

# MARSRAM

## Team 22: NASA Robotic Mining Competition

### Team Members

Jonathan MacDonald

Zachary Moore

Andrew Svendsen

Alexandria Woodruff

### Advisor

Dr. Jonathan Clark

### Sponsor

Florida Space Grant Consortium

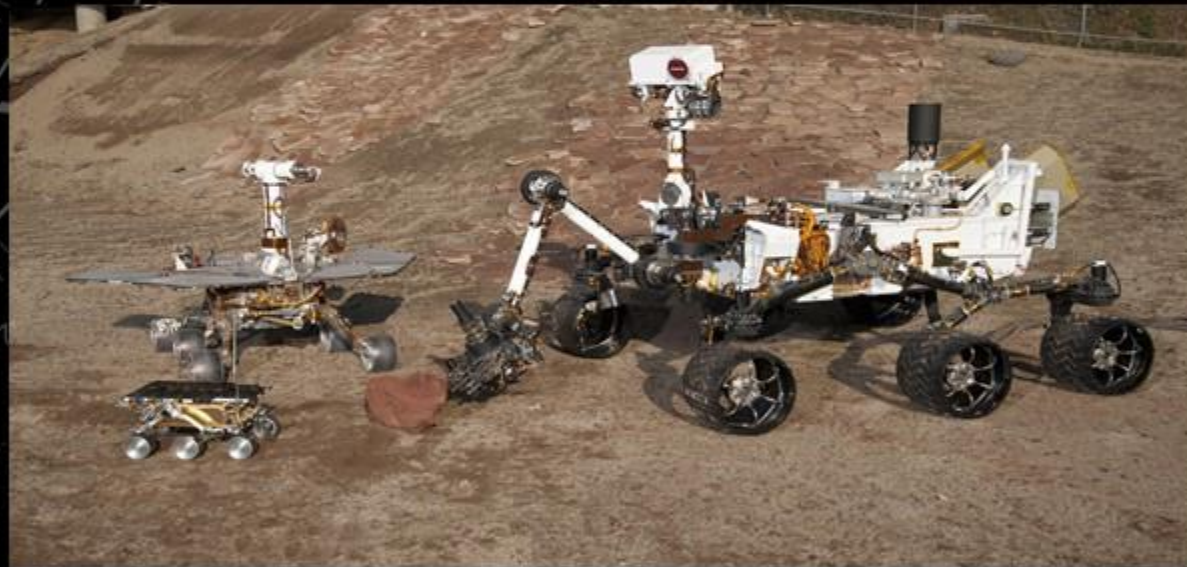
# PROJECT SCOPE

1. On-Site Mining
  - Design/Build a mining robot
2. Systems Engineering Paper
  - Discuss the design philosophy
3. STEM Outreach Report
  - Detail the K-12 outreach events
4. Slide Presentation & Demonstration
5. Social Media and Public Engagement



# ON-SITE MINING

“Design and build a mining robot that can traverse the chaotic Martian terrain and excavate the basaltic regolith simulant and ice simulant and return them for deposit into a collector bin.”



# WHY MARS?

## Why should we go to Mars?

### Past, Present, Future

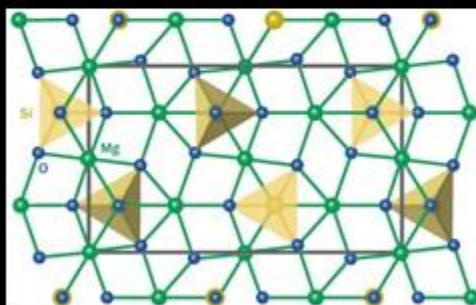
1. Mars' formation and evolution
  - Climate
  - Surface Features
  - Chemistry
2. Are we alone?
  - Previous mission data suggests Mars was habitable



## Why should we mine regolith?

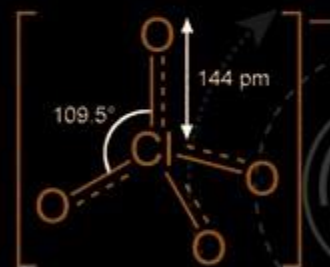
### Olivine ( $Mg_2Fe_2SiO_4$ )

