

Design of a Compact Pressure Sensor for Multi-Layer Insulation in a Vacuum



Team 15

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Presentation Overview

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Project Scope

- The goal of this project is to design and implement a compact pressure sensor that is easily embedded between layers of Multi-Layer Insulation (MLI).
 - ❖ Rapid Response Time
 - ❖ The ability to measure a large pressure range
 - ❖ Noninvasive to the MLI
- This interstitial pressure is measured to quantify the heat transfer through the system
- Heat transfer is critical to cryogenic storage and applications in space

Project Objectives

- Develop a pressure sensor with minimal parts
- Minimize the wiring and power consumption of the device
- Minimize the heat produced by the sensor

Project Constraints

- Pressure Sensor
 - ❖ Be able to measure a pressure as low as 10^{-2} Pa
 - ❖ Have a minimum response rate of 1 sample per second
- Multi-Layer Insulation
 - ❖ Sensor dimensions shouldn't exceed interlayer spacing
 - ❖ 12 layers is roughly 5 mm
- Working environment
 - ❖ Temperature conditions range from 293 K to 77 K
 - ❖ Out gassing
 - ❖ Vacuum

House of Quality

Table 1 - House of Quality for Pressure Sensor Design

Engineering Characteristics Customer Requirements	Customer Importance	Materials	Power Consumption	Geometry	Cost
Minimal Invasiveness	5	3	6	9	
Accuracy	5		6		6
Minimal Heat Produced	4	3	6		
Reading Range	4				6
Reading Speed	3		6		6
Total Weight		27	102	45	72

Capacitor Design

1. Palladium-gold sputtered capacitance tracts
2. Silicone diaphragm
 - 125 μm diameter
 - 0.25 μm thickness
3. Capacitor base shell
 - Germanium doped Silica base with cavity hollowed by acidic etching

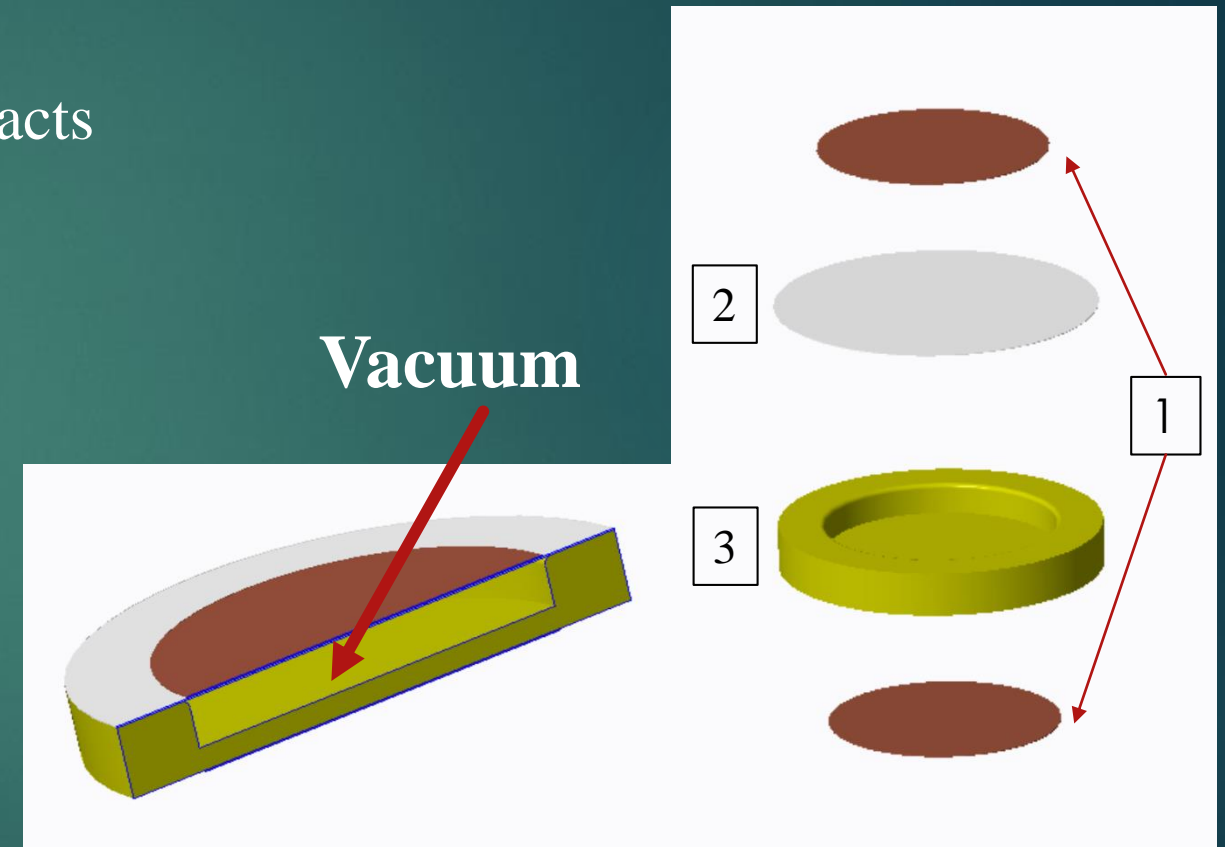


Figure 1: Cross section view of capacitor (left), and exploded view (right)

