



Jane Bartley

Background

Tall Timbers is a research station that studies the Gopher Tortoise. To find these tortoises, researchers must be able to see inside their burrows, which can reach up to 50 feet in length. Our goal is to enhance the surveying process by designing an affordable and capable scope.

Specifications

- •Infrared camera transmits a live-feed of the burrow
- •Sensors to measure temperature and humidity
- •Gamepad control allows user to drive a •Raspberry Pi B+ communicates with the treaded rover
- •User interface with screen and software capable of storing video and images
- •Battery life of eight hours
- •Scope can be replicated for less than \$1000





- RCA
- •C++ code interprets button pushes on the gamepad, displays video and stores data
- •Gamepad allows user to control the rover motion, access video recording functions, pan the camera and shut down the system
- •7 inch LCD screen displays video feed overlaid with temperature and humidity data
- •32 GB micro SD card has enough storage for 5 hours of video and 2,000 pictures
- •Colin Riley: Gamepad programming, Sina Sharifi-raini: Video display and storage, Jane Bartley: Splash-proof enclosure

A schematic illustrating how the major components of the scope will fit together.

User Interface

Arduino over USB and receives video over

Rover

- •Arduino Micro reads commands sent from •Battery has an operating range of 13.4V to the User Interface (UI) over USB 11V; voltage is regulated by buck-boost converters
- •C code on the microcontroller interprets user commands and controls rover motion, •Battery is rechargeable and has an 800 cycle camera panning and data acquisition life expectancy
- •L298N motor driver controls 2 gearmotors
- DHT22 refreshes every 2 sec. providing temperature data from -45°C to 125°C with $\pm 0.2^{\circ}$ C accuracy and relative humidity data from 0% to 100% with $\pm 2\%$ accuracy.
- •Wide-angle, infrared camera with built in infrared LEDs sends video to UI
- •Colin Riley: Microcontroller programming, Sharifi-raini: Hardware selection, Sina Lester Nandati: panning mechanism



- •12V, 14Ah Lithium-ion battery provides enough power for 5 hours of continuous operation; more than enough for an 8 hour day of scoping



