

# **Group 5**

# **Enhanced Agility of MAV's Using Adaptive Structures**

**Joey Alessandria**  
**Mitch Jermyn**  
**Joshua Webb**

# Overview

- ▶ Motivation
- ▶ Introduction
- ▶ Experimental Setup
- ▶ Results
- ▶ Conclusion
- ▶ Future Work



# Motivation

- ▶ Sponsor: Air Force Research Laboratory (AFRL)
- ▶ Unmanned Aerial Vehicle (UAV) operating limitations



Figure 1



Figure 2



# Introduction: Project Focus

- ▶ Implementation and testing of adaptive structures in Micro-Air Vehicles (MAV)
  - Delaying Stall, Increase Lift (Verification)
  - Induce Roll
- ▶ Adaptive Structure:
  - Dielectric Elastomer



# Introduction: Dielectric Elastomer

## ▶ Dielectric Elastomer

- Two Electrodes: Carbon Grease
- Membrane: 3M VHB 4910 300% strain

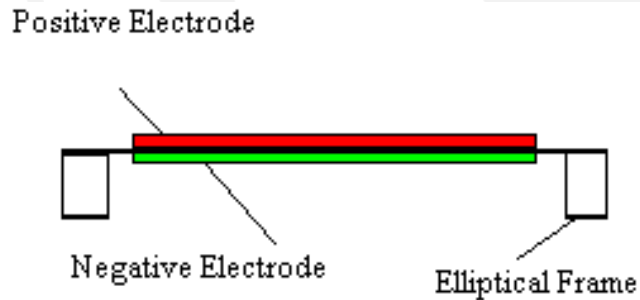


Figure 3

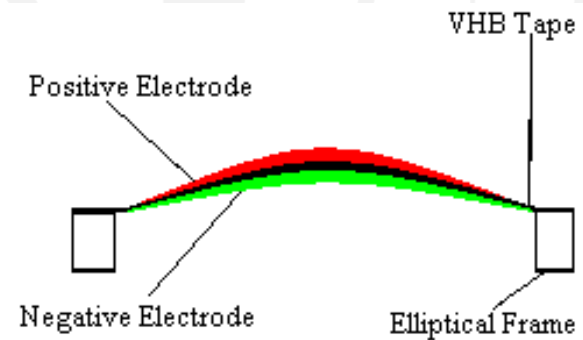
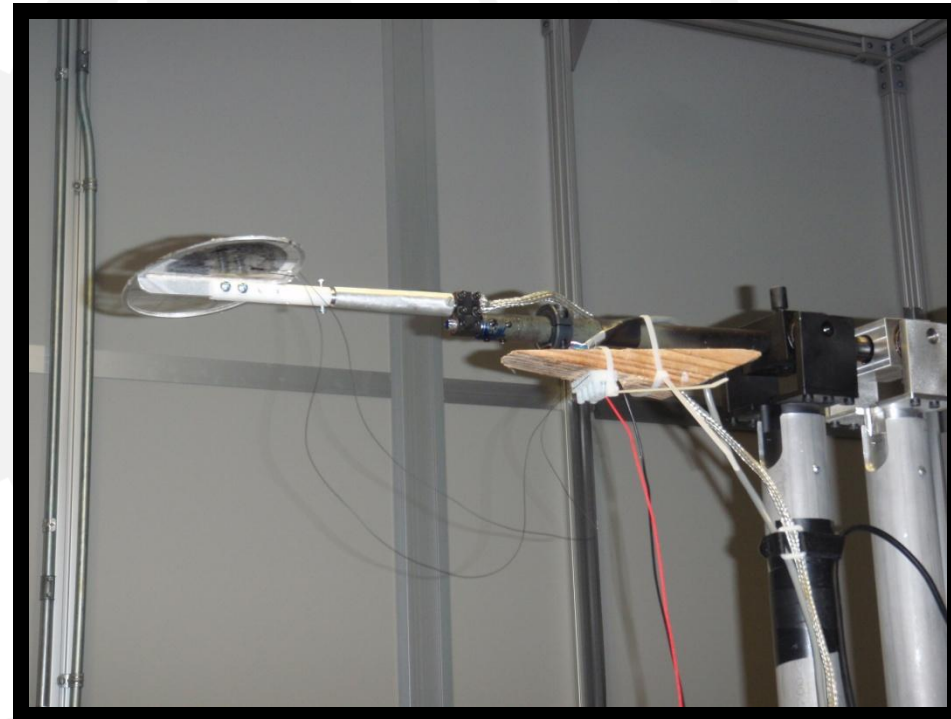
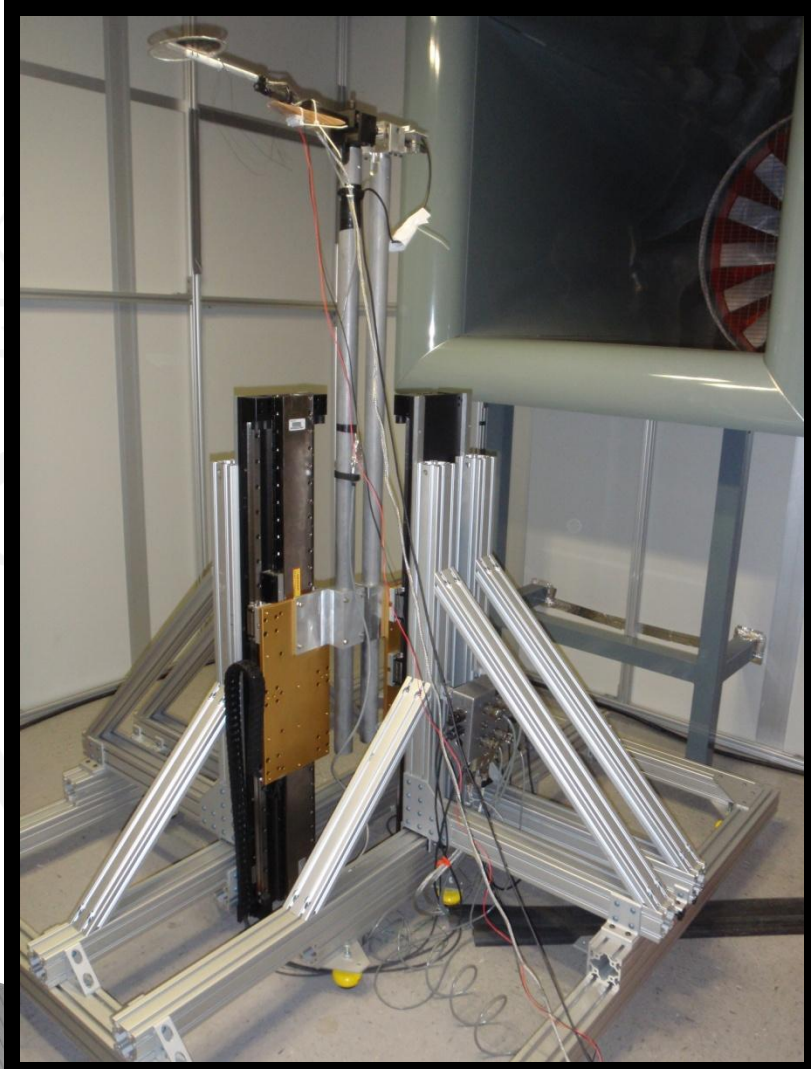
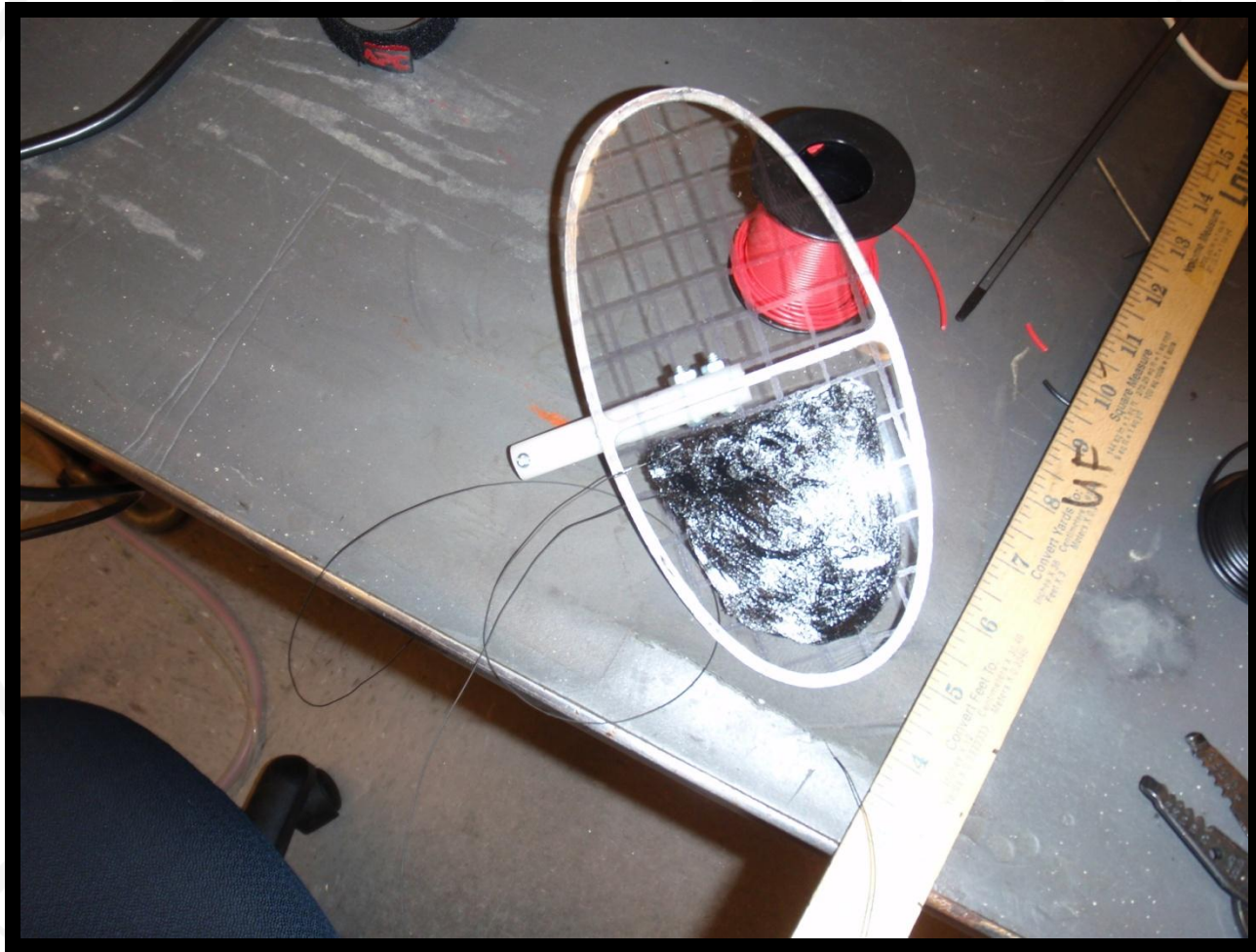