Multi-Stage Capacitor Design

1: Capacitor top diaphragm:

- High sensitivity – reads low pressures
- 165 μm OD, 125 μm ID diaphragm
- 20 nm thickness, 27 μm deflection at 10 Pa
- Nano-metallic coating to create capacitor plate (sputtering)

2: Silica spacer

3: Intermediate diaphragm:

- Medium to low sensitivity – reads medium to high pressure ranges.
- 50 nm thickness, 28 μm deflection at 150 kPa

4: Silica Base plate

5: Capacitor bottom plate:

- Rigid metallic plate

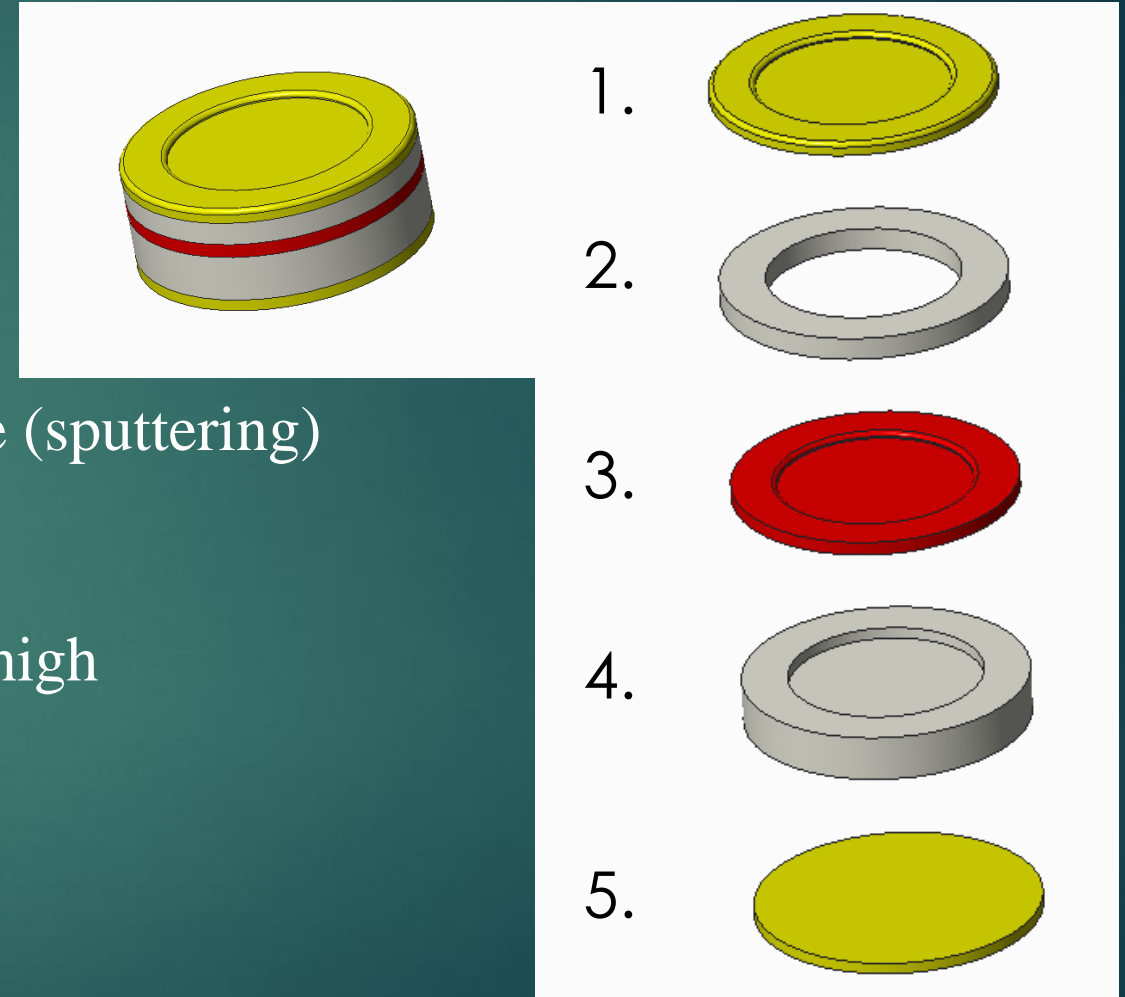


Figure 2: Displays the exploded view of the multi stage capacitor

Multi-Stage Capacitor Design

- Cavities formed in the silica base by parabolic germanium doped etching
- Capacitor assembled in a vacuum
- Parts either fused together, or set with a UV-reactive polymer