1. Build Structures
  - Bunks, Greenhouses, Research Labs
2. Rocket Fuel for missions FROM Mars
  - Methane



### Perchlorates ( $ClO_4^-$ )

1. In-Situ Resources to support human life
  - Oxygen
2. Rocket Fuel for missions FROM Mars
  - Oxygen, Chlorine



# HOUSE OF QUALITY

## Engineering Characteristics:

1. Speed

2. Size

3. Controls

4. Cost

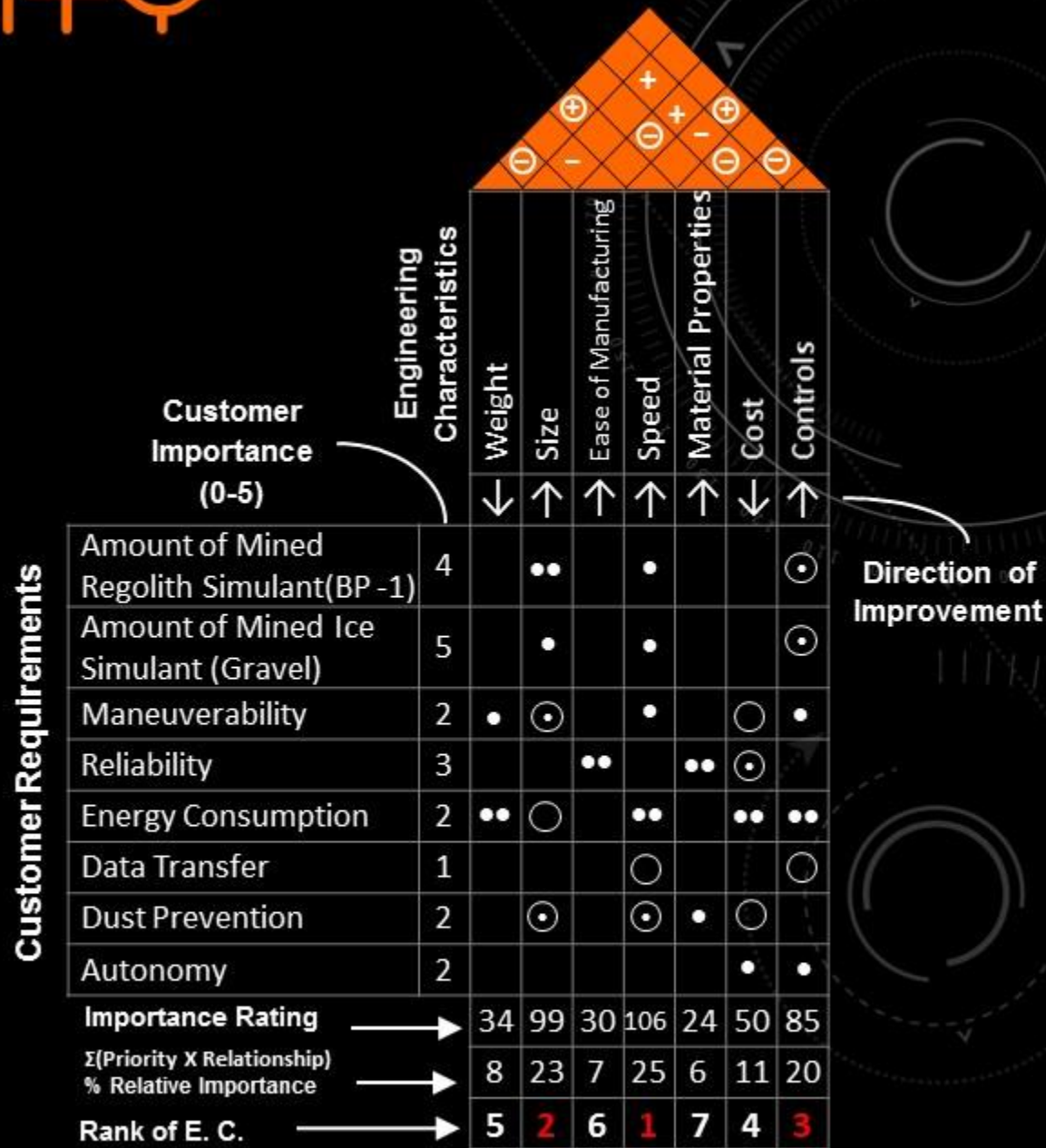
5. Weight

6. Ease of Manufacturing

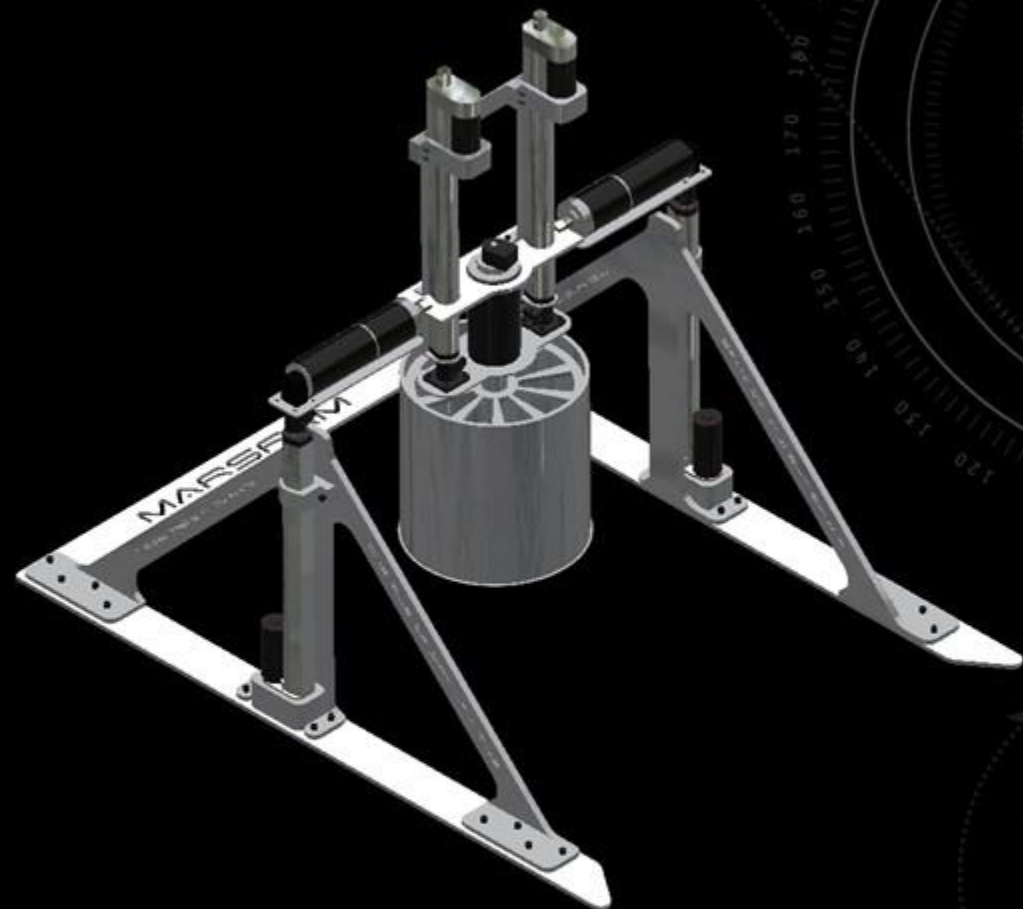
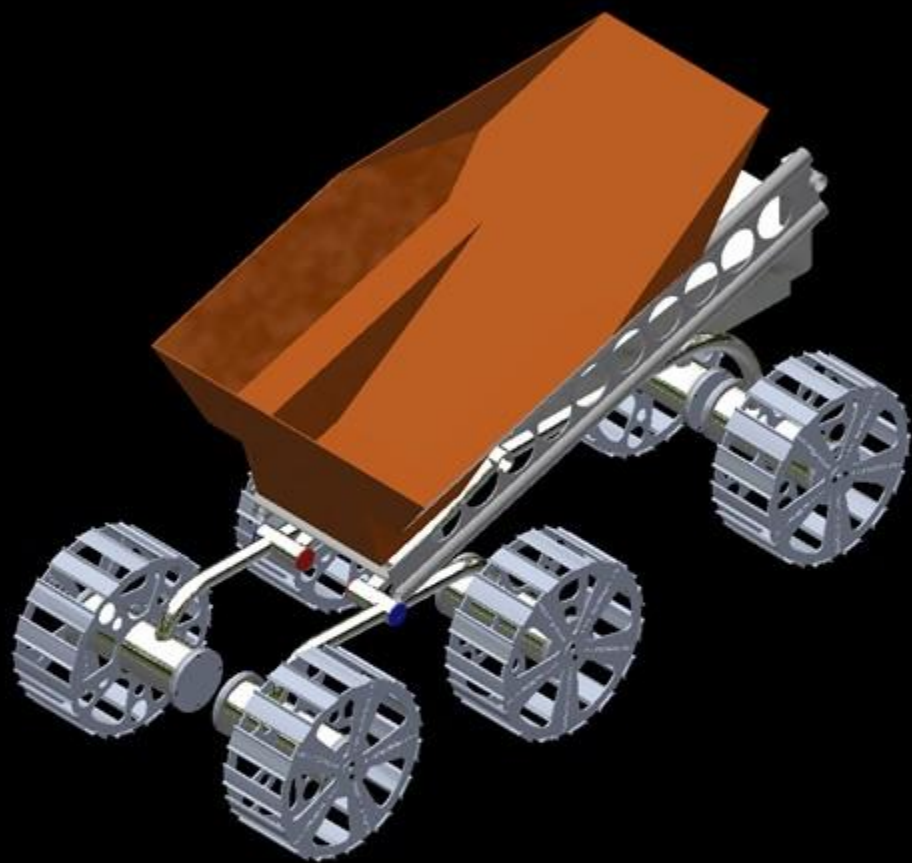
7. Material Properties

Correlations:  
 ⊕ Strong Positive  
 + Positive  
 ⊖ Strong Negative  
 - Negative