Figure 4

# Experimental Setup: Test Platform

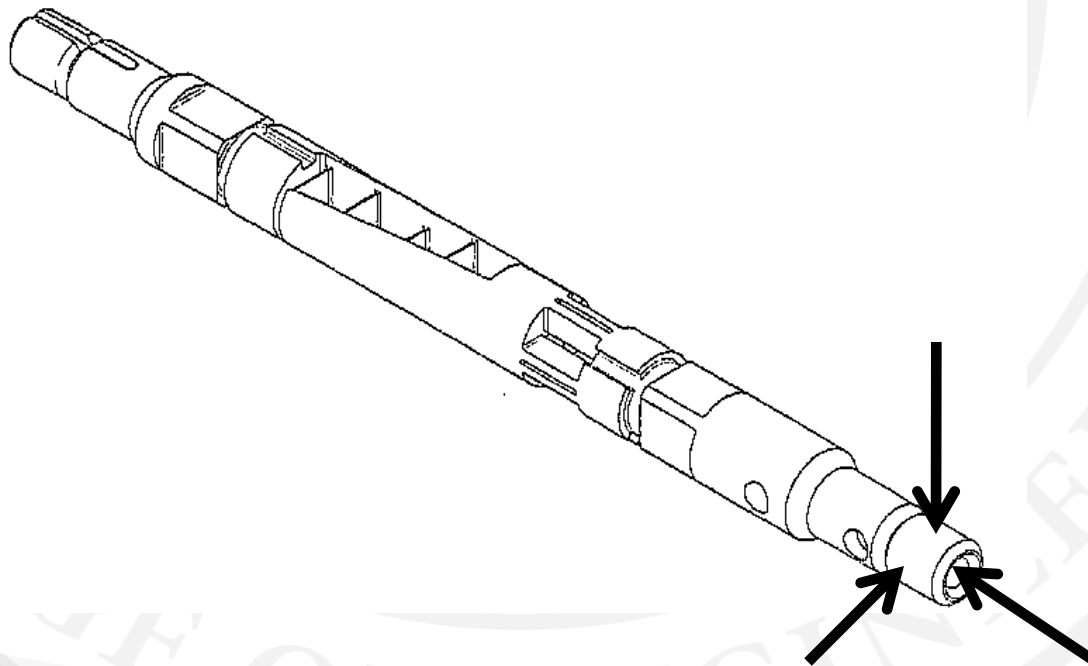


# Experimental Setup: Wing Frame (Roll)



# Experimental Setup: Sting Balance

- ▶ Measures
  - Three moments
  - Three forces





# Experimental Setup: Test Parameters

- ▶ Angle of Attack: 0 to 22 degrees
- ▶ Time at each angle: 30 seconds
- ▶ Wind Velocity: 5 to 10 m/s
- ▶ Sample Rate: 100 samples per second
- ▶ Voltage: 0 to 6.5 kV
- ▶ Outputs: Coefficient of Drag, Lift, and Rolling Moment



# Experimental Setup: Test Parameters

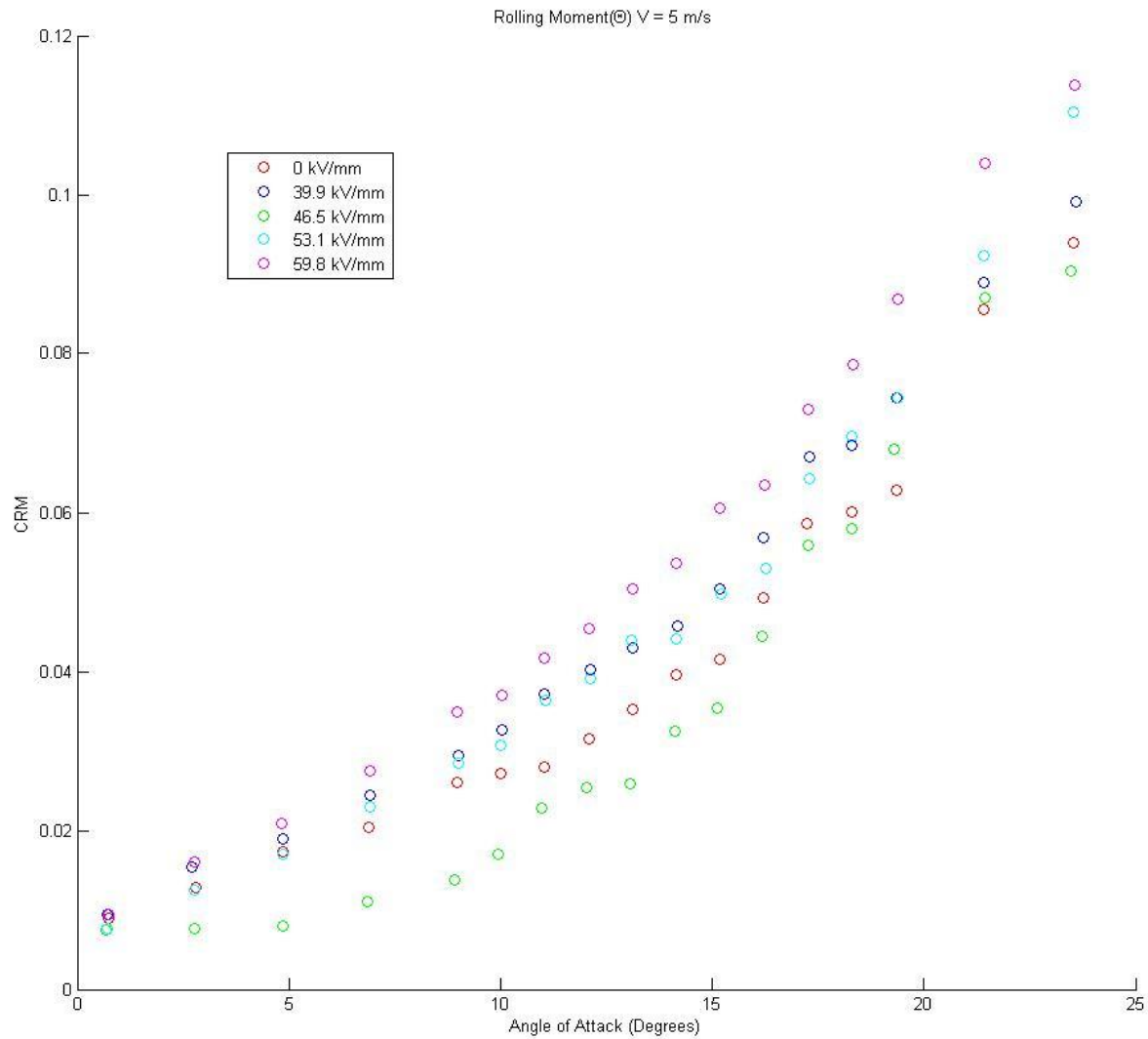
- ▶ Step 1: Tear Run
- ▶ Step 2: Base Line Run Variable Velocity
- ▶ Step 3: Fixed Voltage Variable Velocity
- ▶ Step 4: Change Voltage Repeat Step 3