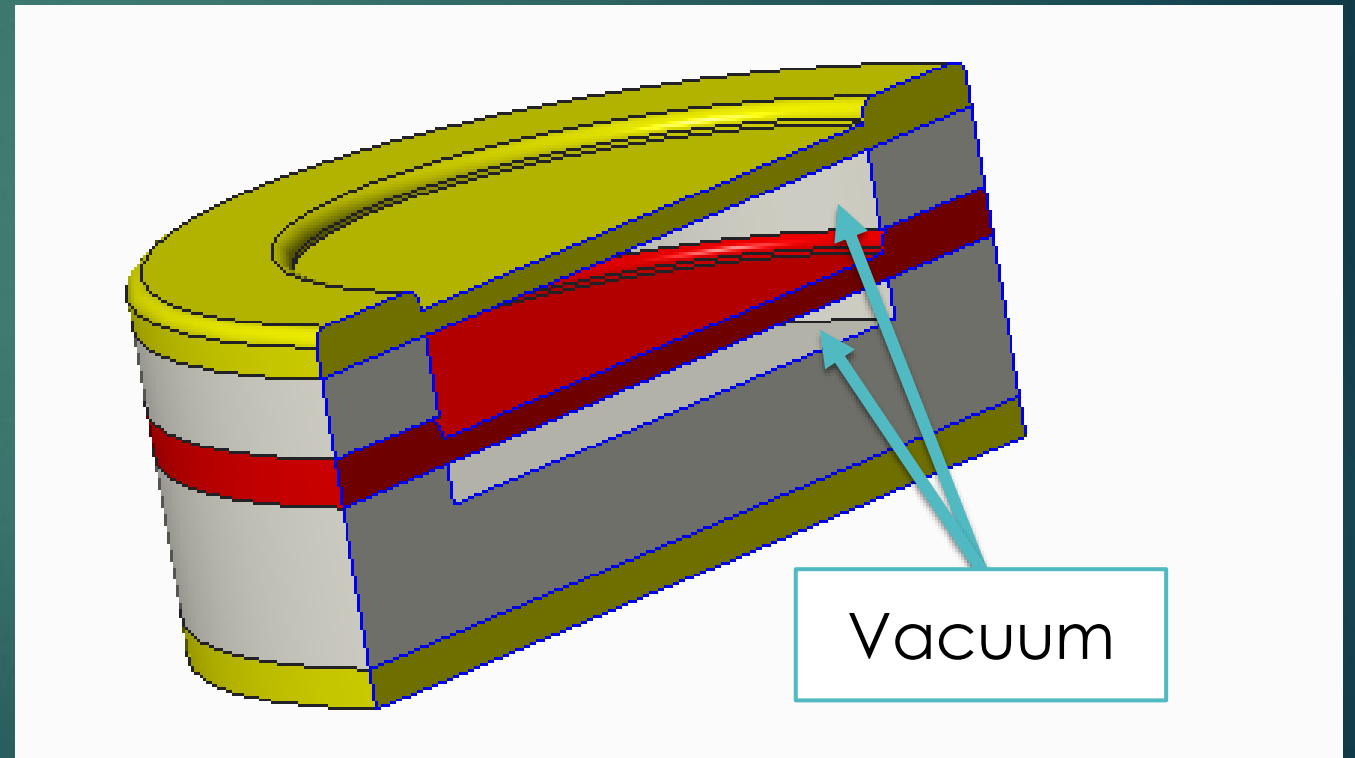


Figure 3: Multi stage capacitor cross sectional view

Fiber Optic Design

- 1: Silica diaphragm
 - ❖ 125 μm OD
 - ❖ 85 μm ID diaphragm
- 2: Silica core
- 3: Lead-in optical fiber
 - ❖ Multimodal or single modal

