NORTHROP GRUMMAN

2nd Stage Development of an Autonomous Search and Rescue **Unmanned Aerial Vehicle (UAV) Team 12**

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Introduction

- Student Unmanned Aerial Systems (SUAS) 2017 Competition.
- Simulated search and rescue mission for a stranded hiker.



Geo-fence

Search Area



- 1st stage development:
 - Design, build, test UAV system
- 2nd stage development:
 - 1. Upgrade electronics package
 - Implement:
 - 2. Target alphanumeric detection
 - 3. Dynamic target detection
 - 4. Target color detection
 - 5. Target shape detection
 - 6. Payload delivery





Goal Statement

Develop an autonomous UAV featuring autonomous takeoff and landing, autonomous flight and navigation, target detection and classification, stationary and dynamic object avoidance, and payload delivery. Demonstrate autonomous flight and waypoint capturing, detect stationary clues and dynamic hiker.



- - ODROID C2 Central Processing Unit (CPU)
 - WIFI Antennas
 - Zubax Global Navigation Satellite System (GNSS)
 - Sony Point and Shoot Camera
- Ultrasonic sensor

2. Alphanumeric Target Detection

• Recognize shape, color, and alphanumeric symbols.



"h'= '0'e'0'r 'n'e' J U°**O°O°O**°h°d°∎'∎°b ∎'t'g'0's'a'n'm'e's e"n's"u'l'd"0"0"0"0 t't'g'a's'n'e'e'p'w •a•o•z•u•**D**• =

3. Dynamic Target Detection

- Compare current image with previous; use differences to detect changes.
- Challenge: constantly changing environment.
- Solution: additional area and intensity.







- **Resize image**
- Gray scale image and blur
- Detect contour lines

Mechanical

Measurement

Addition

Power



- upon hiker.
- Accomplished:
 - Developed electronics package Completed stationary target detection Completed hiker detection

- Future Work:

- **References:**





4. Color Target Detection

- Categorize pixels by color
- Determine color based upon RGB boundaries

5. Shape Target Detection



6. Payload Delivery

An 8oz, water bottle will be mounted on the underside of the UAV, aft of the camera. The latch will be engaged by a servo motor to release recognition of the



Summary

• Develop safe autonomous flight test Improve target detection robustness



J. Denman, D. Fitzpatrick, C. Mard, P. McGlynn, and K. Ijagbemi, "Needs Assessment" Sep. 25, 201 K. Aley, J. Denman, D. Fitzpatrick, C. Mard, P. McGlynn, and K. Ijagbemi, "Project Plan & Product Specifications" Oct. 22, 2015. roducts/, Accessed: Oct. 6, 2016.