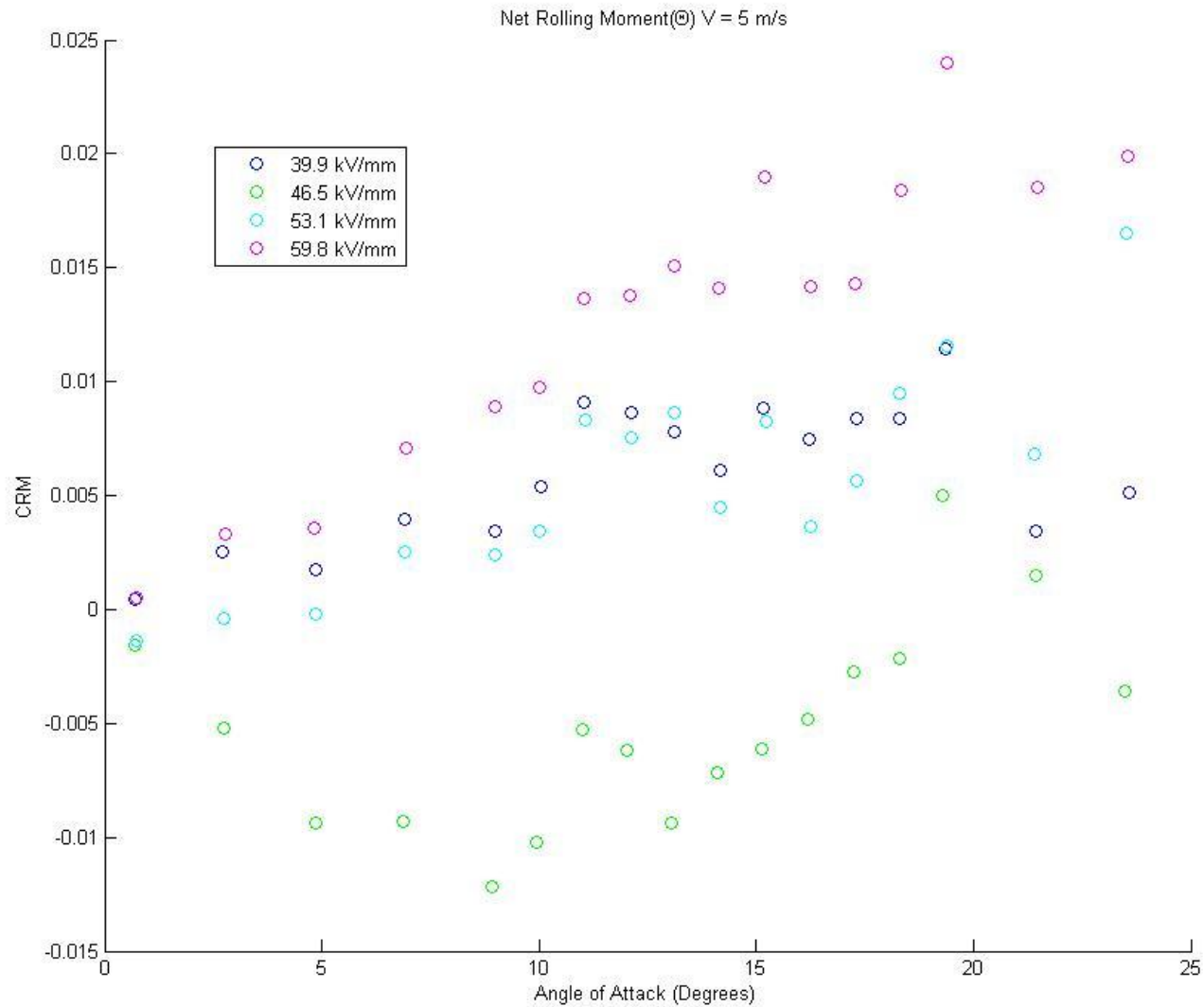
# Experimental Setup: Test Parameters



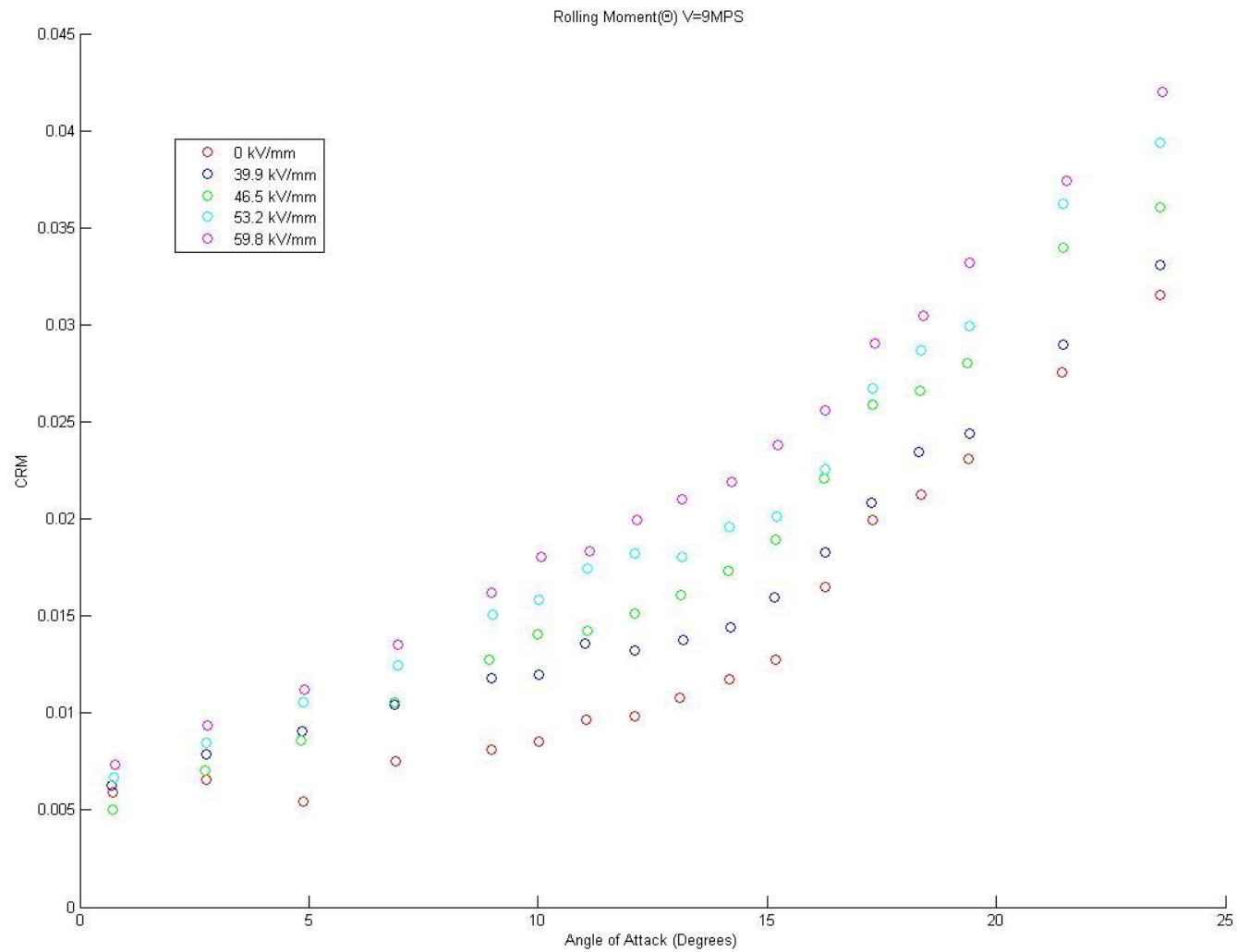