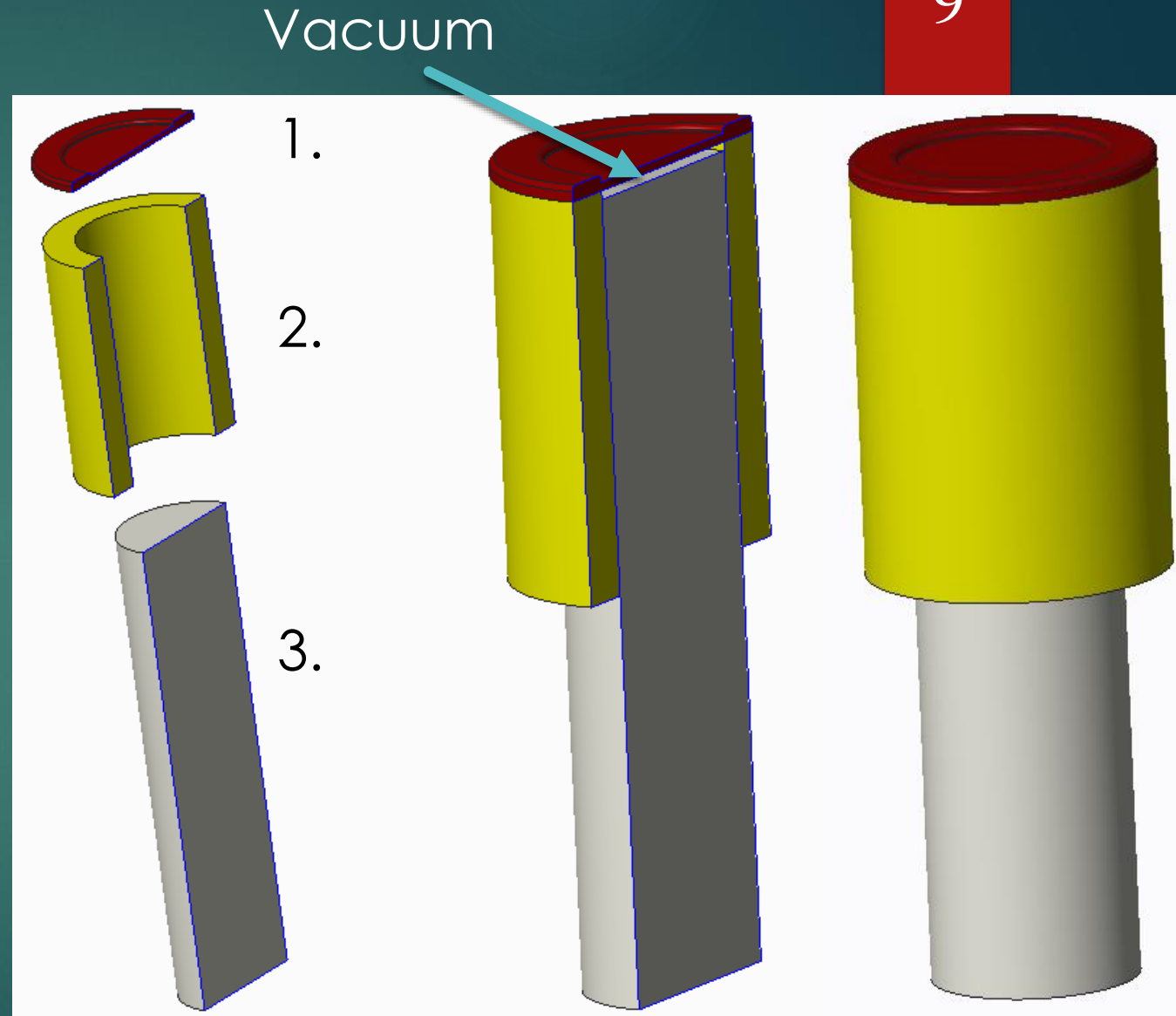


Figure 5 Cross section view and fully assembled view of Fiber optics sensor

Fiber Optics

- Observes change in phase, polarization, transmit time, or wavelength to measure pressure
- Pros
 - ❖ Good in high vibrational, wet, noisy, corrosive, and extreme heat environments
 - ❖ Immune to electromagnetic interference
 - ❖ Ability to measure a large range of pressures
 - ❖ High Sensitivity and Bandwidth
 - ❖ Size (125 micrometers)
- Cons
 - ❖ Relatively difficult design
 - ❖ Cost
 - ❖ Assembly requires special equipment



Figure 4 Displays the size of a fiber optics pressure sensor

Decision Matrix

Table 2 - Pugh Decision Matrix for pressure sensor concepts

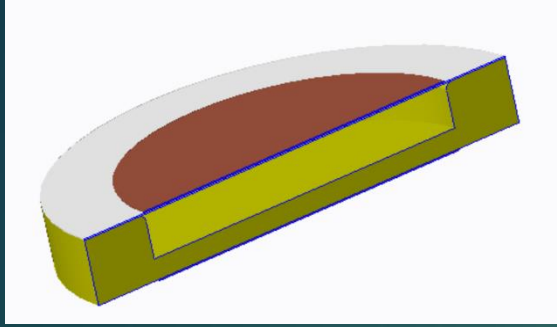
	Capacitor	Fiber Optics	Multi-Stage Capacitor
Accuracy	0	1	0
Minimal Invasiveness	0	0	0
Heat Production	0	-1	0
Reading Range	0	2	1
Reading Speed	0	0	0
Total	0	2	1

naNO

- Creating the nano-capacitance prototype falls outside of the time restraint and budget
- To progress with a prototype and testing, scaling must occur
- Wish to scale from 125 μm diameter diaphragm to a more pragmatic 25 mm (200x)
 - ❖ Enables the experimentation of capacitance pressure sensors in the previously shown design
 - ❖ Easier implementation with ongoing sensor research directed at temperature detection



