Designing and Flying an Experimental Sounding Rocket

TEAM 24 ALEX MIRE TARIQ GRANT WILLIAM POHLE BRANDON GUSTO

10/13/2016 SPONSOR: FAMU-FSU COLLEGE OF ENGINEERING ADVISOR: DR. RAJAN KUMAR

Problem Statement & Scope

Design and construct a rocket capable of carrying an experimental payload to be launched and safely recovered within the parameters of the 2017 Intercollegiate Rocket Engineering Competition hosted by the Experimental Sounding Rocket Association.



Figure 1: 2015-2016 Intercollegiate Rocket Engineering Competition^[1]

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Goals

- •Successfully design, build and fly a single stage rocket
- Reach an apogee of 10,000 ft AGL
- Deploy a scientifically useful payload
- Safely recover all rocket components
- •Win the competition



Figure 2: General Flight Profile^[2]

Objectives

- 1. Conduct Background Research
- 2. Develop Engineering Characteristics
- 3. Conceptual Design
- 4. Detailed Design
- 5. Scale Prototype
- 6. Full Size Prototype
- 7. Flight Testing
- 8. Final Design
- 9. Compete



Figure 3: Conducting Background Research

Vehicle & Payload Constraints

- •Payload must weigh 8.8 lb. minimum
- •Vehicle & payload must be recoverable
- •Must have an altimeter and flight controller
- •Single stage only
- •Non-toxic propellant
- •No hazardous or live material

House of	Qua	lity
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Customer Requirements	Customer Importance	Stability	Rocket Weight	Total Impulse	Reliability	Scientific Value	Material Strength	Avionics
Accurate	7	8		10		7		9
Lightweight	1	6	10				4	4
Recoverable	8	10	7		9	9	7	8
Safe	10	9	3	6	10		8	9

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Score	232	96	130	172	121	140	221
Relative Weight	0.209	0.086	0.117	0.155	0.109	0.126	0.199
Rank	1	7	5	3	6	4	2

Most Important Factors: Stability

Reliability

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Avionics

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Rocket Subsystems



Figure 4: Rocket Subsystems [3]



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Flight Model & Simulation

What the model includes

- Form drag
- Skin friction drag
- Variable atmospheric pressure
- Variable thrust
- Variable vehicle mass

What it doesn't

- Complex geometry
- Lift induced drag
- Compressibility effects
- Vehicle rotation or instability
- Nonlinear propellant burn rate



The model shows that of any single subsystem, the propulsion element has the greatest impact on overall system performance

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Motor Performance Comparison^[4-5]



To reach our target altitude:

M1350P ~ 23 lbs. vehicle weight M1500G ~ 27 lbs. vehicle weight M650W ~ 32 lbs. vehicle weight M900 ~ 38 lbs. vehicle weight M1850W ~ 44 lbs. vehicle weight M750W ~ 46 lbs. vehicle weight

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Mach Regime Comparison^[4-5]



Expected Mach number:

M1350P ~ 0.8 at 23 lbs. M1500G ~ 0.8 at 27 lbs. M650W ~ 0.6-0.7 at 32 lbs. M900 ~ 0.6 at 38 lbs. M1850W ~ 0.6-0.7 at 44 lbs. M750W ~ 0.5-0.6 at 46 lbs.

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Nose Cone Shape Optimization

- Cone shape has an influence over the drag experienced by the rocket.
- Ideal Cone shape varies based upon the speed of the rocket
 - If subsonic a more domed shape is preferred.
 - If supersonic a more coned shape is preferred.

•For our expected velocity, a cone with $x^{\frac{1}{2}}$ profile would be desired



Figure 5: Drag characteristics of various nose shapes in the transonic-to-low Mach regions ^[6]

Nose Cone Shape Optimization $-X^{\frac{1}{2}}$

•To create this profile, a plot is made by graphing the following equation and revolving it around the x axis.

$$Y = Radius of tube \left(\frac{x}{Lengt \ of nose \ cone}\right)^{0.5}$$



Figure 6: Nose Profile Optimization Curve ^[7]

Nose Cone Shape Optimization — Length

•To determine appropriate length of the nose cone the fineness ratio must be considered.

 $Fineness = \frac{Lengt}{Base \ Diameter}$

•As Velocity increases, the fineness ratio of the nose cone affects wave drag

•Higher Fineness ratios cause more surface friction drag.