Relationships:  
 ●● Strongest= 10  
 ● Strong= 7  
 ⊙ Fair= 4  
 ○ Weak= 1



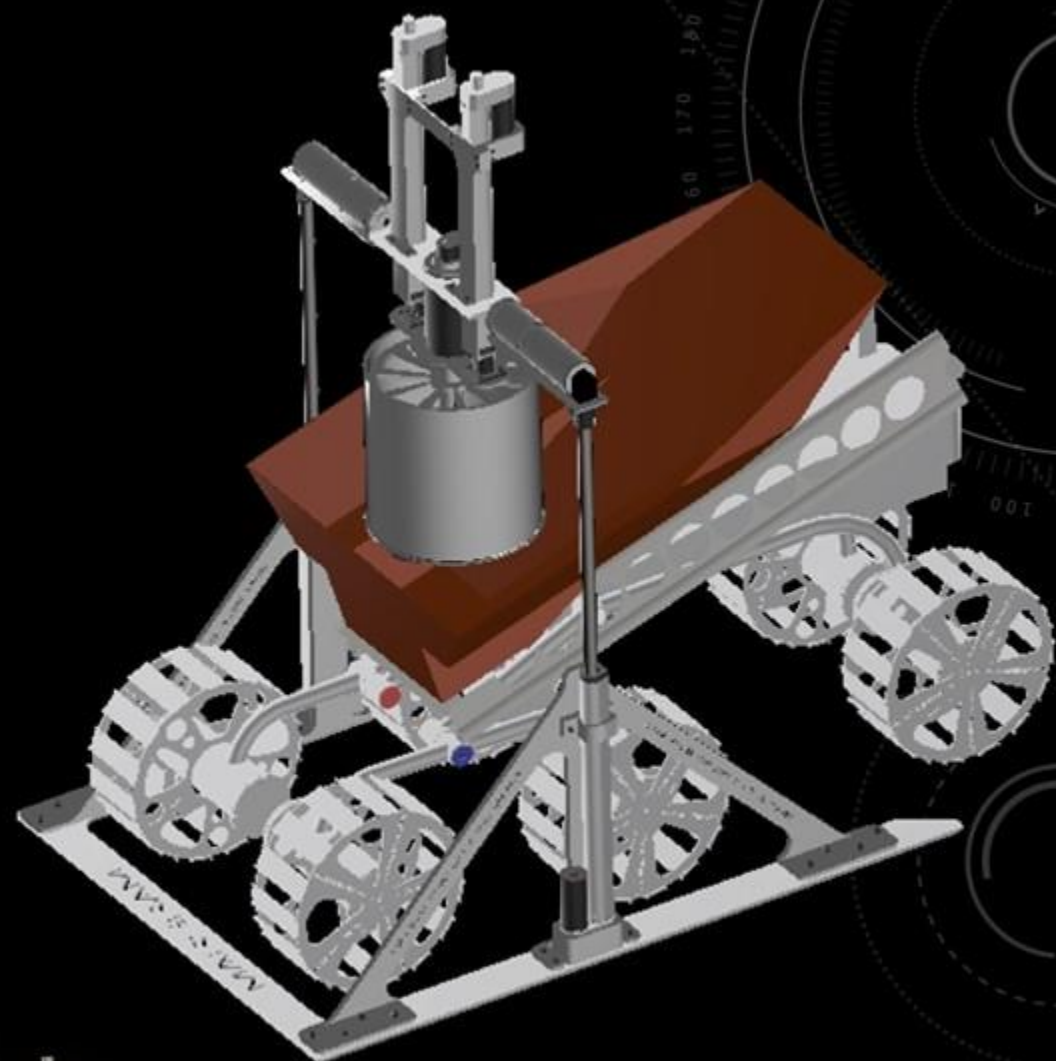
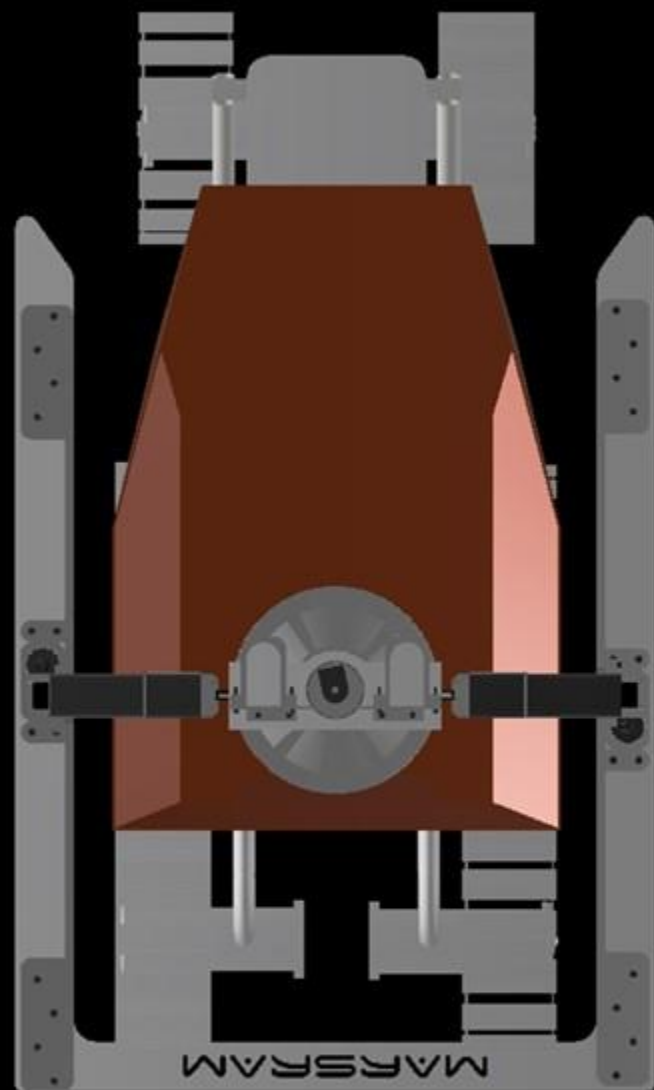
# CHASSIS & MINING SYSTEMS



- Two Independent Designs
- Engineering Characteristics



# CHASSIS & MINING SYSTEMS



# CHASSIS SCRAPS



**SCRAP 1.0**



**SCRAP 1.1**



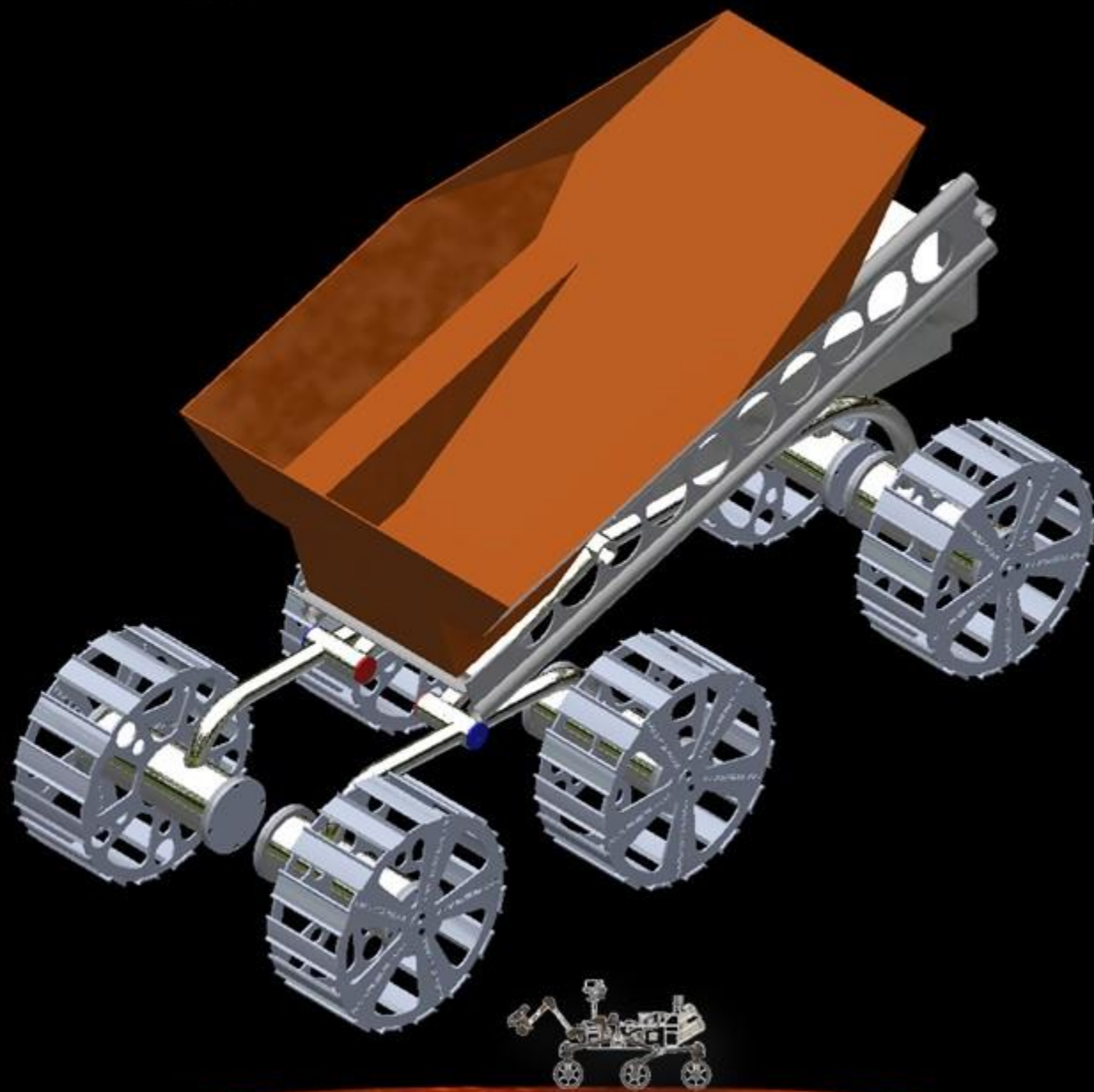
Scaled  
Configuration  
Regolith  
Acquisition  
Prototype