# Results



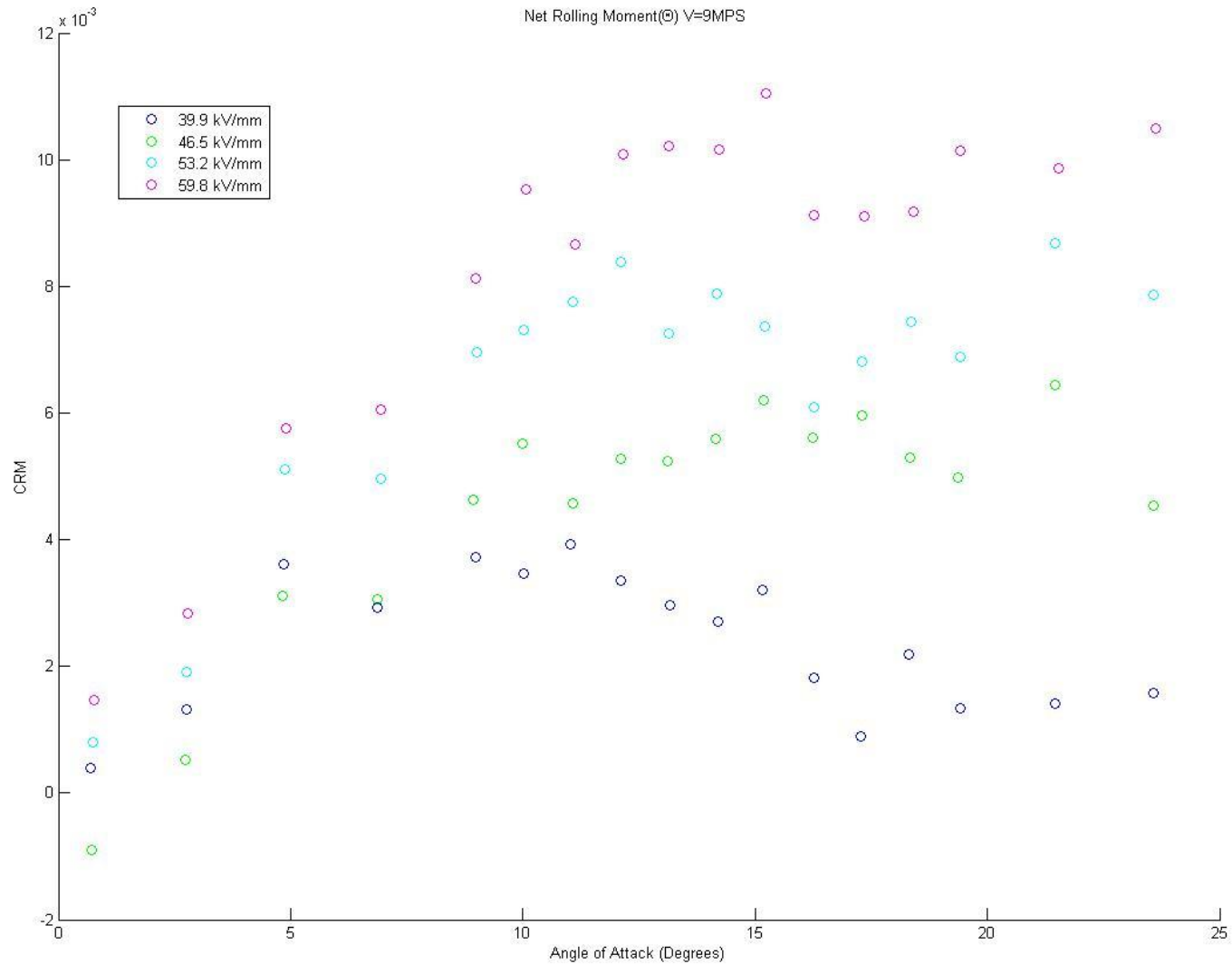
# Results



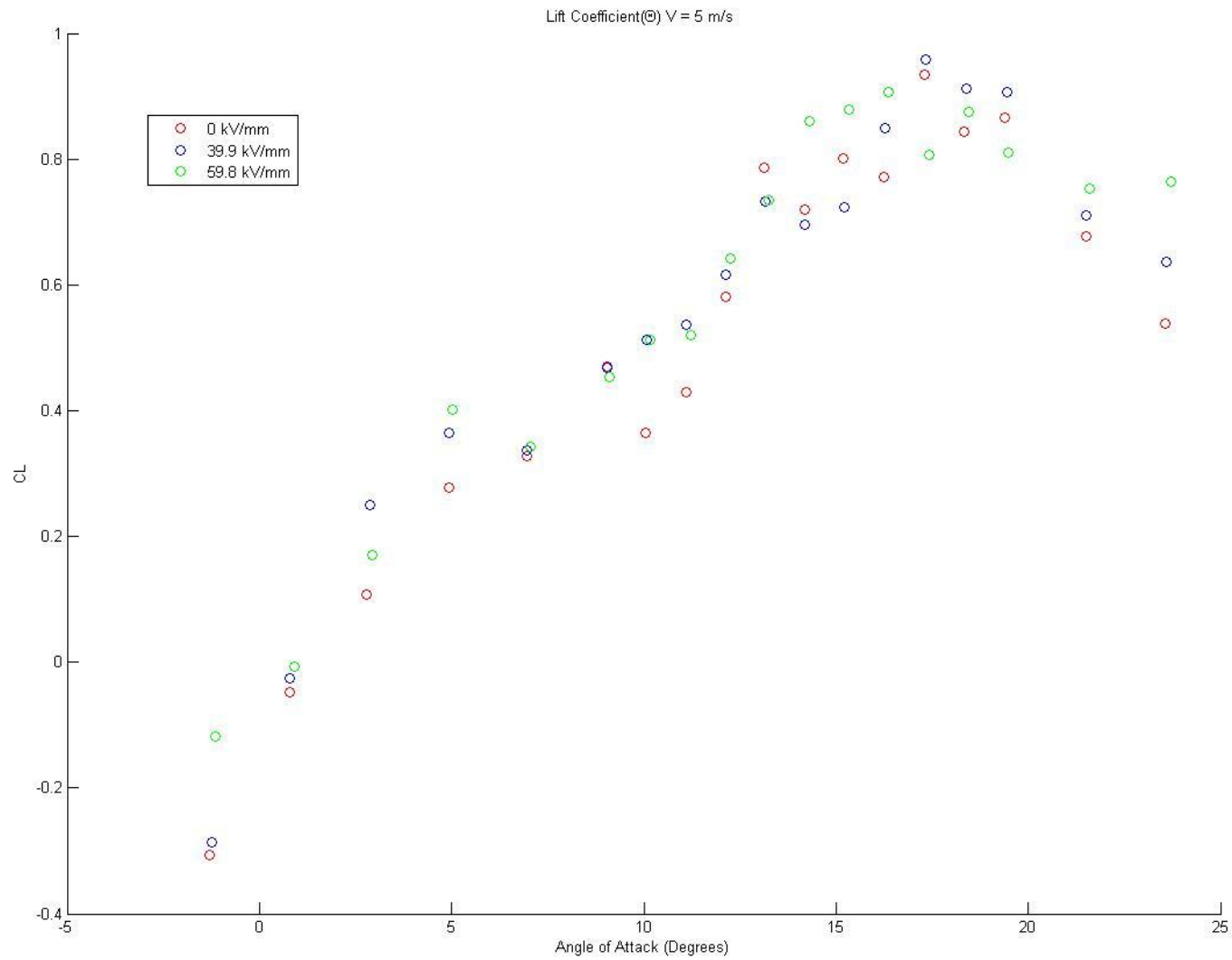