Design Calculations



Critical minimum thickness of diaphragm at given pressure (P):

$$h = \sqrt{\frac{3\pi r^2 * P}{4\pi\sigma_y}}$$

σ_y = yield stress

Maximum deflection at given Pressure (P) and thickness(h):

$$w_{max} = -\frac{3\pi r^2 P ((1/\mu)^2 - 1) r^2}{16\pi E h (1/\mu)^2}$$

Critical maximum body pressure at given shell thickness:

$$p = \frac{0.855}{(1 - \mu^2)^{\frac{3}{4}}} * \frac{E\sqrt{\gamma}}{\left(\frac{r}{t}\right)^{\frac{5}{2}} * \frac{l}{r}}$$

$$\gamma = 1 - 0.901(1 - e^{-\phi})$$

$$\phi = \frac{1}{16} \sqrt{\frac{r}{t}}$$

μ = Poisson's Ratio

E = Young's Modulus

r = diaphragm radius

l = sensor length

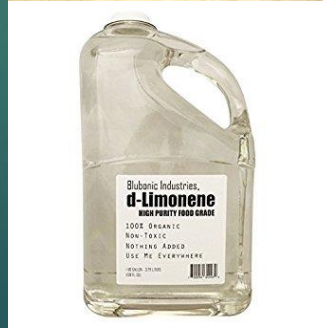
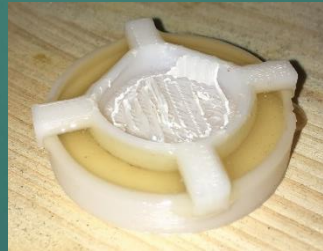
t = shell thickness

Max Pressure during liftoff \approx 150 kPa

	Diaphragm Diameter	Min. Thickness (@150 kPa)	Design Thickness	Safety Factor	Critical Diaphragm Pressure	Maximum Deflection (@150kPa)	Shell Thickness	Critical Body Pressure
Prototype	25 mm	0.05 mm	0.10 mm	2.00	600 kPa	5.60 mm	5 mm	20 MPa
Actual Sensor	125 μ m	0.25 μ m	0.50 μ m	2.00	600 kPa	28.0 μ m	20 μ m	400 MPa

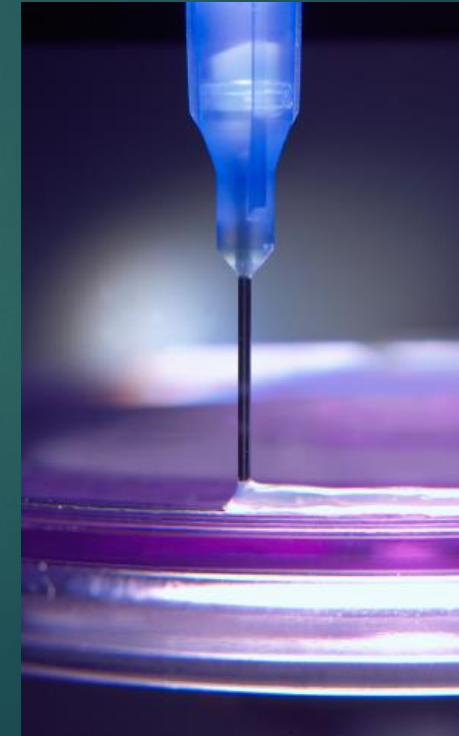
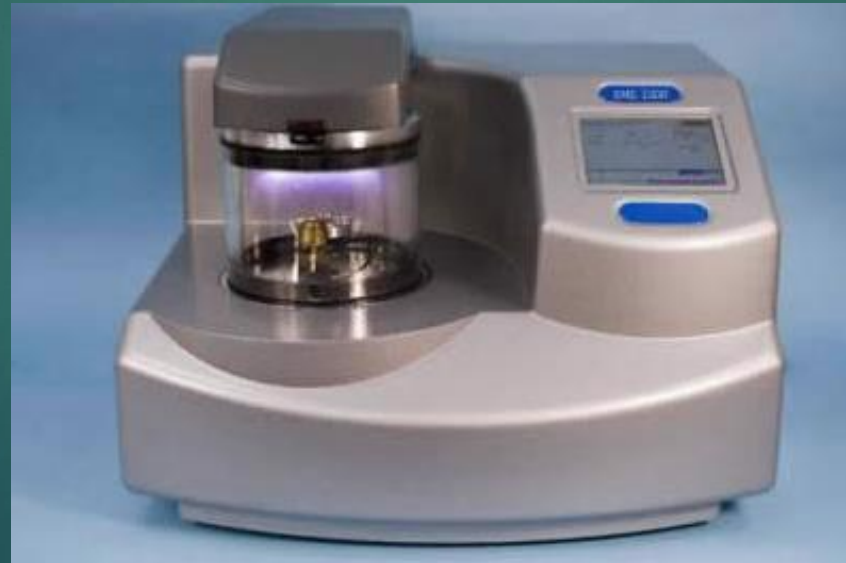
Prototype Production

