

# 9.58(b)

## 1 9.58(b), §1 Asked

Asked: Diagonalize

$$q(x, y) = 2x^2 - 6xy + 10y^2$$

## 2 9.58(b), §2 Solution

$$q = 2x^2 - 6xy + 10y^2$$

Find the matrix of coefficients:

$$A = \begin{pmatrix} 2 & -3 \\ -3 & 10 \end{pmatrix}$$

Eigenvalues:

$$|A - \lambda I| = \begin{vmatrix} 2 - \lambda & -3 \\ -3 & 10 - \lambda \end{vmatrix} = \lambda^2 - 12\lambda + 11 = 0$$

There are two roots:  $\lambda_1 = 1$  and  $\lambda_2 = 11$

The eigenvector corresponding to  $\lambda_1$  satisfies

$$\begin{pmatrix} 1 & -3 \\ -3 & 9 \end{pmatrix} \begin{matrix} (1) \\ (2) \end{matrix} \implies \begin{pmatrix} 1 & -3 \\ 0 & 0 \end{pmatrix} \begin{matrix} (1) \\ (2') = (2) + 3(1) \end{matrix}$$

Taking  $v_{1y} = 1$ , then  $v_{1x} = 3$ , giving an eigenvector  $(3, 1)$ . Normalizing this vector to length one gives:

$$\vec{v}_1 = \begin{pmatrix} 3 \\ 1 \end{pmatrix} / \sqrt{3^2 + 1^2} = \begin{pmatrix} 3/\sqrt{10} \\ 1/\sqrt{10} \end{pmatrix} = \hat{i}'$$

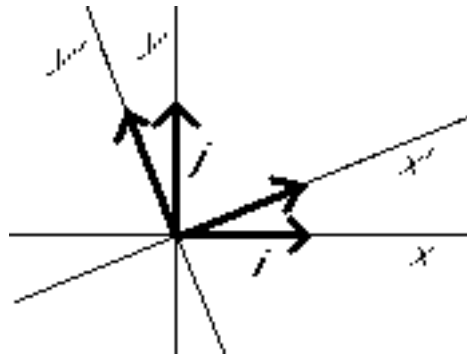
The eigenvector corresponding to  $\lambda_2$  satisfies

$$\begin{pmatrix} -9 & -3 \\ -3 & -1 \end{pmatrix} \begin{matrix} (1) \\ (2) \end{matrix} \implies \begin{pmatrix} -9 & -3 \\ 0 & 0 \end{pmatrix} \begin{matrix} (1) \\ (2') = 3(2) - (1) \end{matrix}$$

Taking  $v_{2y} = 3$ , then  $v_{2x} = -1$ , giving after normalization:

$$\vec{v}_2 = \begin{pmatrix} -1 \\ 3 \end{pmatrix} / \sqrt{(-1)^2 + 3^2} = \begin{pmatrix} -1/\sqrt{10} \\ 3/\sqrt{10} \end{pmatrix} = \hat{j}'$$

Since  $1/\sqrt{10} = \sin(18.4^\circ)$ , the new axes are rotated  $18.5^\circ$  counter clockwise from the old:



In the new coordinates,

$$q = x'^2 + 11y'^2$$

Note that lines of constant  $q$  are now seen to be elliptic.

*Important note:* It is seen that the quadratic form  $\vec{x}^T A \vec{x}$  is always positive for nonzero  $\vec{x}$ . Symmetric matrices for which this is true are called *positive definite*. They have all positive eigenvalues. Similarly, if all eigenvalues are negative, a symmetric matrix is called *negative definite*. If all eigenvalues are positive or zero, it is called *positive semi-definite*.

Finite element codes for structures typically produce positive definite matrices, as do many other physical applications, such as the kinetic energy of a solid body. Definite matrices are typically easier to deal with in numerical applications than general matrices. For example, no pivoting is needed in the Gaussian elimination involving a definite matrix.