Figure 6: Nose Profile Optimization Curve ^[7]

Material Selection for Rocket Body

CARBON FIBER

- High Strength
- High Price
- Rough Surface
- Light Weight

FIBERGLASS

- Medium Strength
- Low Price
- Rough Surface
- Light Weight



Figure 7: Carbon Fiber^[8]

Figure 9: Fiberglass ^[10]

PLASTIC

- Low Strength
- Low Price
- Smooth Surface
- Light Weight

ALUMINUM

- High Strength
- High Price
- Smooth Surface
- High Weight



Figure 8: Plastic ^[9]



Figure 10: Aluminum [11]

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Stabilization

FIXED FINS

- Simple
- Cheap
- 3 fins
- Light Weight

STEERABLE FINS

- Complex
- 3 fins
- Requires actuators
- Heavier than fixed

THRUST VECTORING

- Complex
- Expensive
- Long Development
- Reduced drag
- Accurate flight trajectory

SPIN STABILIZATION

- 3 angled fins
- cheap
- Could affect payload
- Could affect recovery

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Recovery STEERABLE PARAFOIL **REEFED PARACHUTE** DUAL DEPLOYMENT Apogee Apogee Apogee Drogue Drogue parachute Main parachute parachute deployment opens partially deployment Ripcord unreefs main Parafoil is Main Parachute parachute released deployment Landing Landing Landing Figure 12: Reefed Parachute [13] Figure 11: Dual Deployment [12] Figure 13: Steerable Parafoil [14]

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Recovery Concept Selection

A Pugh Selection Matrix is used to determine the optimal r Primary Recovery System	ecovery system:		ual Deployment	eefed Parachute	teerable Parafoil
Reefed Parachute	Engineering Characteristics	Weight	Δ	R	S
	Mass	3	S	+	11 00
Secondary Recovery System	Reliability	3	S	-	-
	Cost	2	S	S	-
 Dual Deployment 	Range Requirement	3	S	S	+
	Complexity	1	S	+	<u> </u>
	Totals		0	1	-6

Figure 14: Recovery System Pugh Selection Matrix

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Recovery System Deployment



Avionics

Flight Computer	• Altimeter	Batteries
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Flight Computer				
Criterion (Weight)	Ease of Use (3)	Cost (5)	Versatility (4)	Total
Purchased	5	3	2	38
Self-Programmed	3	5	5	54

Altimeter Decision Matrix							
Criterion (Weight)	Weight (1)	Ease of Use (4)	Accuracy (5)	Cost (2)	Total		
Barometric Sensor	5	5	3	5	50		
Accelerometer	4	4	2	3	36		
Combined	3	3	5	2	44		

Battery Decision Matrix						
Criterion (Weight)	Weight (4)	Dimensions (3)	Charge/Discharge (2)	Safety (5)	Cost (2)	Total
Lithium Polymer	5	5	5	3	4	68
Nickel-Metal Hydride	4	4	3	5	4	67
Nickel-Cadmium	4	4	4	4	5	66

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Morphological Chart

Component	Option 1	Option 2	Option 3	Option 4
Nose Cone	$x^{\frac{1}{2}}$ Profile			
Material	Carbon Fiber	Fiberglass	Plastic	Aluminum
Stabilization	Fixed Fins	Steerable Fins	Thrust Vectoring	Spin Stabilization
Recovery System	Dual Deployment	Reefed Deployment	Steerable Parafoil	
Recovery Deployment	Compressed CO ₂	Black Powder		
Flight Computer	Purchased	Self-made		
Altimeter	Barometer	Accelerometer		

Risk Assessment & Safety



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Gantt Chart

ID	Task Name	2016 October 2016 November 2016 December 2019 9 12 15 18 21 24 27 30 3 6 9 12 15 18 21 24 27 30 2 5 8 11 14 17 20 23 26 29 2 5 8
1	<research and="" concept="" generation=""></research>	
2	Background Research	
3	Brainstorming	
4	Concept Generation	
5	<detailed analysis="" design=""></detailed>	1
6	Initial Concept Selection	
7	Raw Material Selection	
8	Initial CAD Model	
9	Develop Flight Controler	
10	Develop Recovery System	
11	Initial Payload Selection	
12	Payload Integration	
13	Body and Fin Analysis	
14	Tenative Final Design	
15	FMEA and H-FMEA	
16	Final Design	
17	Bill of Materials	
18	Cost Analysis	
19	<design implementation=""></design>	
20	Placing Orders	

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Thank you! Questions?

