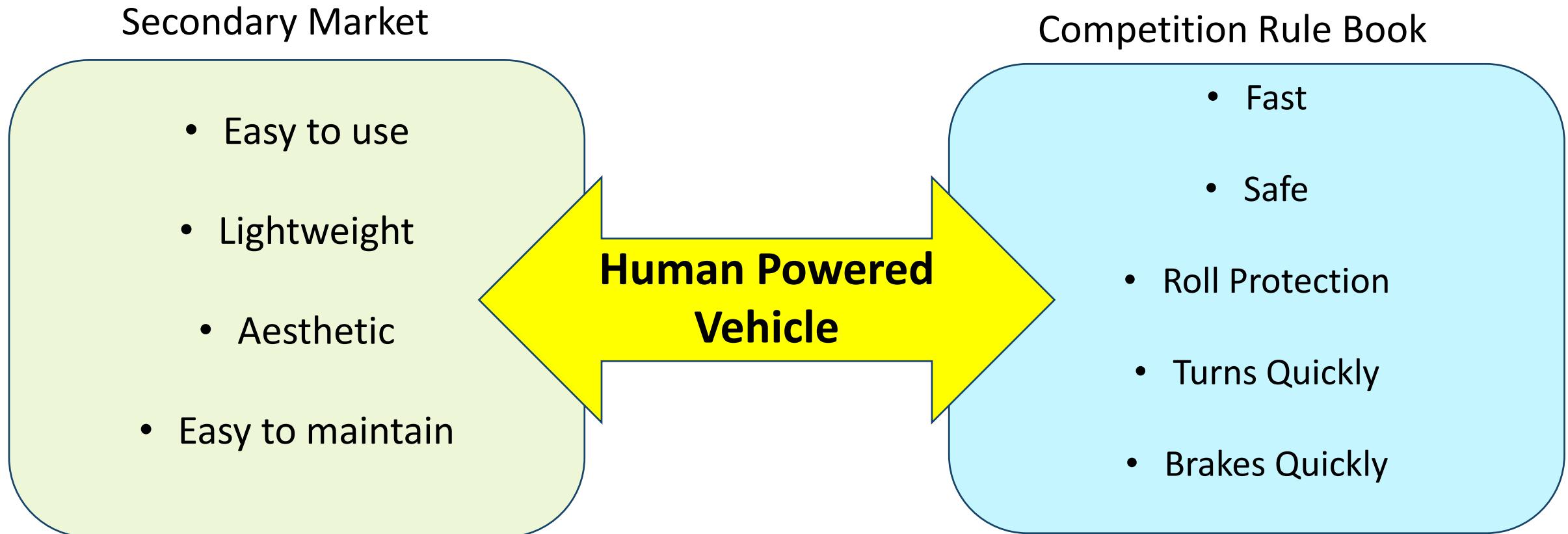
- Agility, Utility and Durability
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Tristan Enriquez



# Customer Needs

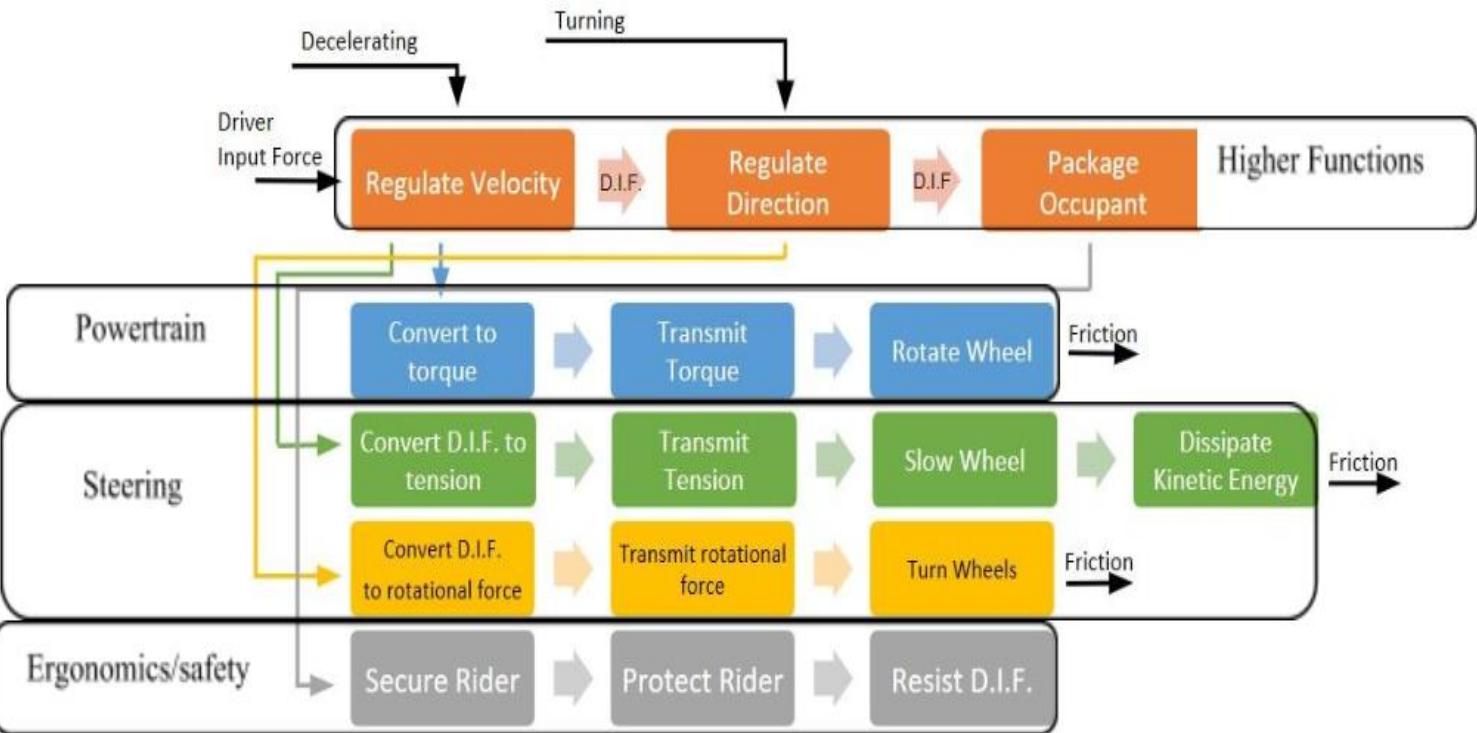
Customer needs developed using the rule book and perceived needs of a secondary market



# Functional Breakdown

## Targets/Metrics

- Top speed of 40 km/h
- Brake in 4 m at a speed of 25 km/h
- Turning radius of 6.0 m
- Supports 2670 N load applied to top roll protection system (RPS) in the event of a rollover
- Supports 1330 N load applied to roll bar at shoulder height



Jacob Thomas 7



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# Five Most Important Points from this Lecture

1. The quick brown fox jumps over the lazy dog. The quick brown fox jumps over the lazy dog.
2. The quick brown fox jumps over the lazy dog. The quick brown fox jumps over the lazy dog.
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4. The quick brown fox jumps over the lazy dog. The quick brown fox jumps over the lazy dog.
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# References

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# Questions



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