

Objective

The Tall Timbers Research Station & Land Conservancy studies burrowing gopher tortoises. Our goal is to enhance research methods by creating a robotic scope with video capability and temperature and humidity sensing in a non-invasive manner.





•30° left-right pan

•Aileron system attached to servo

Top Level Diagram of Scoping System

Specifications

•Rover measures 2.5" by 6.5" by 11.0"

•Lithium-ion battery (five hours of continuous operation)

•User interface includes a gamepad controller a cased screen



External Side Boxes

Custom Treads

Cam Pan-Servo



•Built in clutch with 90° output

•200:1 torque ratio

•Fastened couplers to driver sprockets



.90 ±.58

D 1.63



Research Station & Land Conservance

Tether

- •50 ft Kevlar exterior sheath
- •8 pin waterproof connection

Tether

Body Casing

- •ABS and infrared-capable Plexiglas
- •Angled front shield to mitigate glare

•Splash-proof with silicone sealant



7" Display Monitor

User Interface

- •Raspberry Pi B+ microprocessor
- •7 inch IPS screen displays video feed and temperature and humidity data
- allows for intuitive rover •Gamepad control, camera control, and data acquisition
- •16 GB SD card
- •Encased in splash-proof Plexiglas with a compact tripod mount