- Silicone diaphragm acquired (0.1mm and 0.2 mm)
- Epoxy capacitor base finished using HIPS dissolvable filament



Prototype Production

- Use SEM lab to sputtering tracts onto silicone
- UV polymer to adhere the diaphragm



Experimental Testing

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- Capacitance is a function of geometry (area and distance apart)
- Each capacitor has a resonant frequency that can be determined using a network analyzer and oscilloscope
- Network analyzer creates electromagnetic fields, which will cause voltage to oscillate in the capacitor
- Voltage read at the capacitor positive will decrease when resonance has been achieved at the dictated frequency
- Resonance becomes a function of deflection, thus a function of pressure

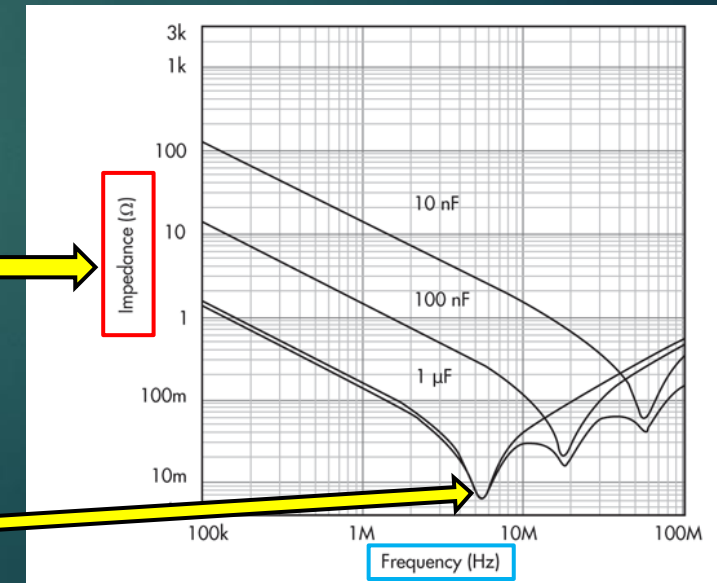
$$V = I * R$$

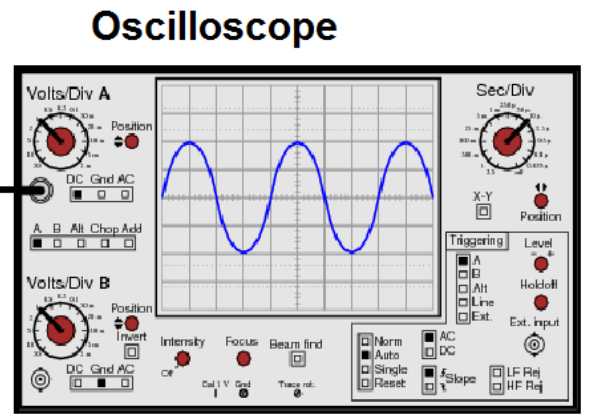
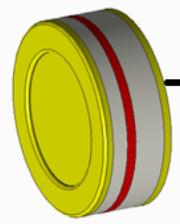
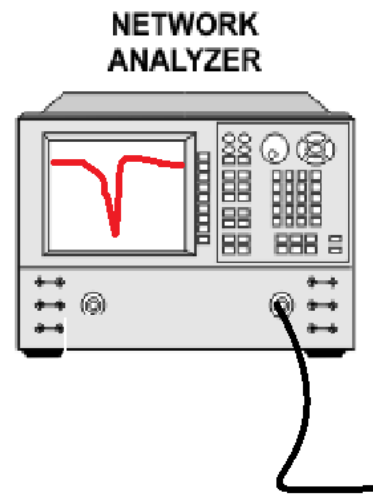
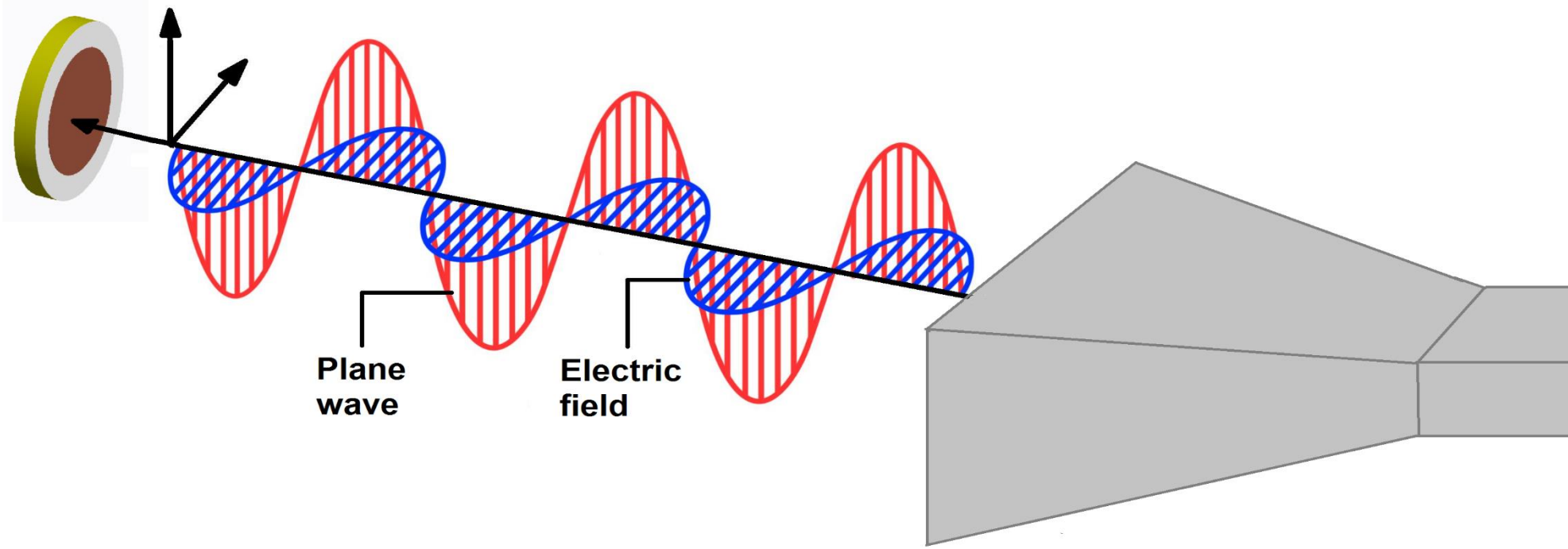
Voltage = $f(\text{frequency})$

