The Gopher Tortoise Scope

Sponsored by

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The Tall Timbers Research and Land Conservancy

In partnership with

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Overview



- Background
- Needs Analysis & Objective
- Major Subsystem Descriptions
- Prototype Design
- Budget Analysis
- Scheduling
- Summary

Background



- Tall Timbers research focuses on fire-dependent ecosystems
- Their current scope has several design flaws
- Possible replacement products are out of their price range



The "Versatrax 450 Tank and Tunnel Crawler" by Spectrum Instroments. [1]

Needs Analysis



Current gopher tortoise scopes have one or more of the following issues:

- Cumbersome and heavy
- Not waterproof or shockproof
- Lack of data acquisition capability
- Poor visibility
- No infrared capabilities
- Expensive

"There is a need for a gopher tortoise scope that has greater mobility, improved weather and impact durability, increased dataacquisition capability, and reduced size, weight and cost."

Objective



Our objective is to create a design that is:

- Durable
- Capable
- Portable
- Affordable

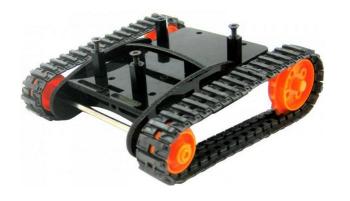
"The main goal is to design a mechanism that has versatile sensors, better durability, and more advanced video capabilities than the current system in order to enhance the surveying process of gopher tortoises."

Chassis Design



- The chassis must be able to function in:
 - Small underground burrows
 - Inclement weather
- Our design will feature:
 - Tracks with treads
 - Plexiglass housing
 - Less than 6 inches in width
 - Less than 4 inches in height





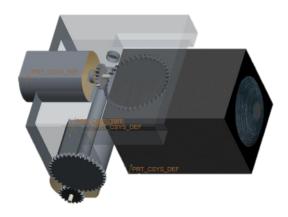
Angle- and side-view of the prototype chassis. [2]

Camera Design



- Purchase Camera (\$34.50)
 - Wide view color infrared camera
 - 7 IR LEDs
 - 25mm (.98 in) diameter
 - Night vision range: 6m
- Build Pan and Tilt System
 - 2" x 2" x 2.5"
 - Custom fit to camera and chassis
 - Smaller than off-the-shelf
 - Will require two motors (\$3.99)

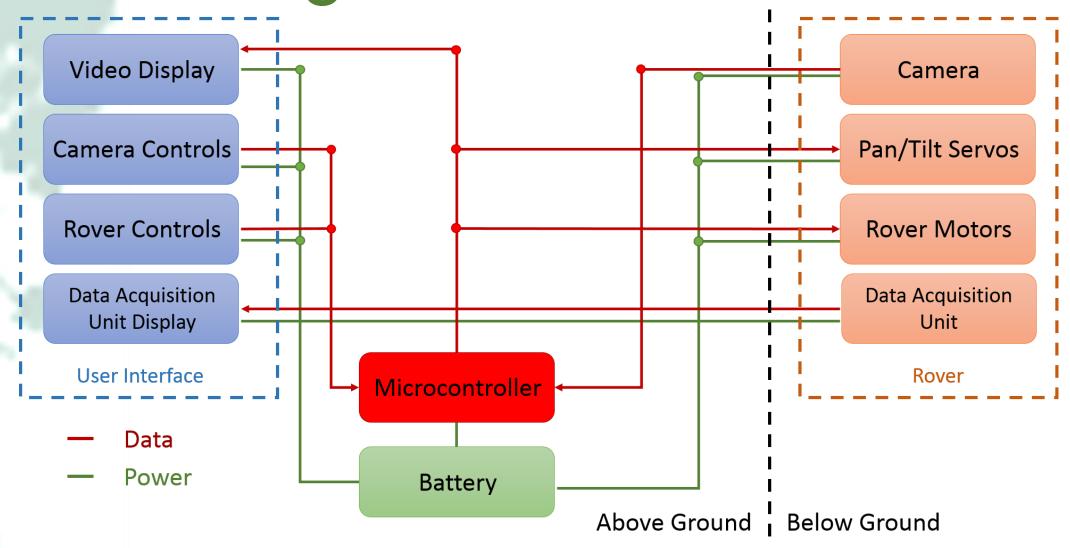




Prototype camera [3] and pan and tilt system.