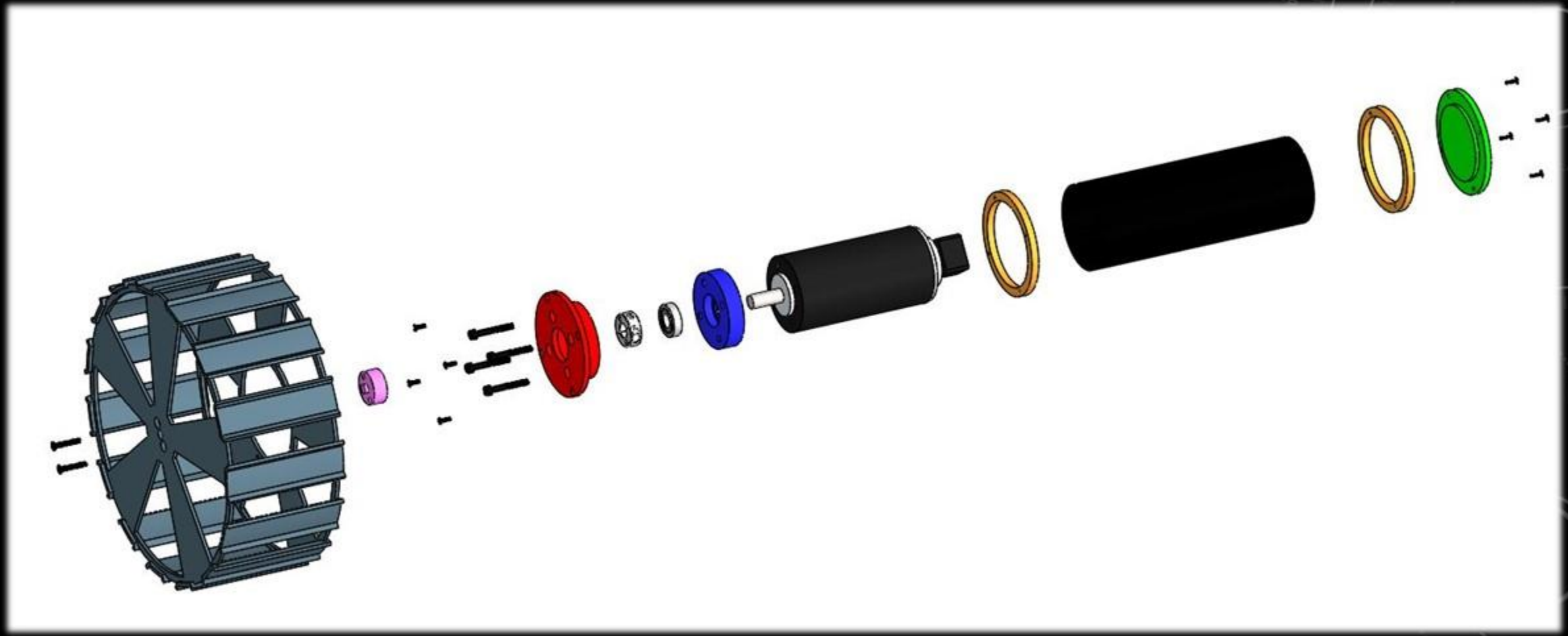


# ROCKER-BOGIE CHASSIS

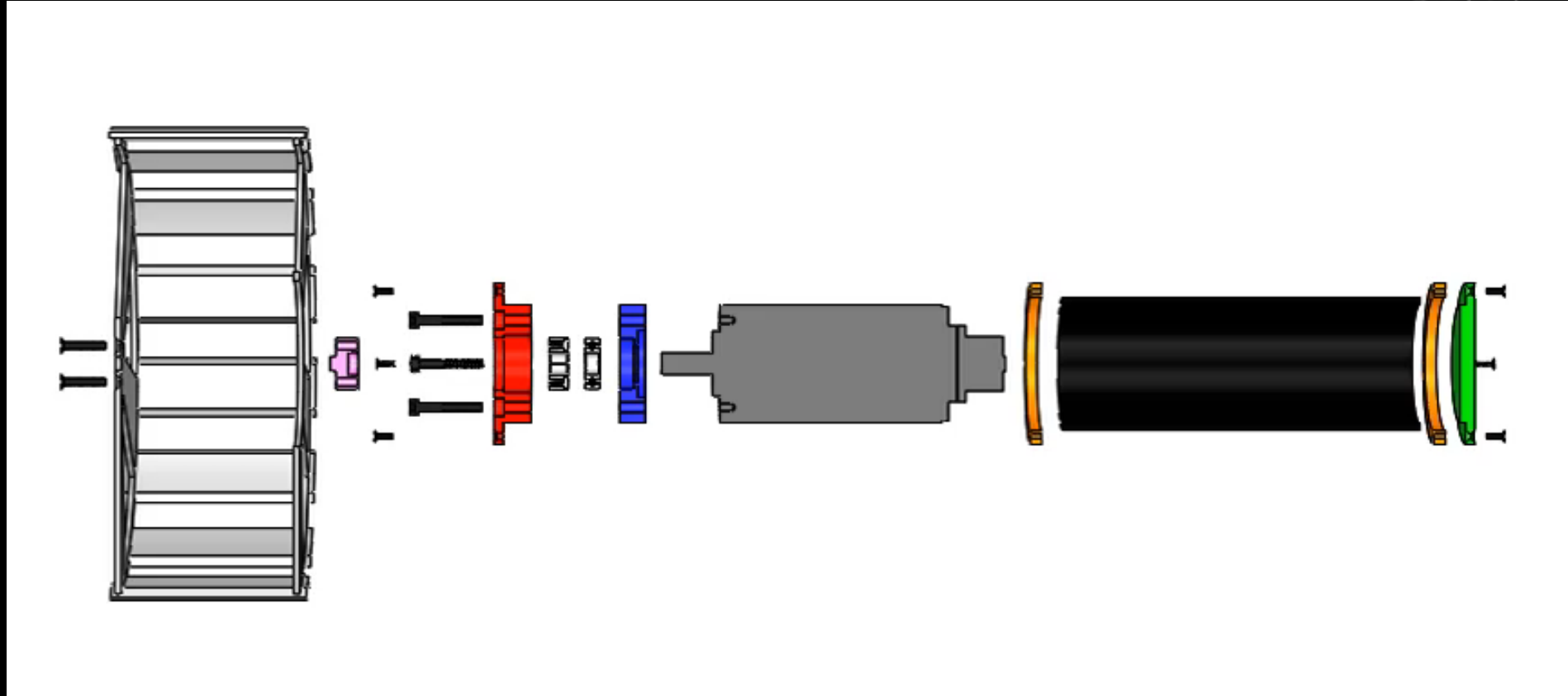
Height: 26 in  
Width: 20 in  
Weight: 82 lb