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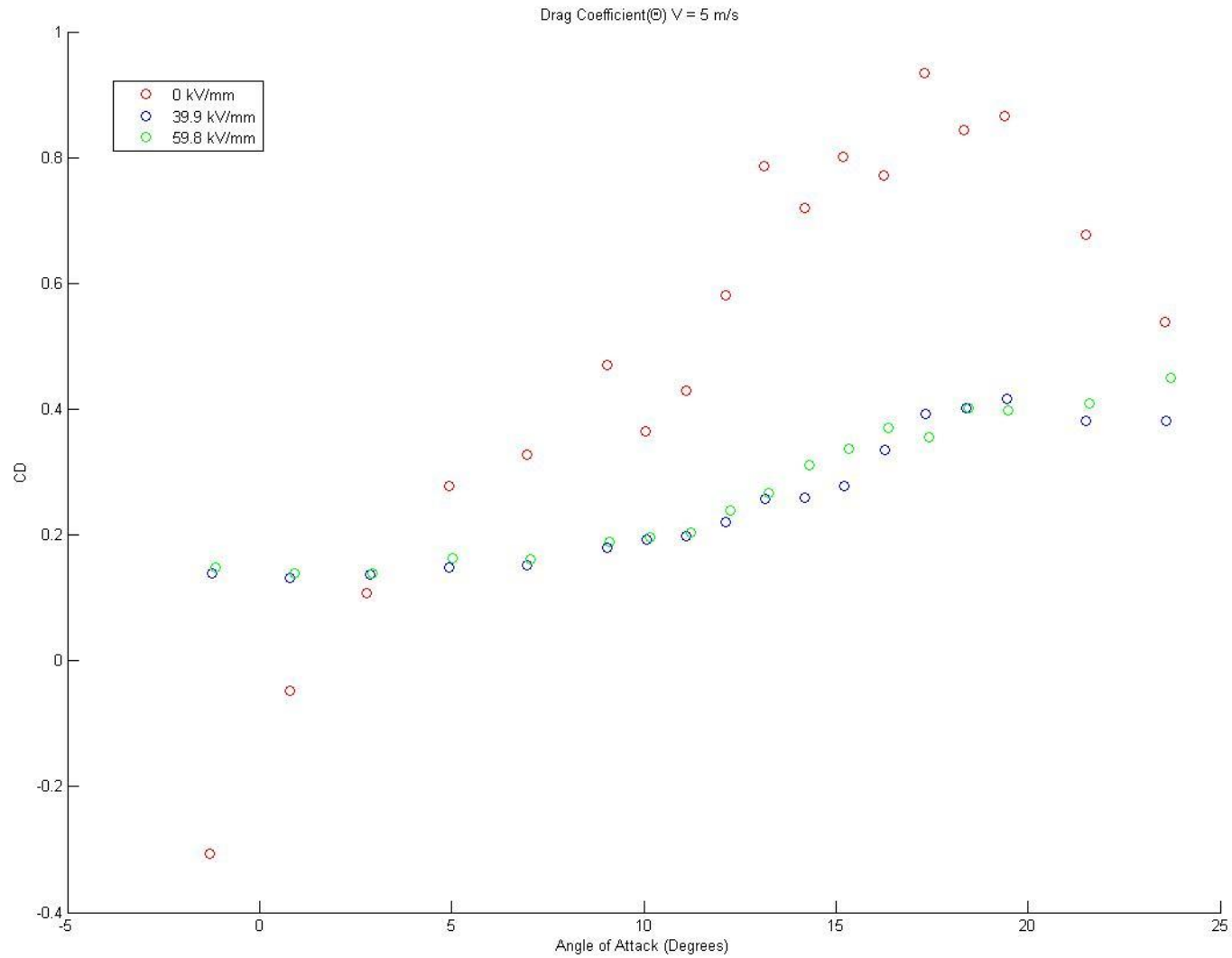