Block Diagram





Prototype Design



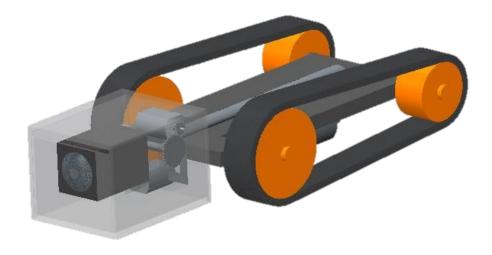
Two designs will be analyzed during the prototyping process:

Design A



Camera is placed within the housing of the chassis

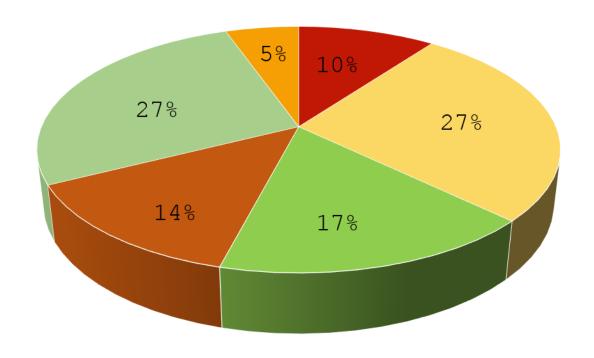
Design B



Camera is in front of the chassis and separate from the main housing

Budget Analysis



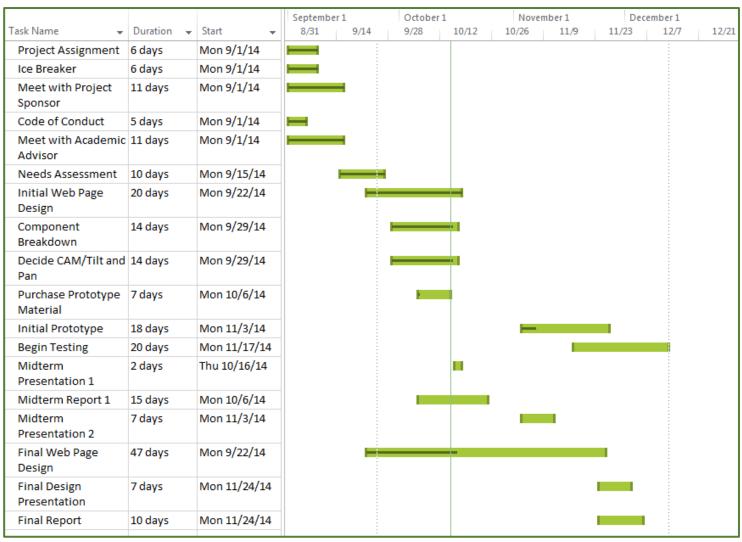


- Camera System
- Tether System
- Power

- Rover System
- User Interface
- Data Acquisition Unit

Scheduling





Summary



- Identified problems with current scope design
- Analyzed component needs
- Proposed two prototype designs
- Established a schedule

References



- "Versatrax 450 Tank and Tunnel Crawler." Versatrax 450 TTC. Spectrum Instruments, 2010. Web. 14 Oct. 2014. http://www.spectrum-instruments.com/products/optical/documents/VT450_TTC.pdf.
- 2) "Mini RobotShop Rover Chassis Kit." Mini RobotShop Rover Chassis Kit. RobotShop, 2014. Web. 14 Oct. 2014. http://www.robotshop.com/en/mini-robotshop-rover-chassis-kit.html.
- 3) "Wide View Color Infra Red Camera with 7 IR LEDs." Wide View Color Infra Red Camera with 7 IR LEDs. SuperDroid Robots, n.d. Web. 14 Oct. 2014. ">http://www.superdroidrobots.com/shop/item.aspx/wide-view-color-infra-red-camera-with-7-ir-leds/1121/>.



Questions?

For more information go to: eng.fsu.edu/~sharisi/TEAM21/index.html