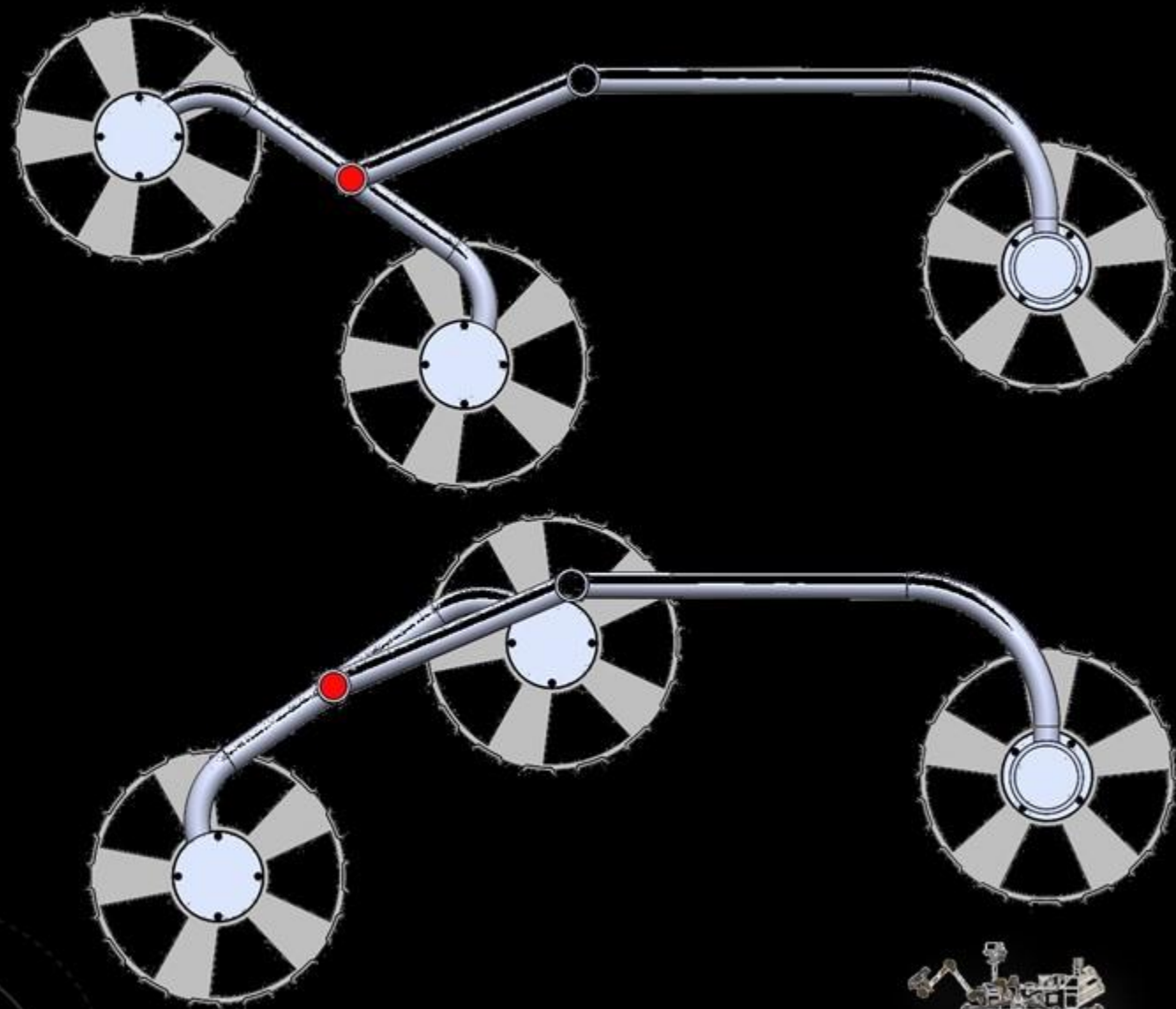
# WHEEL MOTOR HOUSING



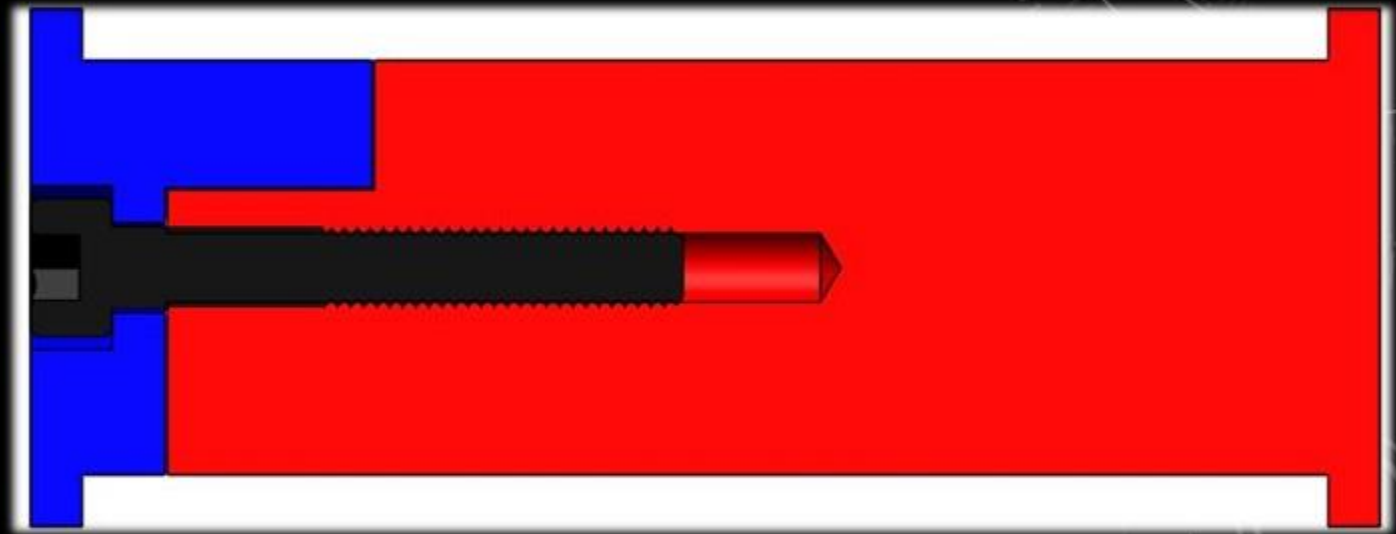
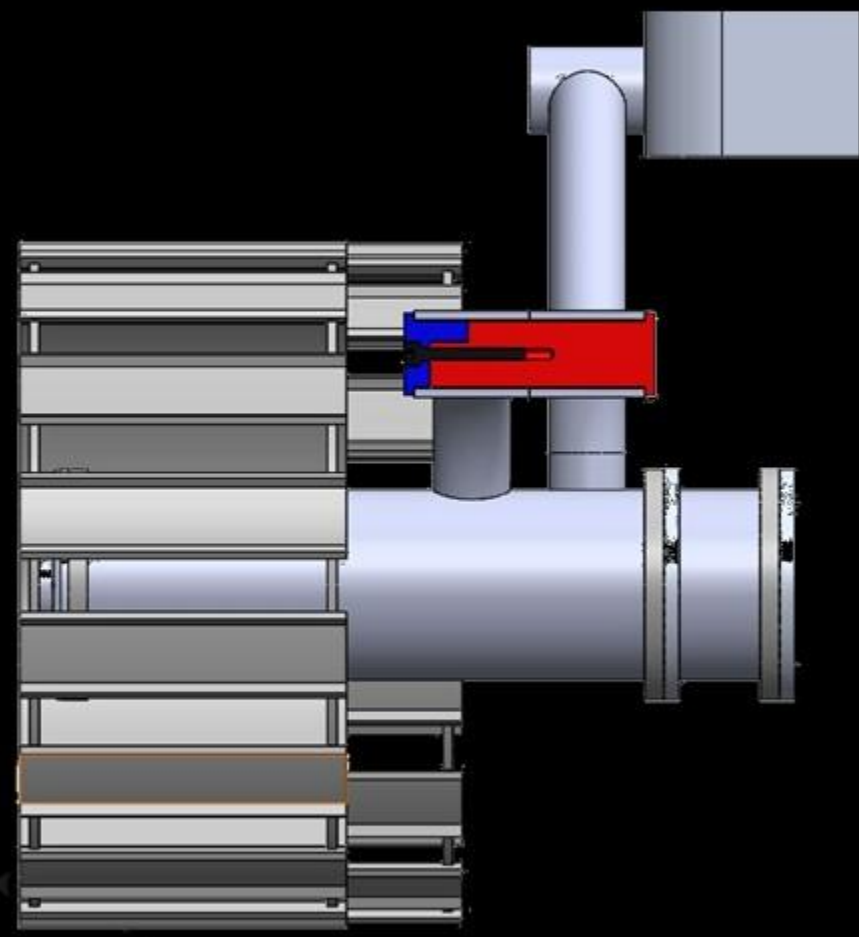
# WHEEL MOTOR HOUSING