# Results

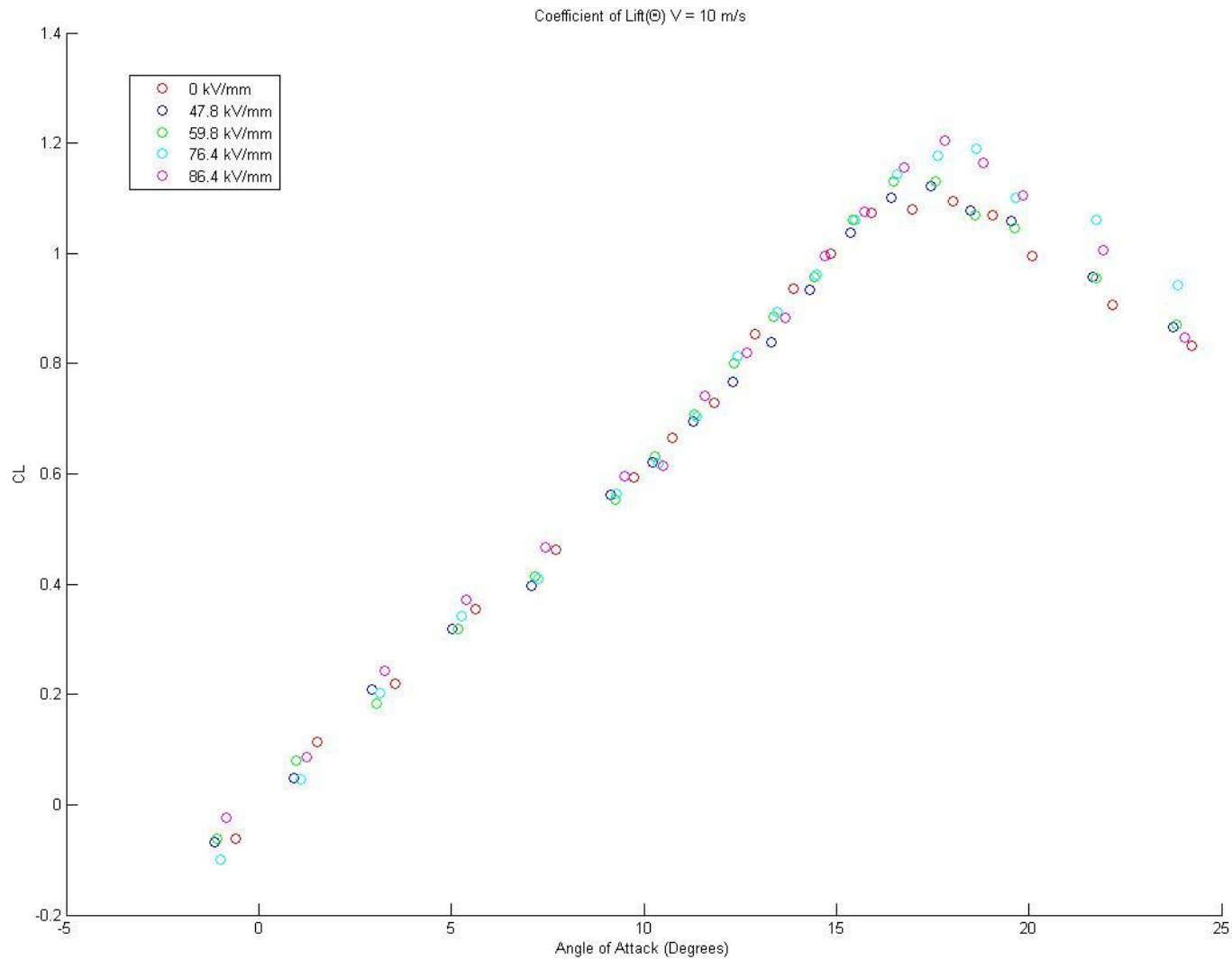




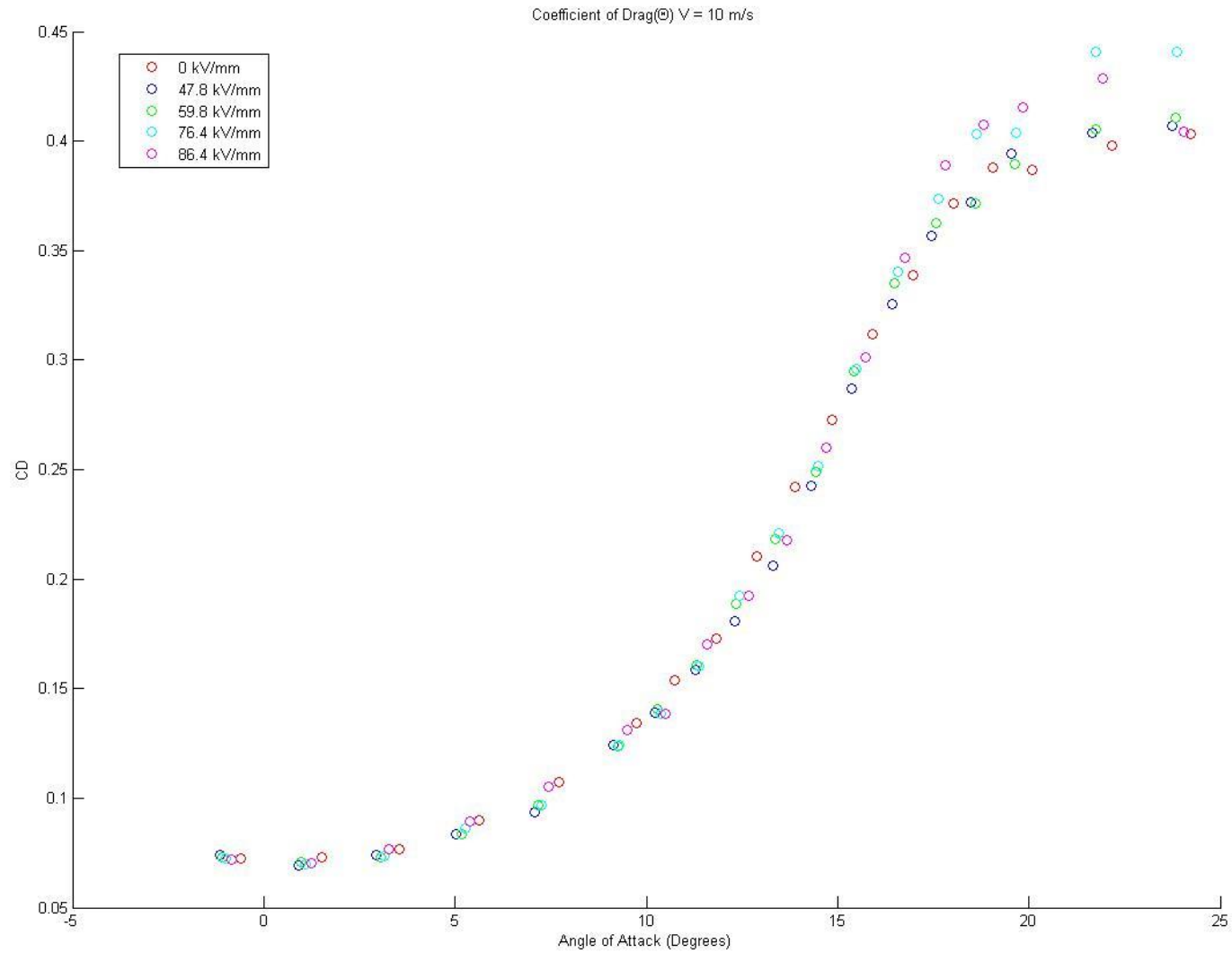
# Results



# Results



# Results



# Conclusion

## ▶ Roll

- 9 m/s: as voltage increases, roll coefficient increases
- 33% Increase over baseline
- Data inconclusive when  $V < 9$  m/s

## ▶ Lift

- 10 m/s: as voltage increases, roll coefficient increases
- 20% Increase over baseline
- Delayed Stall 3 degrees
- $V = 6$  m/s general trend but no conclusive result



# Future Work

- ▶ Dynamic Controls
- ▶ Different electrode material
- ▶ Flow Visualization
- ▶ Different test platform



# Special Thanks

- ▶ Dr. William Oates
- ▶ Dr. Ben Dickinson
- ▶ Michael Hayes



# Questions

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