Frequency_R = $f(\text{deflection})$

Pressure = $f(\text{deflection})$

Pressure = $f(\text{frequency}_R)$





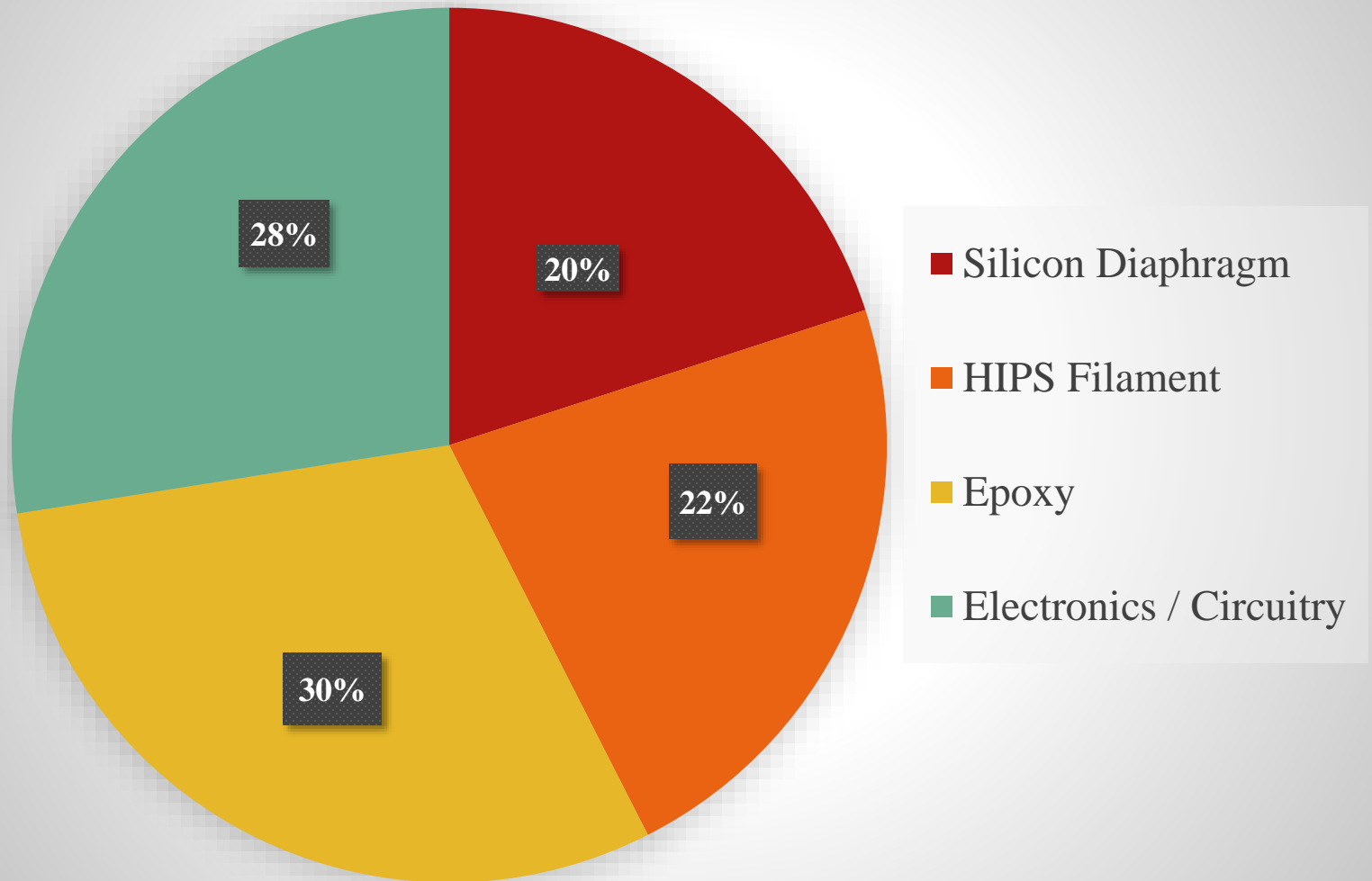
Budget

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Total Budget: \$500

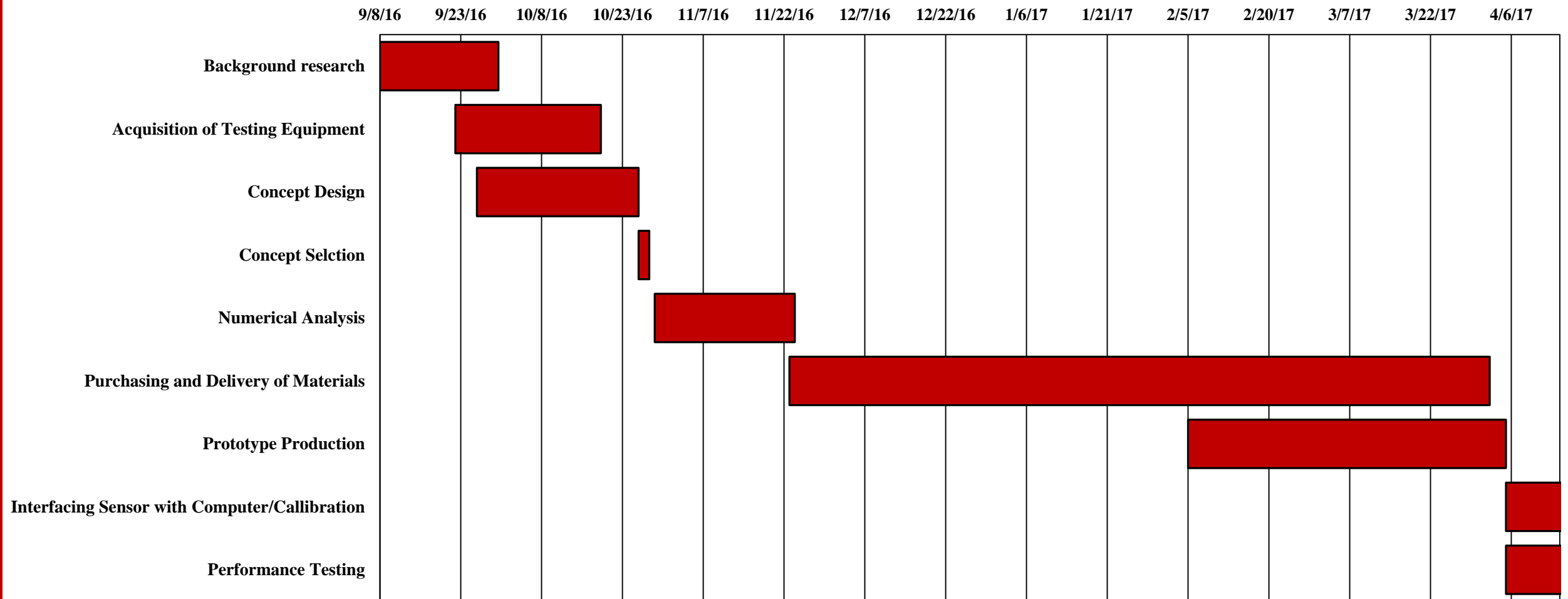
- Electronics: \$55
- Silicone: \$40
- Epoxy: \$60
- HIPS Filament: \$45

Component Cost Analysis



Updated Gantt Chart

Presenter: Sebastian Bellini



Future Work

- Purchase Masterbond UV10 epoxy
- Interface sensor with network analyzer
- Calibrate sensor
- Determine viability

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Questions?