# BOGIE ROTATION LIMIT

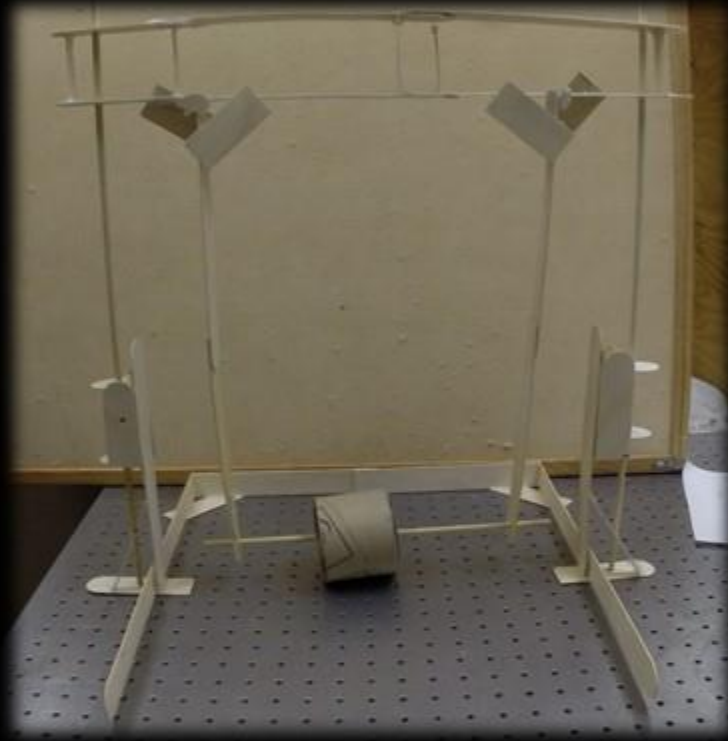


# BOGIE ROTATION LIMIT



# MINING SCRAP ITERATIONS

“Scaled-Configuration Regolith Acquisition Prototype”



SCRAP 2.0



SCRAP 2.1

# MINING SCRAP ITERATIONS

"Scaled-Configuration Regolith Acquisition Prototype"



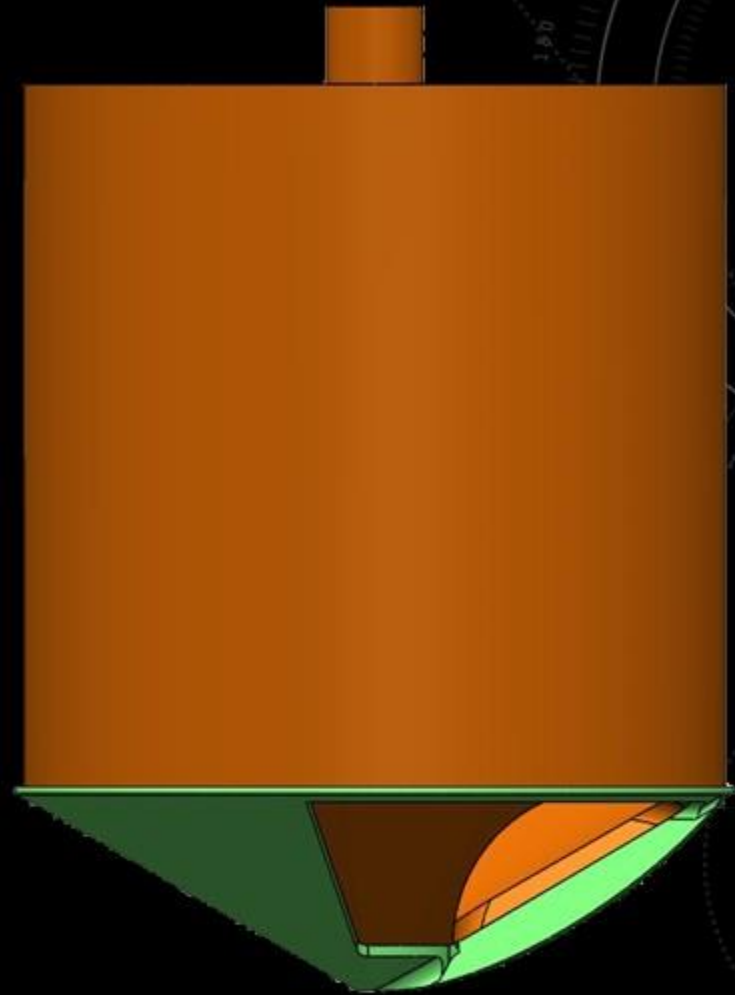
Evolution of the Mining Drill



# MINING DRILL



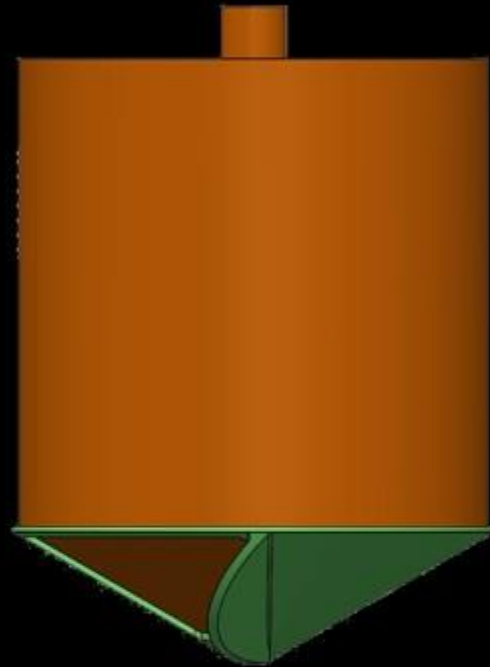
Rock Drilling Bucket





# MINING DRILL

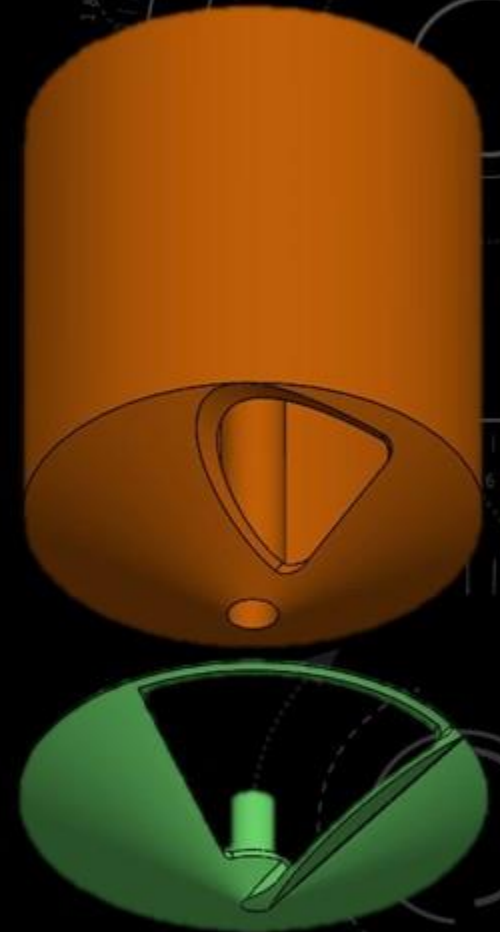
Outer Diameter: 8 in  
Height: 12 in  
Volume: 529 in<sup>3</sup>  
Filled Mass: 26 lb



CLOSED



OPENED

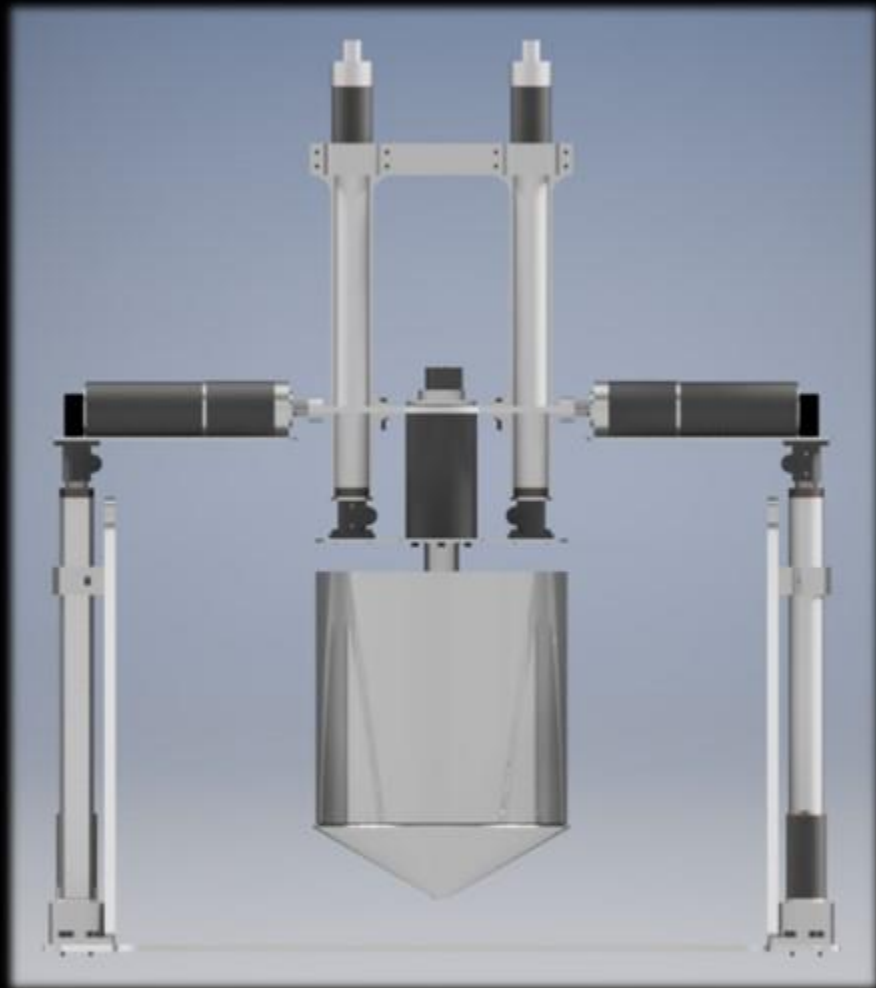


# MINING APPARATUS

Height: 28 in  
Width: 28 in  
Weight: 58 lb



# MINING DESIGN



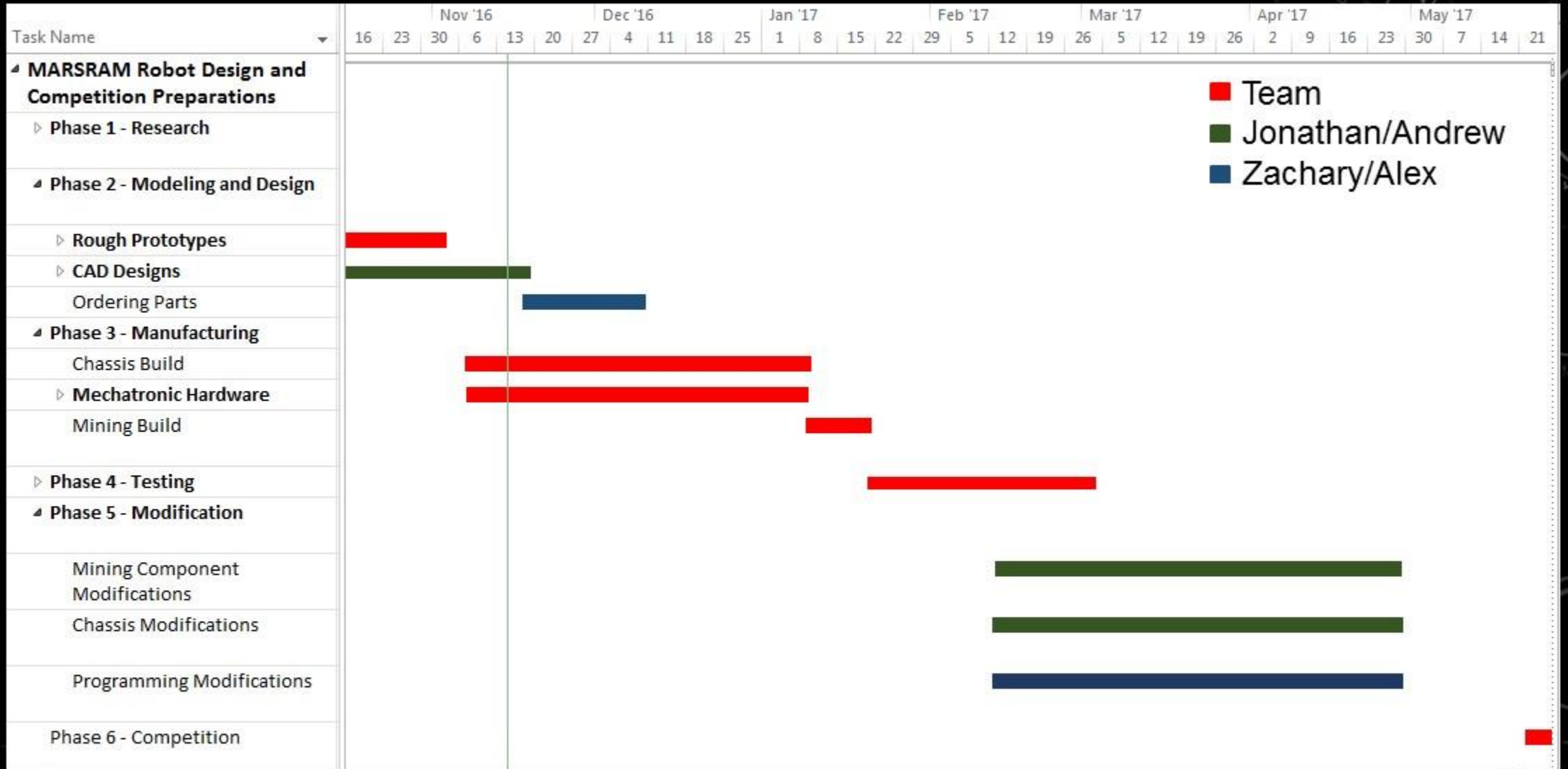


# BUDGET ALLOCATION

Budget Provided: \$2,000

Items	Projected Costs (\$)
Raw Materials	535.00
Hardware	677.82
Total	1212.82

# FUTURE PLANS



# REFERENCES

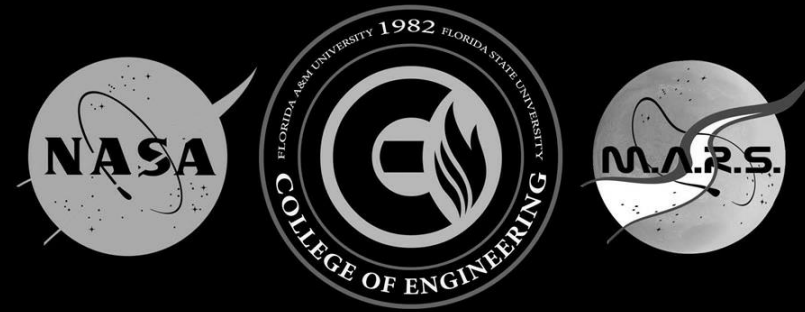
- Ullrich, Franziska, Ali Hayder Goktogan, and Salah SUkkarieh. "Design Optimization of a Mars Rover's Rocker-Bogie Mechanism Using Genetic Algorithms." *Design Optimization of a Mars Rover's Rocker-Bogie Mechanism Using Genetic Algorithms* (2006): n. pag. Print.
- NASA. "Rules and Rubrics." (n.d.): n. pag. *NASA Robotic Mining Competition 2017*. Web. <[http://www.nasa.gov/sites/default/files/atoms/files/00\\_rmc2017\\_rulesrubrics.pdf](http://www.nasa.gov/sites/default/files/atoms/files/00_rmc2017_rulesrubrics.pdf)>.
- NASA. "Overview & Introduction." *NASA Robotic Mining Competition* (n.d.): n. pag. Web. <[http://www.nasa.gov/sites/default/files/atoms/files/01\\_rmc2017\\_overviewintro.pdf](http://www.nasa.gov/sites/default/files/atoms/files/01_rmc2017_overviewintro.pdf)>.
- NASA. "The Competition Events." *NASA Robotic Mining Competition 2017* (n.d.): n. pag. Web. <[http://www.nasa.gov/sites/default/files/atoms/files/03\\_rmc2017\\_competitionevents\\_rev02\\_2c\\_1004\\_2016.pdf](http://www.nasa.gov/sites/default/files/atoms/files/03_rmc2017_competitionevents_rev02_2c_1004_2016.pdf)>.

# MARSRAM



MARSRAM

MINING TOOLING



MARSRAM



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# BUDGET ALLOCATION RAW MATERIALS

Budget Provided: \$2,000

Raw Materials	Maximum Estimated Costs (\$)
Aluminum Sheet 12"x12"- ¼"Thick	40
Aluminum Sheets 4'x8' - 1/8" Thick	150
Aluminum Tubing 1"OD -1/16" Wall	100
Aluminum Pipe 1" SCH40	30
Aluminum Pipe 2.5" SCH40	100
Aluminum Round Rod 1"	15
Aluminum Tubing 8"OD	100
TOTAL	535

# BUDGET ALLOCATION

## MOTOR CONTROL

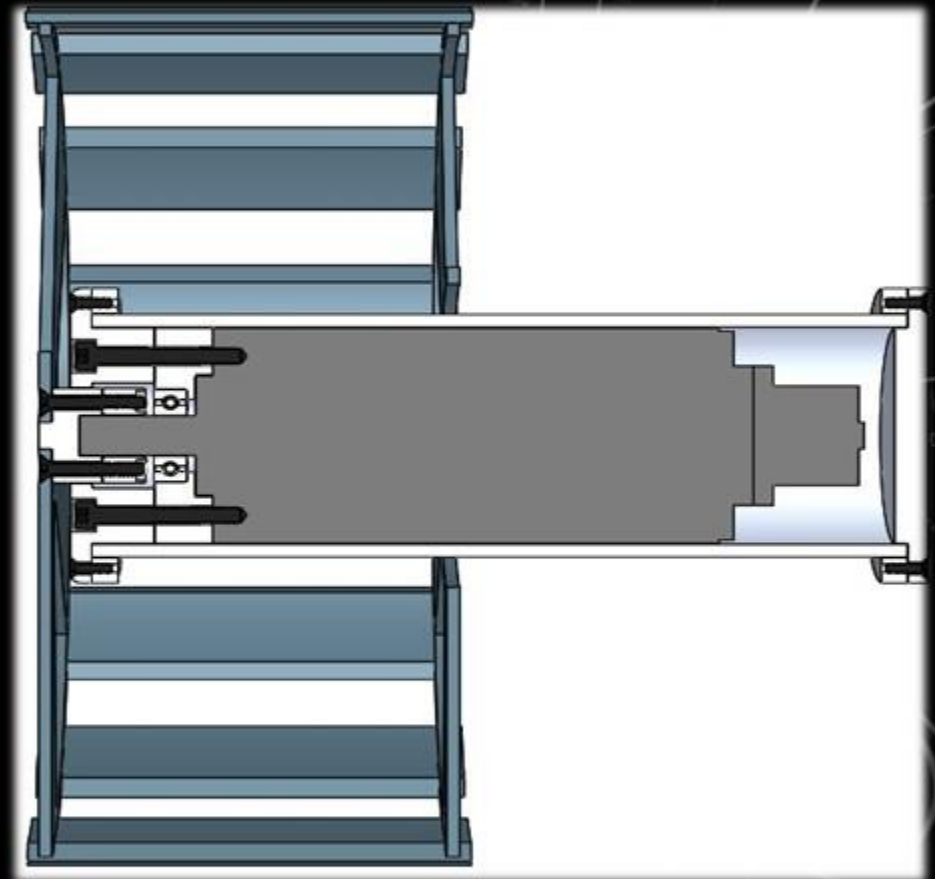
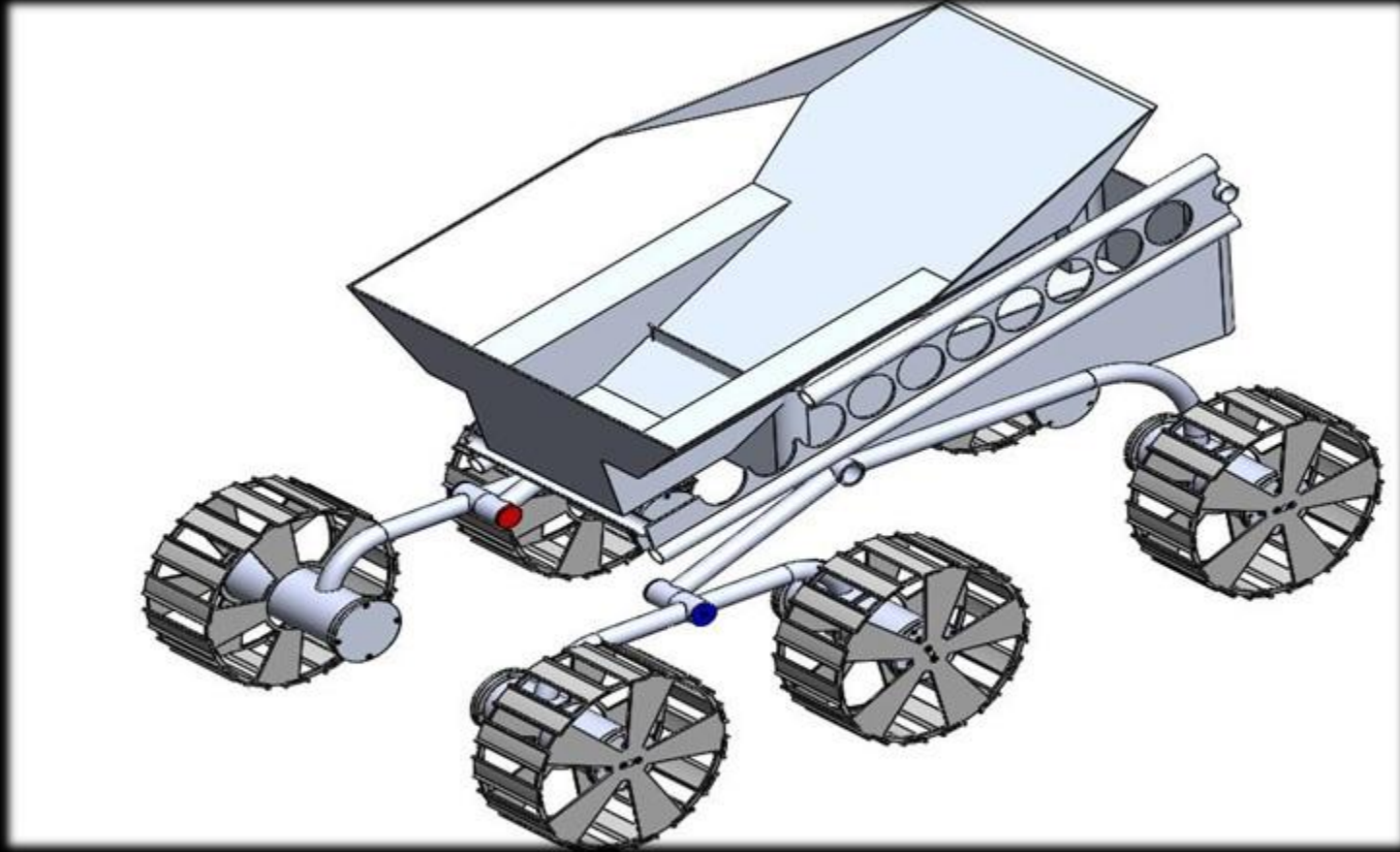
Budget Provided: \$2,000

Item	Quantity	Unit Price(\$)	Estimated Costs (\$)
12mm Shaft Collar-Face Mount Tap	6	19.60	117.60
12mm Double Shielded Press Fit Bearing	6	7.54	44.70
Linear Actuators 16" Stroke – 250lbf Cap.	4	73.00	292.00
18-8 SS FHSC 6-32X3/8" (100 pack)	1	4.30	4.30
18-8 SS SHC M5X0.8mm 35mm Long (25 pack)	1	5.47	5.47
18-8 SS FHSC M4X0.7mm 25mm Long (100 pack)	1	13.75	13.75
Maxon Motor Controller	4	50.00	200
Total			677.82

# APPENDIX A



# ROCKER-BOGIE CHASSIS CAD



COMPETITION

SUMMARY

CHASSIS

MINING

FUTURE

# DONATED MATERIALS

